FURUNO

OPERATOR'S MANUAL

DUAL-FREQUENCY SEARCHLIGHT SONAR

MODEL   CH-300

ECF
(Elemental Chlorine Free)
The paper used in this manual
is elemental chlorine free.

© FURUNO ELECTRIC CO., LTD.

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Your Local Agent/Dealer

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⚠ SAFETY INSTRUCTIONS

⚠ WARNING

**ELECTRICAL SHOCK HAZARD
Do not open the equipment.**

Only qualified personnel should work inside the equipment.

Immediately turn off the power at the switchboard if water leaks into the equipment or something is dropped in the equipment.

Continued use of the equipment can cause fire or electrical shock. Contact a FURUNO agent for service.

Do not disassemble or modify the equipment.

Fire, electrical shock or serious injury can result.

Immediately turn off the power at the switchboard if the equipment is emitting smoke or fire.

Continued use of the equipment can cause fire or electrical shock. Contact a FURUNO agent for service.

Make sure no rain or water splash leaks into the equipment.

Fire or electrical shock can result if water leaks in the equipment.

⚠ WARNING

Keep heater away from equipment.

A heater can melt the equipment's power cord, which can cause fire or electrical shock.

Use the proper fuse.

The fuse in the hull and transceiver units protects them from overvoltage, equipment fault and reverse polarity of the ship's mains. If a fuse blows replace it with fuse of the same amperage. Use of a wrong fuse can result in damage to the equipment.

Retract the transducer before turning off the power.

Damage to the equipment may result. Wait until the transducer retraction switch [↑] lights steadily and then turn off the power.

⚠ CAUTION

Do not exceed 20 knots when operating the equipment and do not exceed 15 knots when lowering or raising the transducer.

The transducer may become damaged.

Do not use the equipment for other than its intended purpose.

Use of the equipment as a stepping stool, for example, may result in personal injury or damage to the equipment.

WORKING WITH THE SONAR OIL

Precautions
- Keep oil away from eyes. Wear protective gloves when working with the oil. The oil can cause inflammation of the eyes.
- Do not touch the oil. Wear protective gloves when working with the oil. The oil can cause inflammation of the skin.
- Do not ingest the oil. Diarrhea and vomiting may result.
- Keep the oil out of reach of children.

Emergency procedures
- If the oil enters eyes, flush with clean water about 15 minutes. Consult a physician.
- If the oil is ingested, see a physician immediately.

Disposal of oil and its container
Dispose of oil and its container in accordance with local regulations. For further details, contact place of purchase.

Storage
Seal container to keep out foreign material. Store in dark, cool place.

⚠ CAUTION

Set the gain properly.

No picture appears if the gain setting is too low, and noise appears when the gain is too high. If the gain is set improperly, the depth indication may be wrong, resulting in a potentially dangerous situation if the vessel is navigated by monitoring the depth indication.
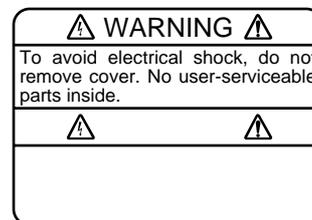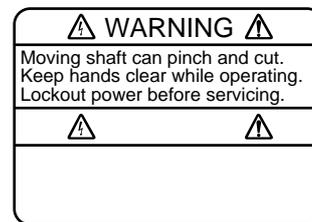
Gain too high	Proper gain	Gain too low

Warning labels

Warning labels are attached to the display, transceiver and hull units. Do not remove the labels. If a label is missing or illegible, contact a FURUNO agent or dealer.

⚠ WARNING ⚠
To avoid electrical shock, do not remove cover. No user-serviceable parts inside.
⚠   ⚠

TRANSCEIVER UNIT
Name: Warning Label (1)
Type: 86-003-1011-1
Code No.: 100-236-231

DISPLAY UNIT
Name: Warning Label (2)
Type: 86-003-1001-1
Code No.: 100-236-741

⚠ WARNING ⚠
Moving shaft can pinch and cut. Keep hands clear while operating. Lockout power before servicing.
⚠   ⚠

HULL UNIT
Name: Injury
　　　 Warning Label
Type: 06-021-4015-0
Code No.: 100-281-590

TFT LCD

The high quality TFT (Thin Film Transistor) LCD displays 99.999% of its picture elements. The remaining 0.01% may drop out or light, however this is an inherent property of the LCD; it is not a sign of malfunction.

TABLE OF CONTENTS

FOREWORD

Thank you for purchasing the CH-300 Dual-Frequency Searchlight Sonar. We are confident you will discover why FURUNO has become synonymous with quality and reliability.

Dedicated in the design and manufacture of marine electronics equipment for half a century, FURUNO Electric Company has gained an unrivaled reputation as a world leader in the industry. This is the result of our technical excellence as well as our worldwide distribution and service network.

Please carefully read and follow the safety information and operating and maintenance instructions set forth in this manual before attempting to operate the equipment and conduct any maintenance. Your sonar will perform to the utmost of its ability only if it is operated and maintained in accordance with the correct procedures.

Features

The CH-300 is a dual-frequency searchlight sonar. Consisting of a monitor unit, control unit, transceiver unit and hull unit, it displays underwater objects on the monitor of choice, in 8 or 16 colors according to received echo strengths.

The main features are

- Horizontal and vertical section modes for detecting, searching, tracking and monitoring fish school.
- 12 display modes for virtually any fishing application.
- Mix mode discriminates small fish.
- Fish or bottom echo can be displayed in white to distinguish bottom fish.
- Hull unit automatically raises the transducer when ship's speed exceeds prescribed speed.
- User-programmed function keys provide one-touch access to desired function.
- Two types of target lock for effective tracking of fish school.
- Digital display of position, speed, course, water temperature, depth, tide speed and direction. (Requires appropriate sensors.)

Usage Precautions

- The Motion Sensor MS-100 compensates for ship's pitching and rolling. However, it does not compensate for load unbalance.

- If the equipment will not be used for a long time, shut off the power to it at the mains switchboard, to prevent battery discharge.

- If the soundome is to be operated while the ship is dry-docked, set the transmitter output power to "minimum" (on the COM1 menu). Damage to the train-tilt section may result if it is operated with maximum transmitter power while the ship is dry-docked.

- When the ship is dry-docked check for signs of corrosion on the soundome. Find the reason for the corrosion and attach a zinc plate to the hull unit as an anticorrosion measure if necessary.

Notice

- No part of this manual may be copied or reproduced without written permission.

- If this manual is lost or worn, contact your dealer about replacement.

- The contents of this manual and equipment specifications are subject to change without notice.

- The example screens (or illustrations) shown in this manual may not match the screens you see on your display. The screen you see depends on your system configuration and equipment settings.

- This manual is intended for use by native speakers of English.

- FURUNO will assume no responsibility for the damage caused by improper use or modification of the equipment or claims of loss of profit by a third party.

SYSTEM CONFIGURATION

INTERFACE UNIT IF-8000

CONTROL UNIT/MONITOR UNIT CH-302/MU-100C

Navigator

Control Unit

MONITOR UNIT
MU-100C

Display
Unit

VGA Ext.
Monitor

Remote
Controller
CH-256

CONTROL UNIT CH-302

**TRANSCEIVER UNIT
CH-303**

SPEAKER

Speaker

Satellite
Compass

12-24 VDC

Motion Sensor

**HULL UNIT
CH-304
CH-305**

12-24 VDC

Note 1: MU-100C is the standard supply
monitor unit. An external monitor
may be connected via the
interface unit (option). The drawing
above shows the system configuration
with the MU-100C.

Note 2: For blackbox type, MU-100C is
not supplied. Connect external
monitor (user supply) and control
unit to the interface unit.
When Monitor MU-151C is connected,
this interface is not necessary.

System configuration

1. OPERATIONAL OVERVIEW

1.1 Control Description

Selects center bearing of training sector.

Selects detection range.

Selects training speed (horizontal mode)/
train center (vertical scan)/picture
advancement speed (echo sounder).

Reverses scanning direction.

Turns the power on/off.

Raises the transducer.

- Controls tilt angle.
- Selects center direction of
  the vertical scanning sector.

Adjusts receiver
sensitivity.

Adjusts display brilliance.

Omnipad
- Shifts cursor.
- Selects menu items, options.

Selects width of
training sector.

Lowers the transducer.

Provide short-cut
key or one-touch
setup.

Opens/closes
menu.

Turns target lock
on/off.

Inscribes/erases event
markers.

Switches training sector to
360° (horizontal mode),
or 180° (vertical scan mode).

Inscribes/erases range
and bearing markers.

Turns mix display on/off.

Low freq/High freq selection

Switches control
between main and
sub windows.

Horizontal Combination*

Horizontal Mode

Vertical Scan Mode

BOW

Tilt

Sounding
beam

Echo Sounder Mode

Horizontal

Horizontal Expansion   Vertical Scan

Echo Sounder

* Horizontal/History, Horizontal/Vertical scan,
Horizontal/Vertical zoom, Horizontal/Video plotter
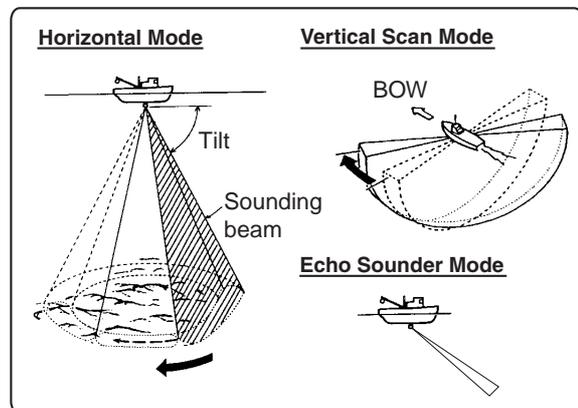
Control unit

1.2   Remote Controller

The Remote Controller CH-256 (option) provides armchair control over range, tilt, target lock and sounding range.

Choose display range. ———

Choose tilt angle.

Chooses sounding area:
Full circle 360° (horizontal mode)
Half circle 180° (vertical scan mode).

Enables/disables target lock.
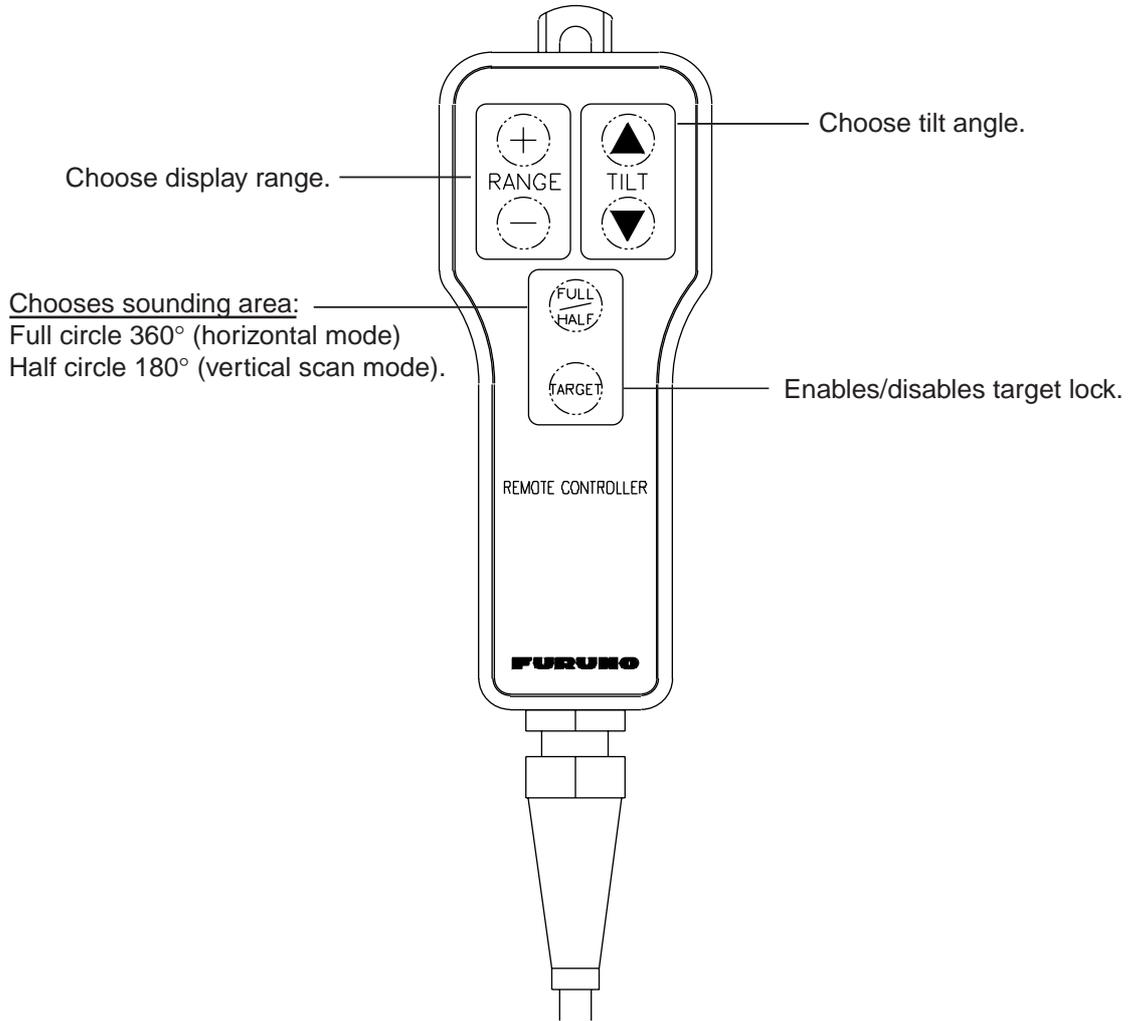
Remote controller

1.3   Turning the Power On/Off

1.3.1   Power on

This sonar has a demonstration mode which provides simulated operation without the transducer. For further details see page 5-20.

Press the **POWER** switch on the control unit till you hear a "click." A beep sounds, the lamp above the switch lights and the startup display appears. Four seconds later the last-used display appears.

MODEL: CH-300 **/***kHz

**: Frequency

Startup display

Note 1: Wait at least five seconds before reapplying the power.

Note 2: If the language selection window appears, see paragraph 5.4.8.

1.3.2   Power off

1. Check that the speed is under 15 knots*, and then press the [↑] switch on the control panel to retract the transducer. The lamp above the switch blinks while the transducer is being raised and lights steadily when it is fully raised. *The transducer may be damaged if it is raised when the speed is more than 15 kts.
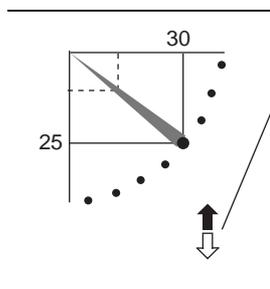
Transducer status indicator
• Up arrow: Filled when transducer is fully retracted into the tank.
• Down arrow: Filled when transducer is fully lowered.
• Appropriate arrow flashes during raising/lowering of transducer.

Note: When the transducer is being raised automatically (auto raise feature), the arrows are filled and the up arrow flashes. When the transducer is fully retracted, the up arrow lights and the down arrow becomes hollow.

Transducer status indicator

2. Confirm that the lamp above the [↑] switch lights steadily (meaning the transducer is fully retracted) and then press the **POWER** switch.

Note 1: The transducer is automatically retracted into the tank even if the equipment is turned off before retracting the transducer. However, for safety purposes, make it a habit to retract the transducer before turning off the power.

Note 2: After changing settings, wait at least one minute before turning off the power to allow the equipment to memorize settings (and start up with them at the next power up). No harm will result to the equipment if this is not done.

1.4 Raising, Lowering the Transducer

1.4.1 Lowering the transducer

⚠ CAUTION

Do not exceed 20 knots when operating the equipment and do not exceed 15 knots when lowering or raising the transducer.

The transducer may become damaged.
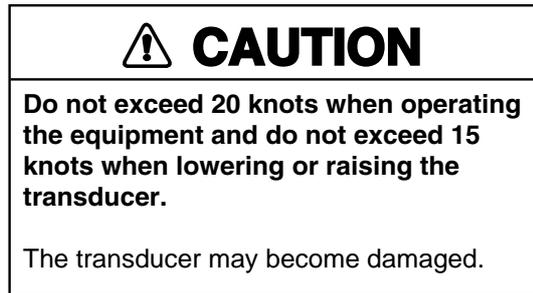
With the boat at the fishing ground, press the [↓] switch to lower the transducer. The lamp above the switch blinks while the transducer is being lowered and lights when it is completely lowered. The down arrow of the transducer status indicator is filled when the transducer is completely lowered.

1.4.2 Raising the transducer

Press the [↑] switch to raise the transducer. The lamp above the switch blinks while the transducer is being raised and lights steadily when it is fully raised. The up arrow of the transducer status indicator is filled when the transducer is fully retracted.

Note 1: The automatic transducer retraction feature, which requires speed input, raises the transducer when the ship's speed exceeds the operator-set speed (between 5 and 15 knots). If speed data is erroneous the transducer may be raised at a speed different from the speed specified. For further details about the automatic transducer retraction, see AUTO RETRACTION on page 5-13.

Note 2: An audio alarm may sound when the ship's speed exceeds the speed specified. For further details, see SPEED ALARM/MESSAGE on page 5-13.

1.5 Adjusting Screen Brilliance, Panel Dimmer

Screen brilliance can be adjusted in 10 steps and panel dimmer (backlighting) in five.

1. Press the **BRILL** key to open the dialog box for screen brilliance and panel dimmer adjustment. Do the next step within four seconds, otherwise the dialog box will be erased.
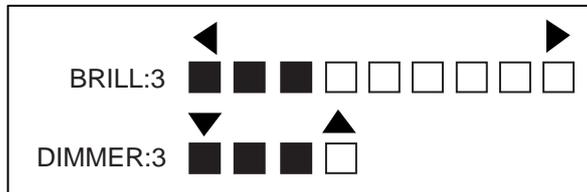
Brilliance, panel dimmer dialog box

2. Press ◄ or ► as appropriate to adjust screen brilliance (0 is the lowest brilliance; 9 the highest). Note that continuous pressing of the **BRILL** key also changes the brilliance level.
3. Press ◄ or ► as appropriate to adjust the panel dimmer (0 is the lowest level; 4 is the highest).
4. Press the **MENU** key to register settings and close the dialog box. Note that the dialog box is automatically erased if there is no control operation within about four seconds.

Note 1: The brilliance of a commercial monitor cannot be adjusted with the **BRILL** key. Use the associated control on the monitor.

Note 2: For the supplied monitor unit, if you turn off the power with the brilliance set at minimum the screen will show nothing at next power-up. In this case press the **BRILL** key several times to raise the brilliance.

1.6   Choosing a Display

12 displays are provided; choose the one which best suits your current needs. For a description of each display, see Chapter 2.

Single-frequency displays

Key	Display	Key	Display
	HORIZONTAL This mode provides 360 degree coverage. Useful for general search. (Chapter 2)		**EXPANDED HORIZONTAL** Expanded horizontal picture appears over the entire screen. (Chapter 2)
	VERTICAL SCAN Vertical section of underwater conditions appears on the entire screen. (Chapter 3)		**ECHO SOUNDER** Using a fixed spot beam this display shows fish echoes below or around the vessel. (Chapter 4)
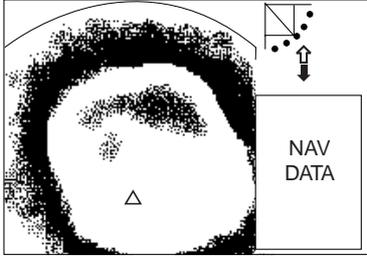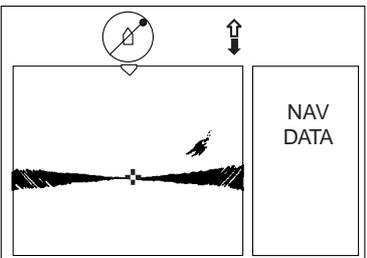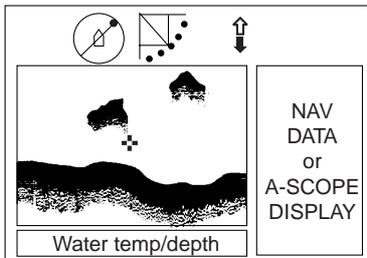
Single-frequency displays

<u>Dual-frequency displays</u>

Key	Display	Key	Display
⊙ x2	DUAL-FREQ HORIZONTAL 360° dual-freq. display of fish echoes, etc. (Chapter 2)	⬭ x2	DUAL-FREQ. HORIZ. EXPANSION Expansion of dual-freq. horizontal display. (Chapter 2)
⬠ x2	NAV DATA DUAL-FREQ. VERTICAL SCAN Dual-freq. display of vertical section of fish echoes. Useful for judging depth and center position of fish school. (Chapter 3)	▱ x2	NAV DATA or A-SCOPE Depth/Temp. Display DUAL-FREQ. ECHO SOUNDER Dual-freq. display of fish echoes below vessel. (Chapter 4)
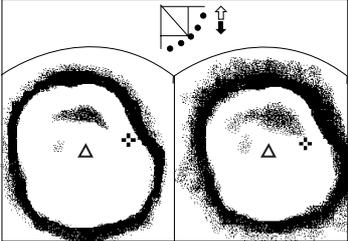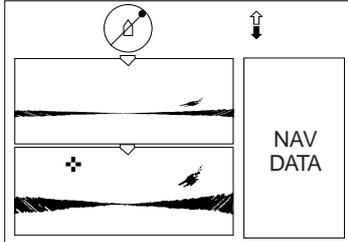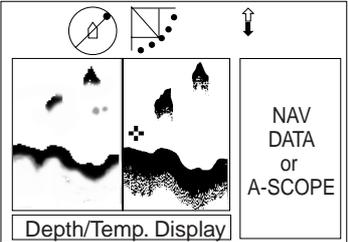
Dual-frequency displays

Combination displays

Key	Display	Key	Display
⊙□ + Choose ◯▣	 HORIZONTAL/HISTORY The horizontal picture appears in the main window; the history picture in the sub window. Useful for showing history of fish movement, distribution. (Chapter 2)	⊙□ + Choose ◯▣	 HORIZONTAL/VIDEO PLOTTER The horizontal picture appears in the main window and the video plotter picture, which traces ship's track, in the sub window. (Chapter 2)
⊙□ + Choose ◯▣	 HORIZONTAL/VERTICAL SCAN The horizontal picture appears in the main window; the vertical fan picture in the sub window. (Chapter 3)	⊙□ + Choose ◸	 HORIZONTAL/VERTICAL ZOOM The horizontal picture appears in the main window; vertical zoom picture in the sub window. (Chapter 3)
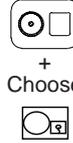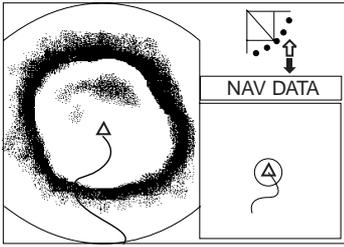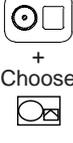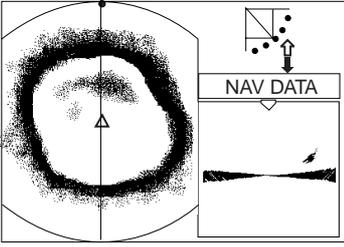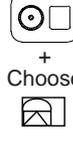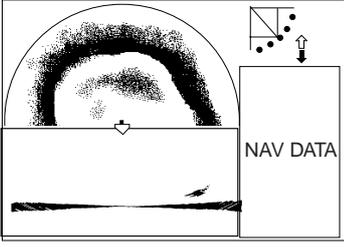
Combination displays

1.7   Choosing a Frequency

You may choose low frequency or high frequency, with the **LF/HF** key. The display shows HI or LO at the top of the screen depending on your selection. Use the table below to determine which frequency to use.

Item	Low frequency	High frequency
Long-range detection	**PREFERABLE** Attenuation loss is small on low frequency.	**NOT RECOMMENDED** Attenuation loss is great on high frequency.
Use in shallow waters	**NOT RECOMMENDED** Bottom echo is prominent because of wide beam width so fish echoes are hidden.	**PREFERABLE** Bottom echo is less prominent because of narrow beam width so fish echoes are easy to find.
Detection range (detection "leaks")	**PREFERABLE** Detection area is wide (beam width is wide).	**NOT RECOMMENDED** Detection area is narrow (beam width is narrow).
Detection of bottom fish	**NOT RECOMMENDED** Fish echo and bottom echo overlap. (Wide beam width)	**PREFERABLE** Fish echo and bottom echo are displayed separately. (Narrow beam width)
Detection of bait fish	**NOT RECOMMENDED** Not suited for this purpose. (Bait fish are not easily detected with low frequency.)	**PREFERABLE** Well suited for this purpose. (Bait fish are more easily detected with high frequency.)
Affected by air bubbles from other vessels	**NOT RECOMMENDED** Low frequency is easily interfered by cavitation from other vessels.	**PREFERABLE** High frequency is not easily interfered by cavitation from other vessels.

The dual-frequency display is useful for comparing the picture from one frequency against the other to overcome deficiencies in both. Use the single-frequency for objective-specific fishing.
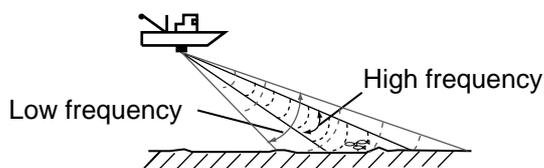
Frequency selection and mode

Single-frequency display or combination display (other than vertical scan combination): The **LF/HF** key chooses low frequency or high frequency alternately.

Dual-frequency display (mix mode OFF): The **LF/HF** key switches the frequency of the high-and low-frequency displays alternately.

Dual-frequency display (mix mode ON): The **LF/HF** key changes the frequency of the left-hand display* (top display in dual-frequency vertical scan display) from low to high alternately.

* Dual-frequency horizontal display, Dual-frequency horizontal expansion display, Dual-frequency echo sounder display.
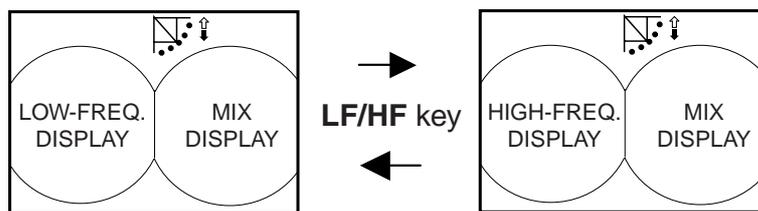
Frequency switching in dual-frequency combination display, mix display ON

Combination display (vertical scan combination):
Main window is active: The **LF/HF** key changes the frequency of the main window from low to high alternately.
Sub window is active: The **LF/HF** key changes the frequency of the sub window from low to high alternately.

To switch between main and sub windows use the **MAIN/SUB** key.

1.8   Mix Display

The mix display compares echo intensity between low and high frequencies, and displays echoes from tiny fish in discriminative colors. This is done by utilizing the fact that tiny fish return a stronger echo against a high frequency rather than a low frequency. The equipment accomplishes this as follows:

- If a high frequency echo is stronger than the corresponding echo on the low frequency, the high frequency echo is displayed.
- If the low frequency echo is stronger than or equal to the high frequency echo, it is less likely to be a tiny fish and therefore is displayed in blue.

In other words, the echoes displayed in orange thru light-blue may be considered to be tiny fish such as whitebait. When the mix display is active the indication MX appears at the top of the display.
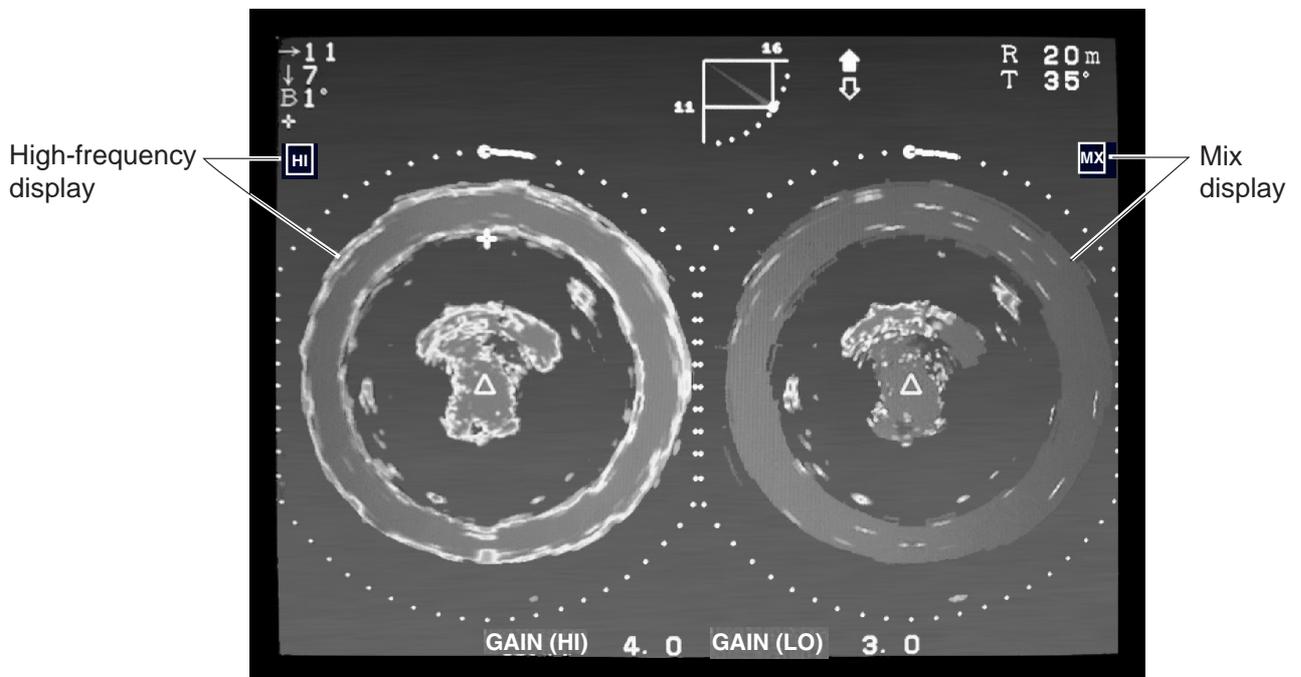
How the mix display works

To use the mix display effectively, it is important that the gain for both the low and high frequencies is set properly. When searching for young fish such as whitebait, follow the procedure below. For detailed information about gain adjustment, see the next section.

Gain adjustment

1. Adjust the high-frequency gain while observing targeted fish.
2. While observing the mix display, set the low-frequency gain to 0 and gradually raise it just until echoes from adult fish disappear from the mix display.
3. While observing the echoes from young fish on the mix display, readjust the low-frequency gain in order to distinguish young fish. When the echoes from young fish are weak, lower the low-frequency gain. If adult fish appear, raise the low-frequency gain. (Rule of thumb: For whitebait, low-frequency gain is set 3-4 steps lower than high-frequency gain.)

To activate the mix mode, press the **MIX** key. How to display the mix display depends on the display mode in use.

Single-frequency display or combination display (other than vertical scan combination): Use the **MIX** key to switch between the mix display and the single-frequency display alternately.

Dual-frequency display: Use the **MIX** key to switch between the mix display and the dual-frequency display alternately.
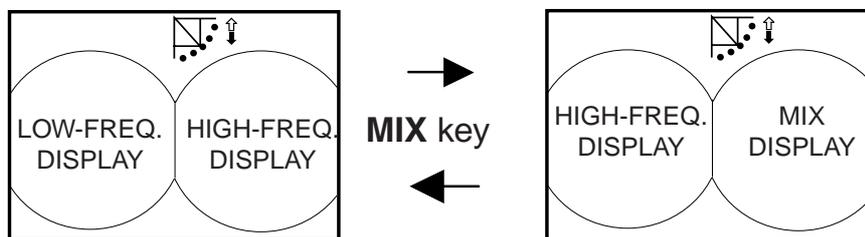
How the MIX key works in dual-frequency mode

Combination display (vertical scan combination:
Main window is active: The **MIX** key changes the frequency of the main window from low to high alternately.
Sub window is active: The **MIX** key changes the frequency of the sub window from low to high alternately.
To switch between main and sub windows use the **MAIN/SUB** key.

1.9   Adjusting the Gain

The **GAIN** control adjusts the sensitivity of the receiver. Normally, the control is adjusted so that the bottom echo is displayed in reddish-brown mixed with red. Initially set the gain between "4" and "6" and then fine tune according to fishing ground, etc.

Too Low	Proper	Too High
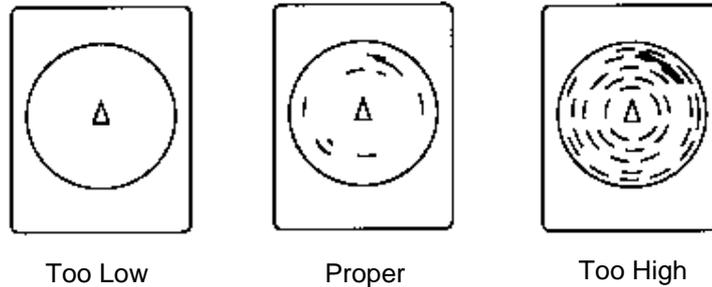
How to adjust the gain

Single-frequency or combination display

When using both high and low frequency in the horizontal/vertical scan display, refer to the procedure on the next page.

1. Push the **GAIN** control.

> HIGH FREQ GAIN: 5.0   (0-10)
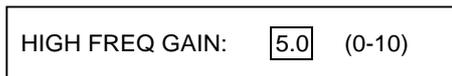
2. Turn the **GAIN** control to adjust the gain (range: 0-10).
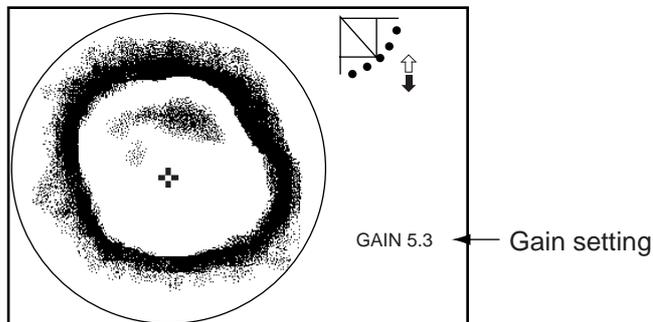
Location of gain setting indication

3. Press the **MENU** key to close the gain setting window. Note that it is not necessary to press the **MENU** key – the window will automatically if no operation is detected for four seconds.

Note 1: Step 1 is not necessary if the menu item GAIN SETTING PROTECT (SYSTEM SETTING 2 menu) is set for OFF.

Note 2: You can switch control between the main and sub windows in the horizontal/vertical scan display with the **MAIN/SUB** key.

Dual-frequency display

1. Push the **GAIN** control.

| HIGH FREQ GAIN : 5.0 | (0-10) |
| LOW FREQ GAIN : 5.0 | (0-10) |

PUSH GAIN KNOB TO SPECIFY THE FREQ
ROTATE GAIN KNOB TO CHANGE THE FREQ

2. Push the **GAIN** control to choose the frequency for which you want to adjust the gain.
3. Rotate the **GAIN** control to adjust the gain (range: 0-10).
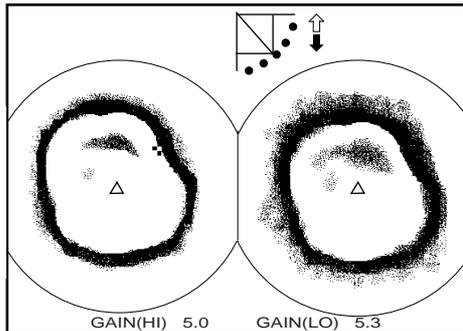
Gain setting high and low frequencies

Location of gain setting indications on dual-frequency display

4. Press the **MENU** key to close the gain setting window.

1.10 Menu Overview

The menu, consisting of six menus, mostly contains items which once preset do not require frequent adjustment. Below is the procedure for basic menu operation.

1. Press the **MENU** key to open the menu.

   Note: Either PRESET (default setting) or SHORT-CUT appears between ES and SYS at the top of the screen depending on the setting of CUSTOM KEY on the SYSTEM SETTING 1 menu, and they set the function of the custom keys [1], [2], [3]. For further details see pages 5-3 through 5-7.)

```
MENU          COM1  COM2  HORZ  VERT  ES  PRESET   SYS

  DELETING TRACK    NO
  MIX MODE          STANDARD
  WHITE MARKER      OFF
  SIG LEVEL         OFF
  COLOR             16
  BKGD COLOR        2




▲▼ : SELECT ◄ ► : CHANGE    MENU: END
```

COM2 menu

2. The last-used menu is displayed. To choose a different menu, press ▲ to choose MENU and then press ◄ or ► to choose menu desired.
3. Press ▲ or ▼ to choose menu item desired. At the bottom of the screen menu help is provided.
4. Press ► to open the corresponding dialog box. The example below shows the dialog box for DELETING TRACK, which is in the COM2 menu.

```
DELETING TRACK

NO   YES
```

Dialog box for deleting track

5. Press ◄ or ► to choose option desired. If the option requires input of numeric data, use ◄ or ► to lower or raise the figure, respectively.
6. Press ▲ or ▼ to return to the menu, or press the **MENU** key to register your selection and close the menu.

1-15

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2. HORIZONTAL MODE

2.1 Operational Overview

The figure below shows the typical horizontal mode operating sequence.
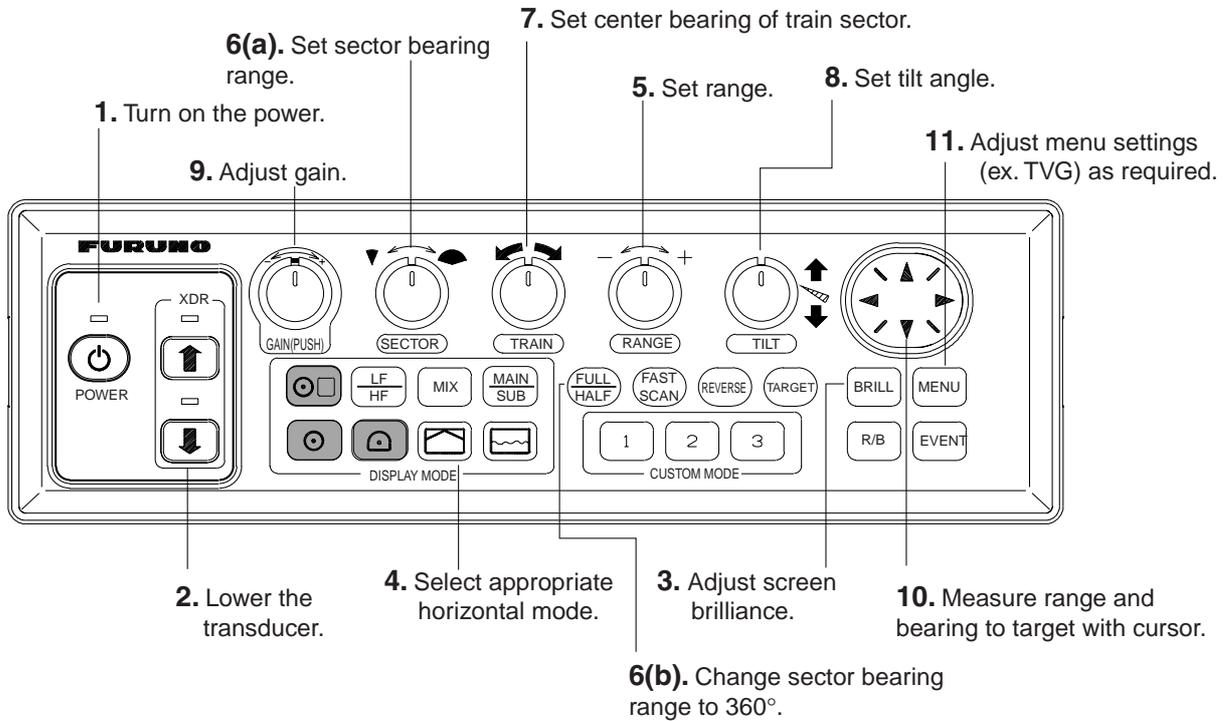
Control panel

2.2   Typical Horizontal Mode Display

Press the ⊙ (horizontal mode) key. Each press chooses the single frequency or dual-frequency horizontal mode display alternately.

Single-freq. Display   Dual-freq. Display
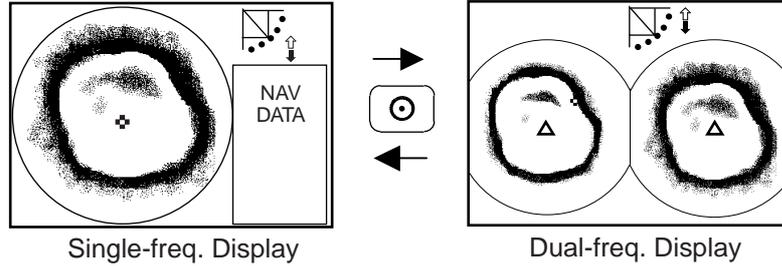
Switching between single-frequency horizontal and dual-frequency horizontal displays

* **Depth marker**
When depth data is input from external equipment, the depth marker shifts according to depth data. If the depth data is greater than the horizontal range, the depth marker shifts to lowest position.
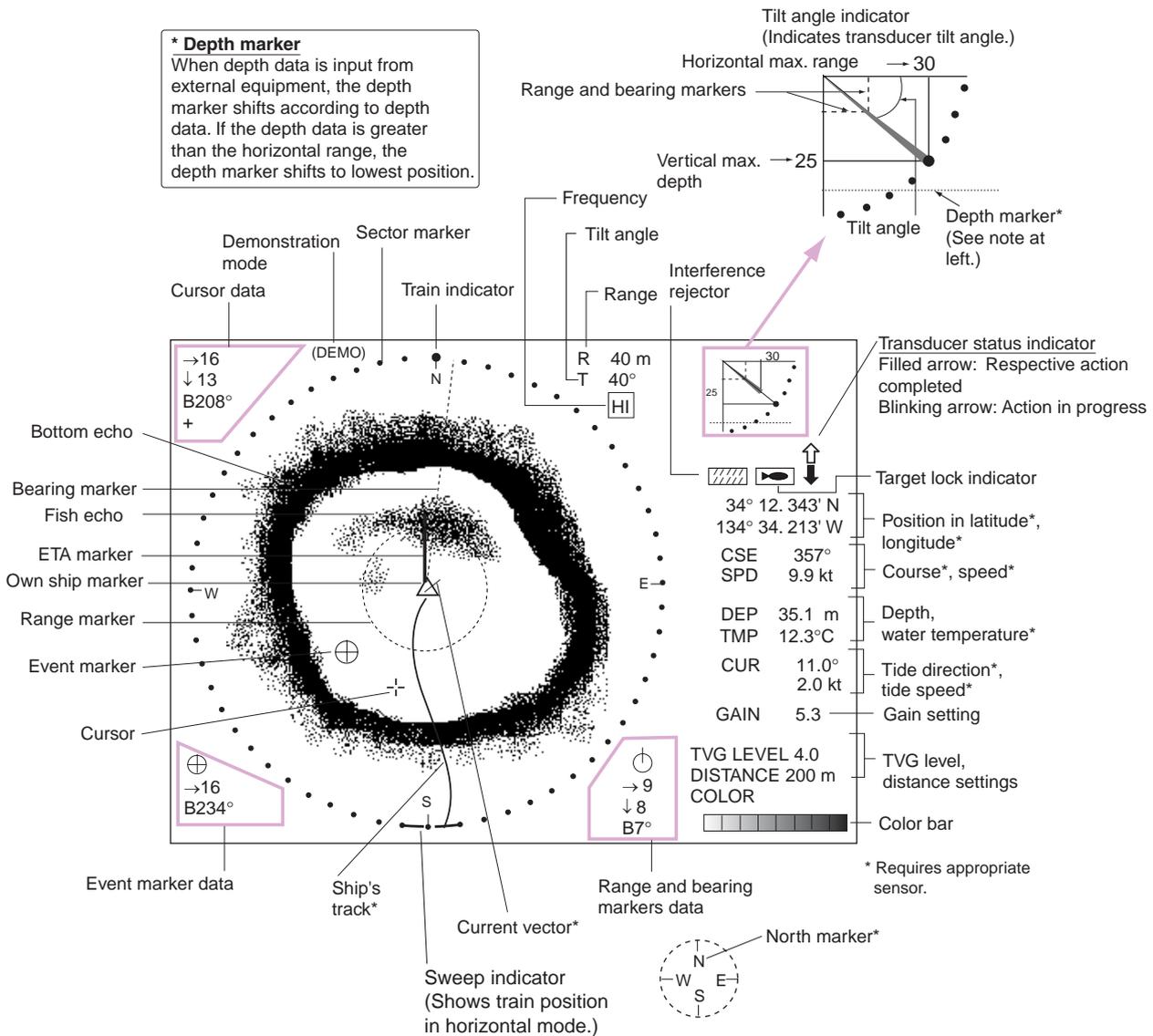
Single-frequency horizontal display

2.3   Choosing a Range

The **RANGE** control chooses the detection (display) range. Choose the range according to either the fish species being searched or the depth desired. 15 ranges are available and minimum and maximum ranges depend on the transducer used.
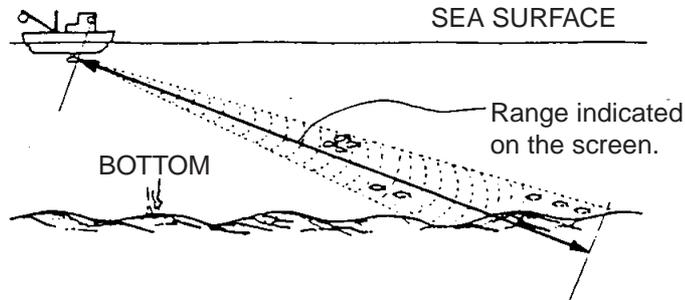
Range description

Default horizontal mode range settings

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
m	20	40	60	80	100	120	160	200	250	300	400	500	600	800	1200
ft	50	100	200	300	400	500	600	700	800	1000	1200	1500	2000	3000	4000

Normally the range is set so that the bottom is traced at the lower part of the screen (like an echo sounder). Each time the **RANGE** control is operated the newly selected range briefly appears in large characters at the screen top. Range is always displayed at the right-hand corner of the screen.

Note 1: Unit of range measurement may be chosen from among meters, feet, fathoms, passi/braza or Hiro (Japanese) with UNIT on the SYSTEM SETTING 1 menu. For details see page 5-11.

Note 2: Ranges may be freely preset as desired. For details see page 5-14.

2.4   Choosing Sector Width

You may set the width of the scanned sector.
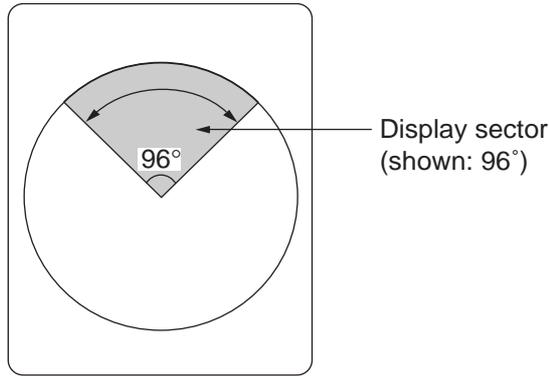
Sector width

The **SECTOR** control chooses the width of the scanned sector among the sixteen positions shown in the table below. Clockwise rotation of the control increases the sector width; counterclockwise rotation decreases it.

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Sector width (°)	6	24	48	72	96	120	144	168	192	216	240	264	288	312	336	360

In the full-circle mode (360°) the direction of training is clockwise; in the half-circle mode the direction is clockwise to counterclockwise alternately.

One-touch selection of 360° sector

Each pressing of the **FULL/HALF** key alternately chooses 360° sector (full circle) or 168° sector (half circle). If the **SECTOR** control is operated following the selection of the full-circle display, the next pressing of the **FULL/HALF** key presents the full-circle display.
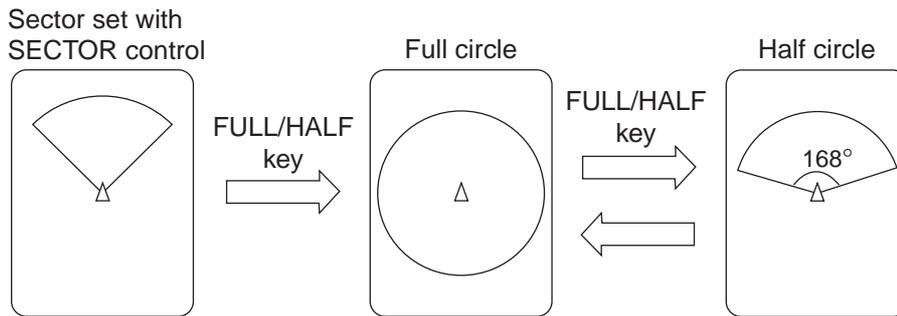
How the FULL/HALF key works

2.5   Choosing Train Center

The **TRAIN** control chooses the center direction of the detection range. The range of adjustment is 0° to 354° in increments of 6°. The selected bearing is shown with a filled circle, the train indicator, on the bearing scale.

0° (360°) → 6° → 12° → 18° → ... 354°

Train center
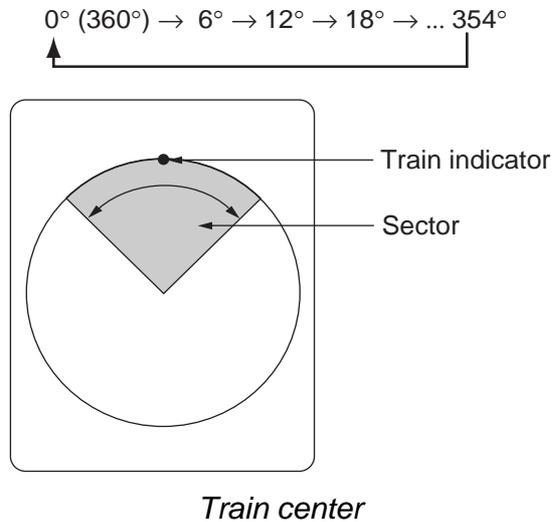
2.6   Choosing a Tilt Angle

The tilt angle shown the direction to which the sound wave is emitted. When the sound wave is emitted horizontally, the tilt angle is said to be 0° and when emitted vertically, 90°.

To set a tilt angle, operate the **TILT** control. Watch the tilt angle indication and tilt angle indicator at the top right corner of the screen. The tilt angle can be set in increments of 1° from 0° to +5° (upward) to 0° to 90° (downward). Choose tilt angle depending on target fish. For surface fish choose a narrow angle (about 5°) and for bottom fish, a wide angle (about 40°).
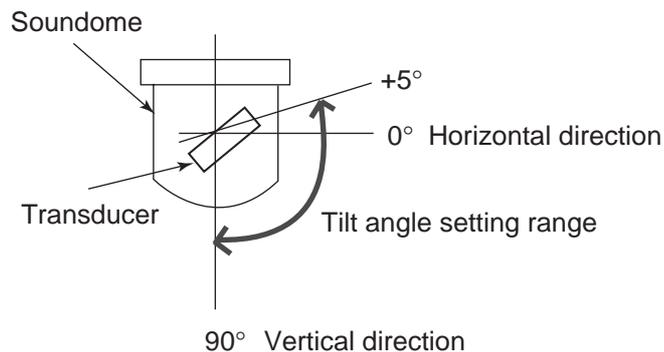
2.6.1   Tilt angle for surface fish

Sound emitted from the sonar transducer forms an oval-shaped beam with a width of approximately 10° (–3 dB, full scan, vertical beam width on 85 kHz) in the vertical direction (vertical beam width). The tilt angle is indicated by the angle between the center line is parallel with the sea surface and one half of the emitted sound goes upward, toward the sea surface. This causes one half of the emitted sound to be reflected toward the transducer and displayed on the screen as sea surface reflections. When the sea is calm, since the sound is reflected just like reflections become negligible.

However if the sea is not calm enough, they will become dominant and interfere with observation of wanted echoes. To minimize these sea surface reflections and to search fish schools effectively, the tilt angle is usually set between 5° and 7° so the upper portion of the beam becomes almost parallel with the sea surface. When the sea is rough, the tilt angle is slightly increased to lessen the affect of sea surface reflections.

Tilt angle
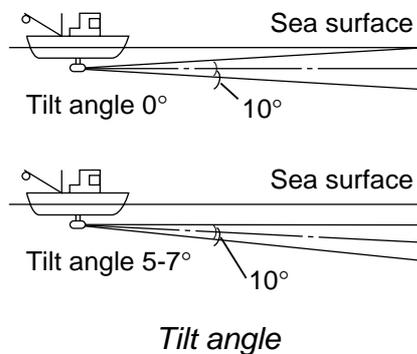
2.6.2   Distinguishing fish echo from bottom echo in coastal waters

In coastal operations the bottom reflection is prominent so it is important to be able to distinguish fish echoes from the bottom echo. The information below will help you to do this.

Tilt angle and bottom echo

Case 1 - Tilt angle 30° to 40°: The bottom echo, captured by the vertical beam width (10° at -3dB full circle, 85kHz), is displayed "ring-shaped" and in strong colors.

Case 2 - Tilt angle 10° to 20°: The bottom echo is displayed wider and in weak colors as the distance to the bottom increases.

Case 3 - Tilt angle 0° to 5°: The bottom echo is either weak or is not displayed even if the vertical beam width captures the bottom echo, because the distance to the bottom is too far.

How to discriminate fish echoes from the bottom

The figure at the bottom of the page illustrates how two fish schools "a" and "b" are displayed on the screen using three different tilt angles.
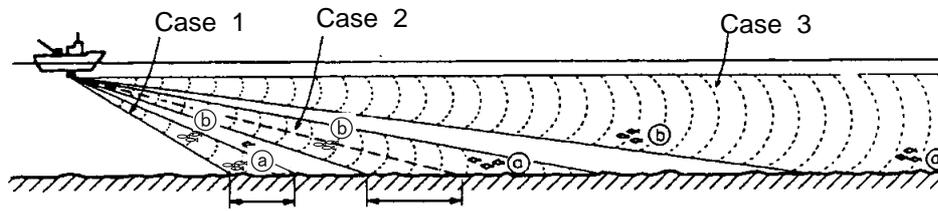
(Case 1, 2 and 3 are relative to the bottom pictured above.)

Detecting beam and fish position

Using the above three cases, fish schools will be displayed as below.
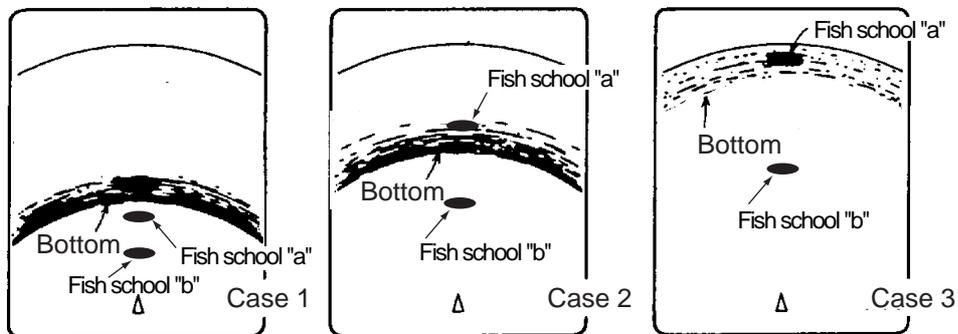
Fish echo and tilt angle

Case 1(Tilt angle 30° to 40°):   Fish school "a" and "b" are just above the bottom echo.

Case 2(Tilt angle 10° to 20°):   Fish school "b" is clearly seen. Fish school "a" is behind the bottom echo therefore it is difficult to discern.

Case 3(Tilt angle 0° to 5°):   Bottom echo is weak so fish school "b" is easily seen. Fish school "a" is masked by the bottom echo so it is difficult to discern. However, larger fish schools may appear in this condition.

2.6.3   Suitable tilt angle

The figure below illustrates the relationship among tilt angle (0, 5, 10 and 15 degrees), depth and detection range. Refer to it to find out the suitable tilt angle for a given depth/detection range.

Tilt angle and beam coverage (frequency 85 kHz, vertical beamwidth 10° at -3 dB)
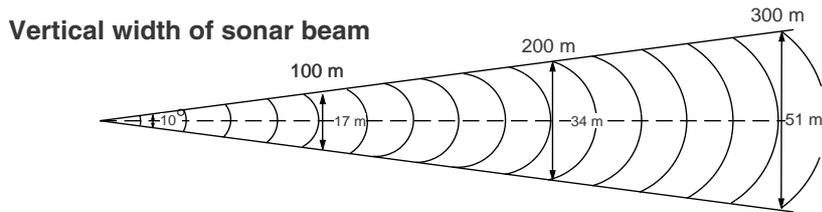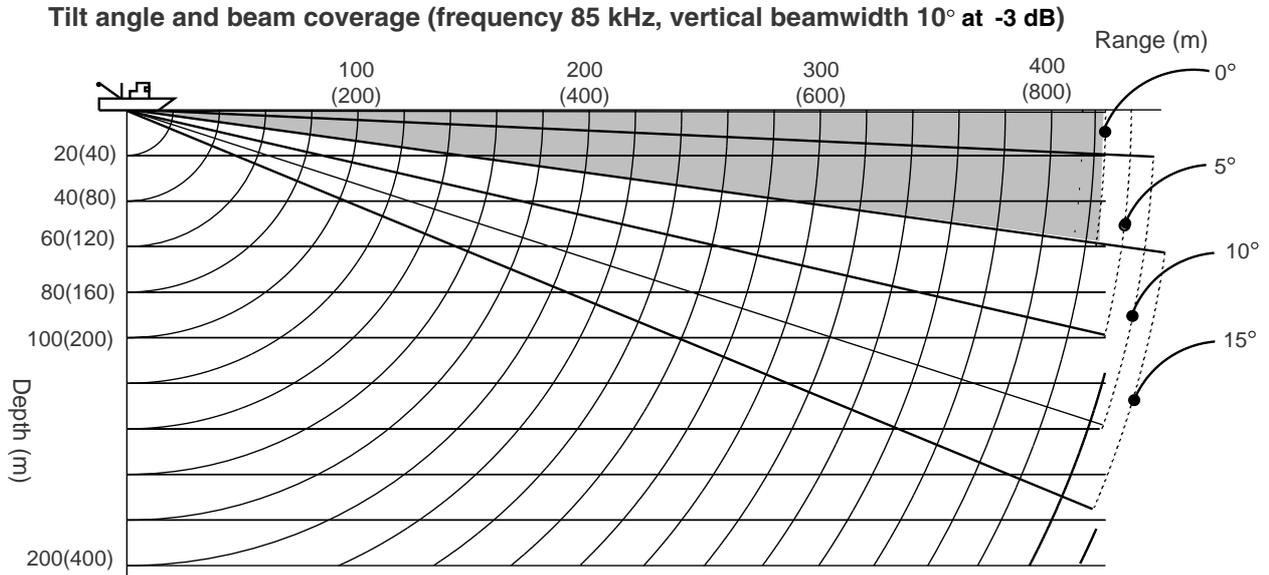
Tilt angle and beam coverage

Frequency and detection range

Frequency	Vertical beam width	100 m	200 m	300 m
85 kHz	10° -3 dB	17 m	34 m	51 m
60 kHz	14° -3 dB	24 m	48 m	72 m
153 kHz	5° -3 dB	9 m	18 m	27 m
215 kHz	4° -3 dB	7 m	14 m	21 m

2.7   Choosing Training Speed

The training speed chooses how fast the transducer scans the sounding sector. Two choices are available, normal speed (default setting) and high speed, and one may be selected with the **FAST SCAN** key. Each time the key is pressed "NORM" (normal speed) or "FAST" (high speed) momentarily appears at the screen top.

Normal (6°) :   60 transmissions required to complete full 360° picture (default setting).
High (12°) :   On ranges higher than 160 m, 30 transmissions required to complete the full 360° picture.

The time necessary to train a full circle depends on frequency, range and mode. The table below shows the time required to complete one full circle in the horizontal mode.

Single frequency

Range (m)		20	40	60	80	100	120	160	200	250	300	400	500	600	800	1200
Time (sec)	NS*	9	9	9	9	9	11	14	17	21	25	33	41	49	65	97
	HS*	9	9	9	9	9	11	12	14	16	18	22	26	30	38	54

Dual frequency

Range (m)		20	40	60	80	100	120	160	200	250	300	400	500	600	800	1200
Time (sec)	NS*	11	11	11	11	11	12	15	18	22	26	34	42	50	66	98
	HS*	11	11	11	11	11	12	14	15	17	19	23	27	31	39	55

* NS, Normal Speed, HS, High Speed

2.8   Changing Training Direction

The training direction may be reversed to reconfirm fish echoes. Press the **REVERSE** key to reverse training direction between counterclockwise and clockwise alternately. "REVERSE" appears at the top of the screen for three seconds when training direction is reversed.

2.9   Finding Echo Position with the Cursor

The cursor measures horizontal range, depth and bearing. Operate the Omnipad to place the cursor where desired. Cursor position data appears at the top left-hand corner on the screen.
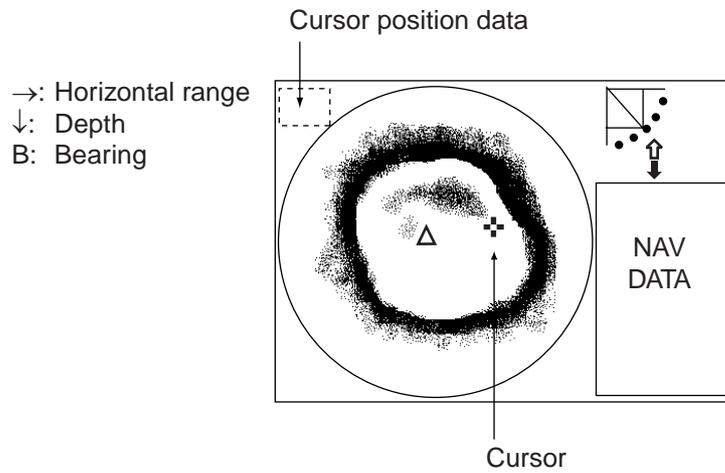
Location of cursor position data

2.10 Event Marker

The event marker functions to mark important locations on the horizontal mode display, and five event markers may be inscribed. Press the **EVENT** key to inscribe the event marker. Each time the key is pressed the "latest event marker" (⊕) is inscribed at the cursor location and all previously entered event markers are shown by the "previous event marker" (+). Five event markers may be entered and when the capacity for event markers is reached the eldest event marker is erased from the screen to make room for the latest.

Note 1: Event markers cannot be entered from the history or video plotter display (other display in horizontal combination displays). Event markers may only be entered from the horizontal display.
Note 2: The tilt angle must be less than 75-degrees. Correct event marker position data is not possible with the tilt angle higher than 75-degrees.
Note 3: Event marker position may be output to external equipment. See paragraph 5.4.2
Note 4: Event markers are only erased from the currently used display (horizontal, vertical, echo sounder).

<u>**Entering an event mark**</u>

1. Operate the Omnipad to place the cursor on the location desired for an event marker.
2. Press the **EVENT** key to inscribe the event marker. Event marker data appears at the bottom left-hand corner.
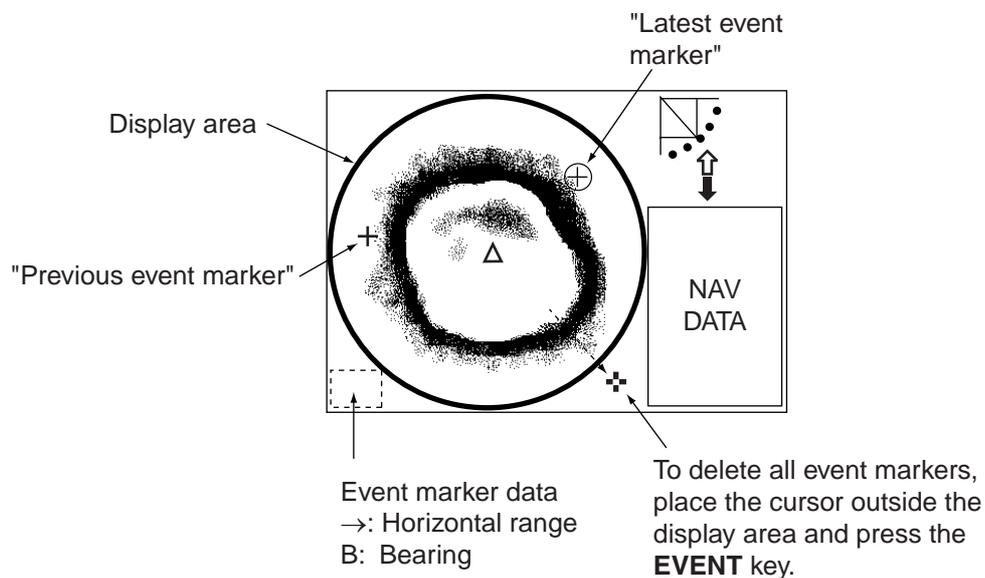
How to use the event marker

Deleting all event markers from the horizontal display

To delete all event markers inscribed on the horizontal mode display, do the following:

1. Operate the Omnipad to place the cursor outside the display area.
2. Press the **EVENT** key to show the following dialog box. Do the next step within four seconds, otherwise the dialog box will be erased.

> DELETE EVENT MARK?
>
> **NO**   YES
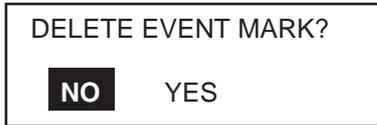
3. Press ► to choose YES and then press the **MENU** key.

2.11   Depth and Horizontal Range Markers

The horizontal range, depth and bearing to a fish school can be measured by using the range and bearing markers.

Note: Range and bearing markers cannot be inscribed on the history display or video plotter display.

1. Operate the Omnipad to place the cursor on the location desired.
2. Press the **R/B** key to display the range and bearing markers. Horizontal range, depth and bearing to the cursor location are shown at the bottom right-hand corner of the screen.
3. To erase the range and bearing markers, place the cursor outside the display area and press the **R/B** key, or place the cursor on the range or bearing marker and press the **R/B** key.

Range and bearing markers

Dashed lines show horizontal range and depth of range marker.

NAV DATA

Bearing marker

Range marker

Range and bearing markers data
→: Horizontal range
↓: Depth
B: Bearing from ship's bow
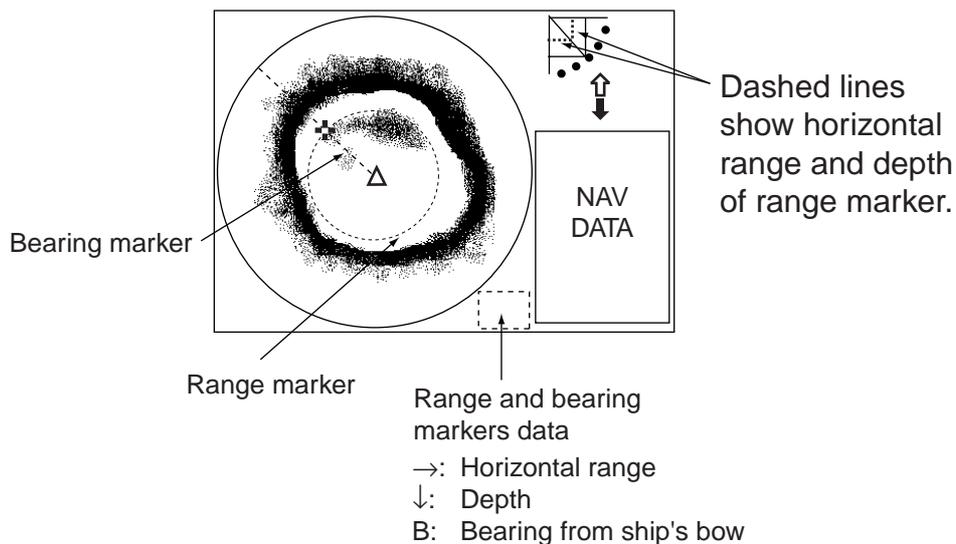
2.12 Adjusting the Picture

2.12.1 Suppressing bottom and surface reflections

In shallow fishing grounds, excessive sea surface and bottom reflections often interfere with wanted fish echoes and they cannot be eliminated sufficiently with the TVG controls. In such cases, try to reduce the output power, without turning down the gain. The picture becomes clearer when output power is reduces rather than when the gain is decreased.

Maximum TX power   Minimum TX power
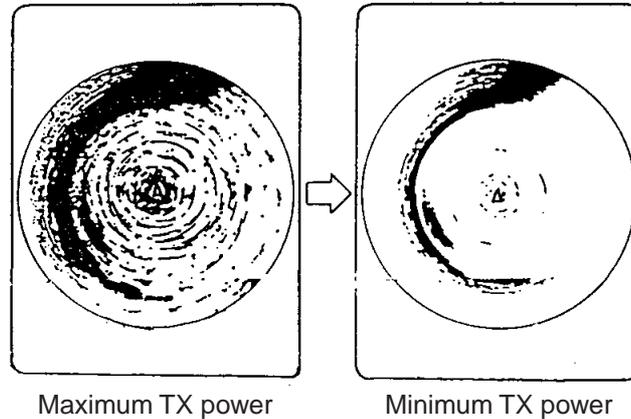
Sonar image and TX power setting

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ to choose the COM1 menu.

MENU	COM1	COM2	HORZ	VERT	ES	PRESET	SYS
TX POWER	MAX						
PULSELENGTH	LONG						
TX RATE	10						
INT REJECT	OFF						
AGC	OFF						
AUDIO LEVEL	0						

▲▼ : SELECT ◄ ► : CHANGE   MENU: END
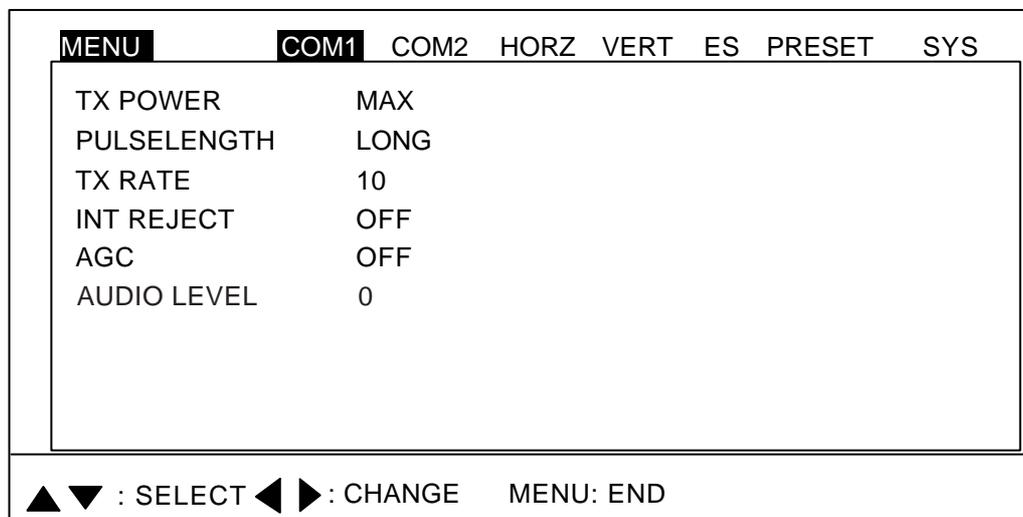
COM1 menu

3. Press ▲ to choose TX POWER and then press ►. The following dialog box appears.

TX POWER
MAX   MIN
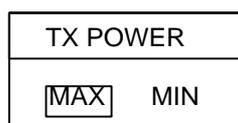
4. Press ► to choose MIN. (For long-range detection be sure to return the setting to MAX.)
5. Press the **MENU** key to register your selection and close the menu.

2.12.2   Suppressing bottom tail

As described earlier, fish schools near the bottom are sometimes difficult to detect because you have to discriminate fish echoes from the bottom reflections. To discriminate fish echoes near the bottom, choose the short Tx pulselength on the COM1 menu to decrease the tail of bottom reflections.

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ to choose the COM1 menu.
3. Press ▲ or ▼ to choose PULSELENGTH and then press ►. The following dialog box appears.

```
 PULSELENGTH

 LONG   SHORT
```
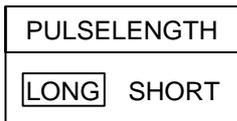
4. Press ► to choose SHORT.
5. Press the **MENU** key to register your selection and close the menu.

2.12.3   Displaying weak echoes clearly

Echoes from targets (such as the bottom or a fish) return to the transducer in order of the distance to them, and when their intensities are compared at the transducer face, those from nearer targets are generally stronger when their reflecting properties are nearly equal. The sonar operator will be quite inconvenienced if these echoes are directly displayed on the screen, since he won't be able to judge the actual size of the target from the size of echoes displayed on the screen. To overcome this inconvenience, use the TVG function. It compensates for propagation loss of sound in water: amplification of echoes on short range is suppressed and gradually increased as range increases, so that similar targets are displayed in similar intensities irrespective of the ranges to them.

The TVG also functions to suppress unwanted echoes and noise which appears in a certain range area on the screen.

How TVG works

Note: Excessive TVG may eliminate short-range echoes.

To adjust TVG:

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ or ► to choose HORZ.
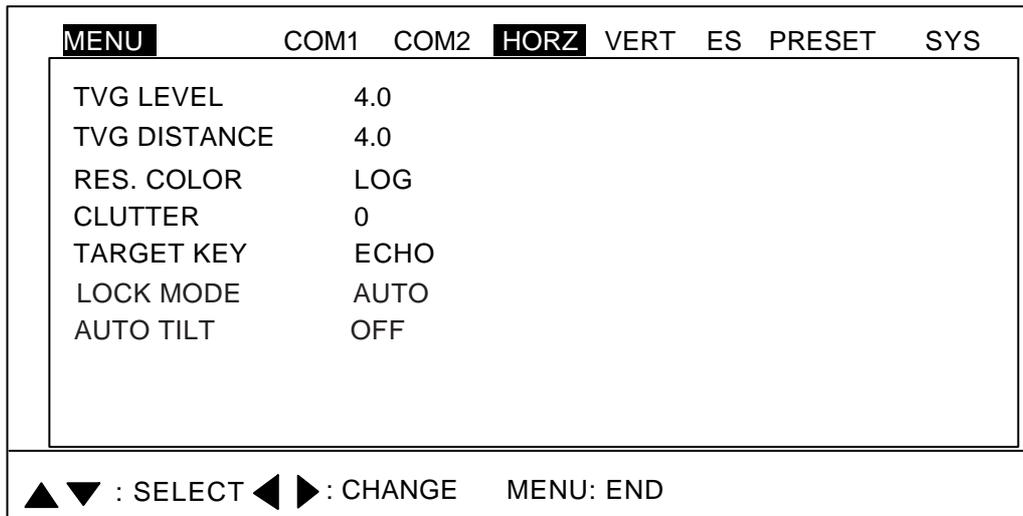
```
┌─────────────────────────────────────────────────────────────┐
│ MENU        COM1   COM2   HORZ  VERT  ES  PRESET    SYS       │
│                                                               │
│   TVG LEVEL          4.0                                       │
│   TVG DISTANCE       4.0                                       │
│   RES. COLOR         LOG                                       │
│   CLUTTER            0                                         │
│   TARGET KEY          ECHO                                     │
│   LOCK MODE          AUTO                                      │
│   AUTO TILT          OFF                                       │
│                                                               │
│                                                               │
├─────────────────────────────────────────────────────────────┤
│  ▲▼ : SELECT ◄ ► : CHANGE     MENU: END                       │
└─────────────────────────────────────────────────────────────┘
```

HORZ menu

3. Press ▲ or ▼ to choose TVG DISTANCE and press ►. The following dialog box appears.

```
┌──────────────────────────────────┐
│   TVG DISTANCE  │    4.0          │
│─────────────────┴────────────────│
│                                   │
│ Hi ┤        _____      │
│    │      /                       │
│    │    /                         │
│    │  /                           │
│    │ /                            │
│    │/                             │
│ Lo └┴─┴─┴─┴─┴─┴─┴─┴─┴─┴           │
│        200m                       │
└──────────────────────────────────┘
```
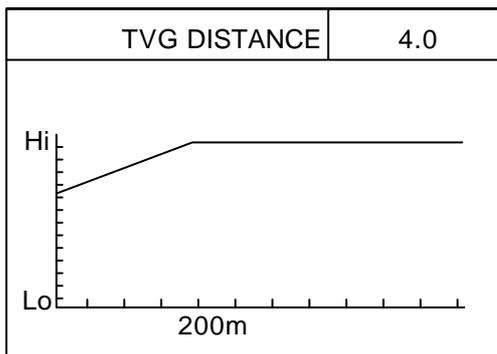
4. Press ◄ or ► to adjust TVG distance between 3.0 and 5.0 (130-320 m). As a general rule, use a higher setting for low-frequency transducer; a lower setting for high frequency transducer. The larger the figure the greater the distance at which TVG works. When you open the TVG dialog box the TVG line changes from solid to dashed and a solid line denotes current TVG setting.

TVG Distance Setting	0	0.5	1.0	1.5	2.0	2.5	3.0	3.5	4.0	4.5	5.0	….	10.0
Meters	3	8	20	40	60	100	130	160	200	250	320	….	1000
Feet	10	30	70	130	210	330	410	520	660	820	1040		3280
Passi/braza	2	5	10	20	40	60	80	100	120	150	180		600
Hiro	2	5	10	20	40	60	80	100	130	170	210	….	660

5. Press the **MENU** key to register your selection and close the menu.
6. To suppress reflections by the sea surface or plankton, choose TVG LEVEL and press ►.
7. Press ◄ or ► to adjust TVG LEVEL, considering sea conditions. A setting between 2.0 and 5.0 should provide satisfactory results. The higher the figure the less the gain over distance.
8. Press the **MENU** key to register your selection and close the menu.
9. Watch a distant fish echo which is approaching own ship, adjusting the tilt angle so the fish echo is within the sounding beam. Observe color of fish echo. If the color and size of the echo stay the same as the echo approaches own ship, the TVG setting is proper. If the echo suddenly becomes smaller, the TVG level may be too high.

2.12.4 Erasing weak echoes

Weak echoes such as interference can be erased from the screen, using the "signal level" feature. This is useful when you want to observe a fish school echo.

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU.
3. Press ◄ to choose COM2.
4. Press ▲ or ▼ to choose SIG LEVEL.
5. Press ► to open the dialog box.

SIG LEVEL	OFF
OFF 1	14

(OFF, 1-14)

8-color display: OFF, 1-6
16-color display: OFF, 1-14
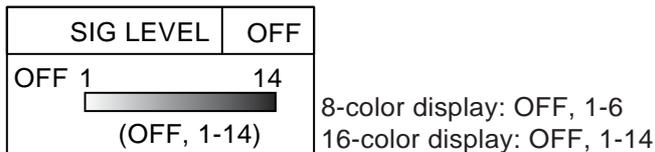
6. Press ◄ or ► to choose echo color to erase. Pressing ► erases echoes from weak to strong in ascending order of strength. You can also see which echo color is erased by watching the color bar.
7. Press the **MENU** key to register your selection and close the menu.

2.12.5   Suppressing interference from marine life

If you are fishing in an area where there are a lot of fishing vessels, you may receive interference from other vessels' sonar or echo sounder. Further, electrical interference onboard own ship may generate interference. To suppress this type of interference use the interference rejector.
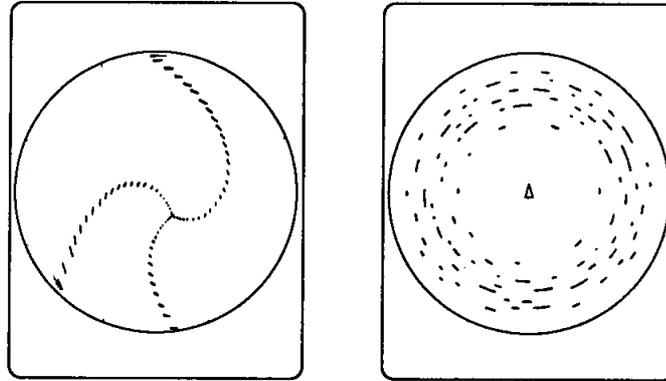
(A) Inteference from other sonars (yours or other's)

(B) Interference from marine life

Interference from other sonars, marine life

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ to choose the COM1 menu.
3. Press ▲ or ▼ to choose INT REJECT and then press ►. The following dialog box appears.

```
INT REJECT

 OFF  LoFREQ  HiFREQ  BOTH
```
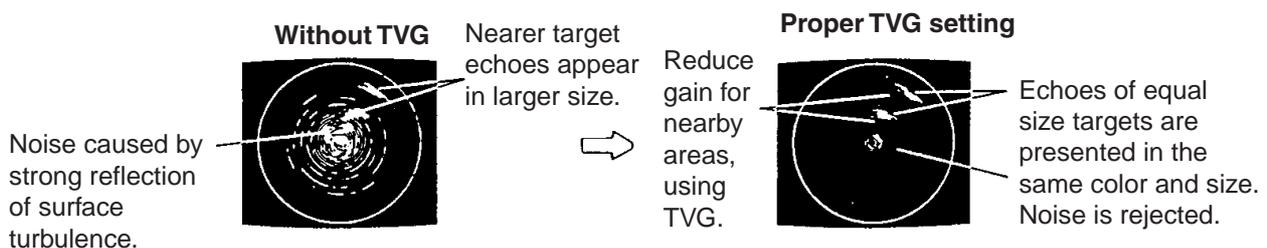
4. Press ◄ or ► to choose the frequency where you want to suppress interference. When the interference suppressor is turned on ▨ appears at the top of the screen.
5. Press the **MENU** key to register your selection and close the menu.

Note that the interference rejector cannot be turned on/off independently for each frequency in case of the dual-frequency display.

2.12.6 Enlarging fish echoes (horizontal expansion display)

Fish echoes may be enlarged 1.5 times by using the horizontal expansion display. Press the ⊙ key to activate the horizontal expansion display (single frequency). Then, the horizontal display is expanded at the center of training direction, bow direction.

Train center direction	Position after expansion	Remarks
318° –42°	Moves to screen bottom	For viewing forward
48° –123°	Moves to left side of screen	For viewing starboard side
138° –222°	Moves to screen top	For viewing aft
228° -312°	Moves to right side of screen	For viewing port side

You can switch between the single-frequency horizontal expansion display and the dual-frequency horizontal expansion display alternately with the ⓐ key as shown below.

Single-freq. Display   Dual-freq. Display
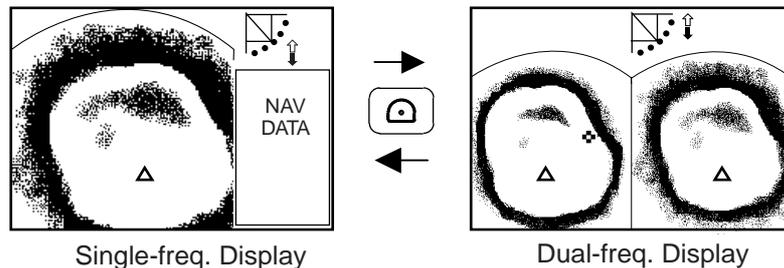
Switching between single-frequency horizontal expansion and dual-frequency horizontal expansion displays
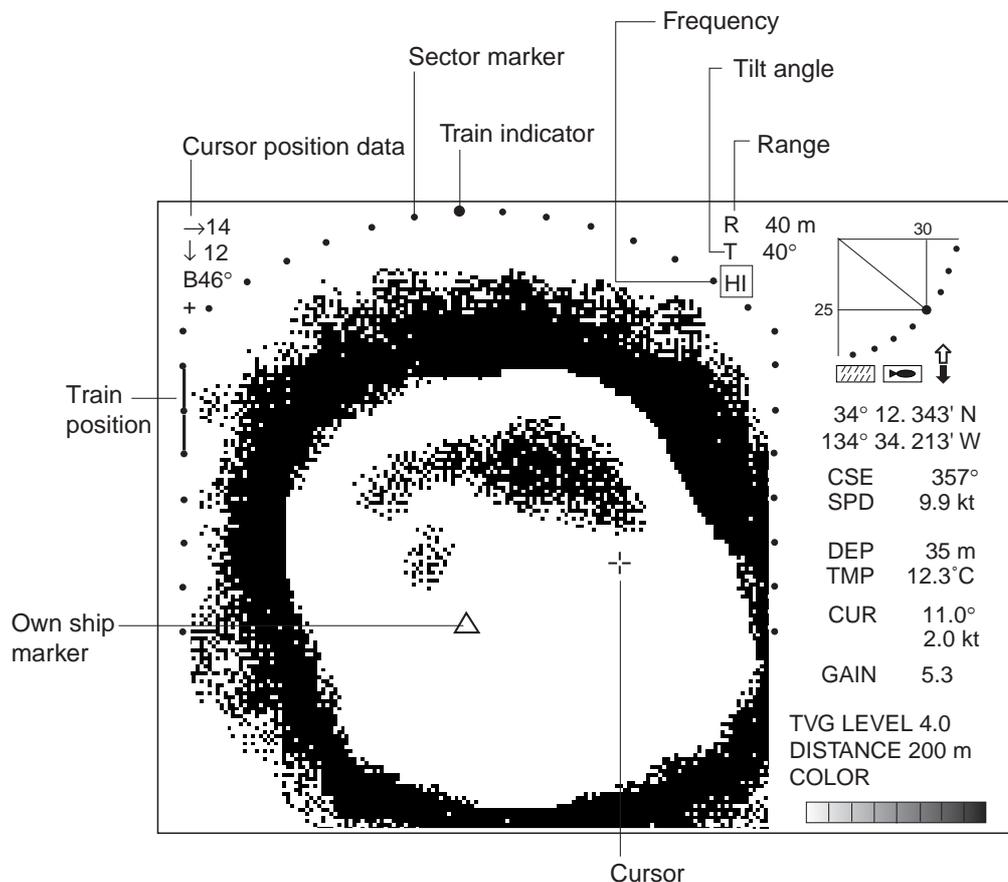
Horizontal expansion display

2.13 Target Lock

Two types of target lock modes are available.

Position: Tracks stationary position (such as a reef) using position data from a navigator. Available in the horizontal mode only.

Echo: Tracks fish echo either manually or automatically. Available in the horizontal mode only.

2.13.1 Choosing a target lock mode

1. Press the **MENU** key to open the menu.
2. Press▲ to choose MENU
3. Press ◄ or ► to choose the HORZ menu.
4. Press ▲ or ▼ to choose TARGET KEY.
5. Press ◄ or ► to show following dialog box.

```
┌─────────────────────────┐
│     TARGET KEY          │
├─────────────────────────┤
│               ┌──────┐  │
│  POS          │ ECHO │  │
│               └──────┘  │
└─────────────────────────┘
```

6. Press ◄ or ► to choose option desired.
7. Press the **MENU** key to register your selection and close the menu.

2.13.2 Position mode

This mode tracks a stationary position (such as a reef) using position data fed from a navigator.

Note 1: This function is inoperative in the echo sounder mode.

Note 2: This mode requires position data. When there is no position data the message "NO POSITION DATA." appears for four seconds and tracking is automatically cancelled. Check the navigator.

Note 3: The tilt angle must be less than 75 degrees to use this feature.

1. Use the Omnipad to choose the location to track.
2. Press the **TARGET** key.

   The message "POS LOCK" appears momentarily at the screen top, the target lock marker is displayed at the cursor position and the target lock indicator appears at the top right-hand corner of the screen while tracking (with position data from external equipment) is occurring. **SECTOR**, **TILT** and **FULL/HALF** controls are inoperative since their functions are inoperative during position mode target lock.

   The detection area is fixed at 48-degrees. Tilt angle and train are automatically adjusted to track the target even if your vessel is moving.

Target lock indicator
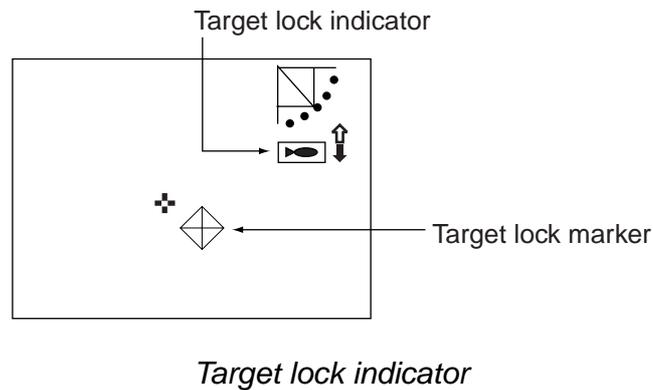
3. To turn off the target lock, press the **TARGET** key again. The message "LOCK END" momentarily appears, the target lock marker and the target lock indicator disappear and previously used sector, train and tilt settings are restored. Also, latitude and longitude indication returns to normal.

Note 1: Target lock is automatically canceled if position data is lost.

Note 2: When target lock is activated in the vertical scan combination display, the vertical bearing cursor automatically shows target direction. When target lock is canceled the vertical bearing cursor is returned to its previous position. The vertical scan display operates like the vertical search features when the target lock is active. For further details about the vertical search feature, see page 5-8.

2.13.3   Echo mode

The echo mode tracks a fish school either automatically or manually. The default setting is automatic, and you can choose automatic or manual with "LOCK MODE" in the HORZ menu. Note that this mode is not available in the vertical scan or echo sounder mode

Automatic tracking

The automatic echo target lock function automatically tracks a fish school appearing in the operator-chosen target lock zone. I

1. Press the **TARGET** key.

   The dialog box below appears at the screen center, the message "ECHO LOCK" appears for three seconds at the top of the screen, the target lock area appears in the current train area and the target lock indicator appears at the right-hand side of the screen.

   ```
   TARGET LOCK AREA.
        ◀ ▶    : INSIDE
        ▲ ▼    : OUTSIDE
   ```
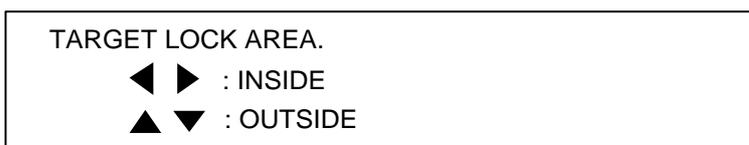
2. Use the Omnipad to set the detection area: ▲ of ▼ to set the outer boundary; ◀ or ▶ to set the inner boundary. Use the SECTOR and TRAIN controls to adjust the detection area. Do not include bottom echoes in the zone, so that target lock will not be activated by bottom echoes.
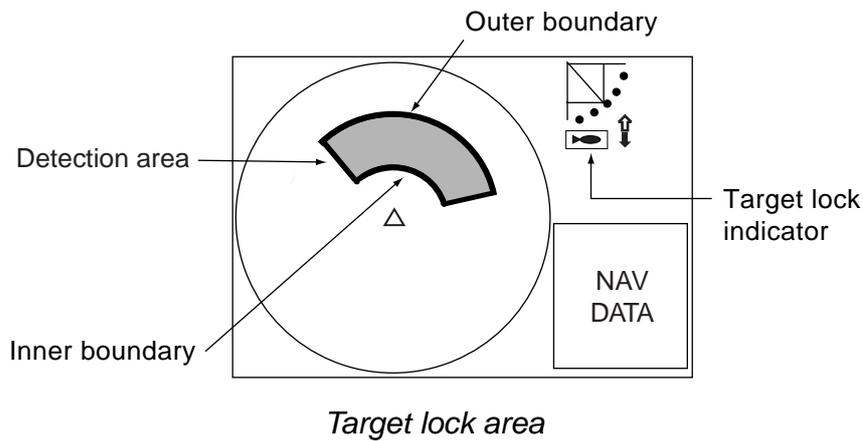
Target lock area

When a target of red or reddish-brown color is detected in the zone, the target lock indicator blinks, the buzzer sounds and the detection area disappears. When a tracked target is lost, the operation shown below is repeated.

Tilt changed to search [(A + 10°) → (A - 10°) →A]

Detection area displayed once again and target lock indicator lights.

A: Tilt angle at start of target lock
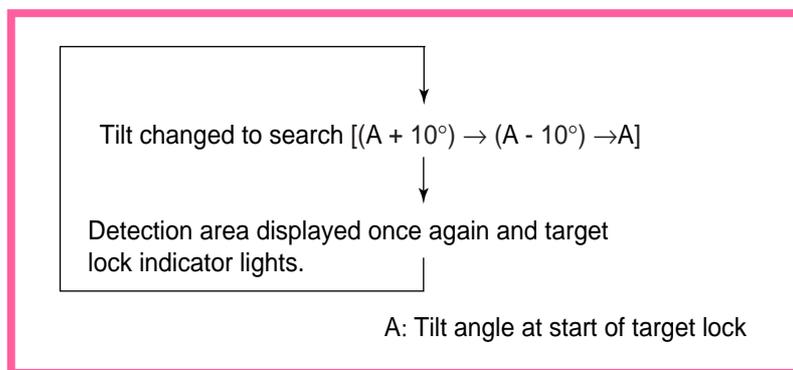
3. If the target does not appear even though the tilt angle is changed, adjust the **SECTOR** and **TRAIN** controls to change the detection area.
4. To turn off the target lock, press the **TARGET** key again. The message "LOCK END" appears for three seconds at the screen top, the target lock indicator disappears and operation continues with current train and tilt settings.

Manual tracking

1. Set LOCK MODE to MANUAL on the HORZ menu.
2. Press the **TARGET** key when a wanted target echo appears.

The message "ECHO LOCK" appears along with the target lock indicator. Then, the transducer train direction is reversed and searching starts with the current tilt angle. When a target echo appears the transducer train direction is again reversed automatically, the buzzer sounds and the target lock indicator blinks.

If the fish echo is lost the tilt angle is automatically changed to continue tracking as shown right.

1. Tilt angle is changed by +10° (A+10°). (A is the tilt angle used when tracking began.)

2. Tilt angle is changed by -10° (A-10°).

3. If the echo could not be found, tracking is cancelled and tilt angle A is restored.

4. To quit the target lock, press the **TARGET** key again. The message "LOCK END" appears momentarily.

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2.14   Horizontal Menu Overview

This section presents an overview of the items on the HORZ menu.

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ or ► to choose the HORZ menu.

```
┌──────────────────────────────────────────────────────────┐
│  MENU        COM1   COM2  HORZ  VERT  ES  PRESET    SYS    │
│ ┌────────────────────────────────────────────────┐        │
│ │  TVG LEVEL          4.0                          │        │
│ │  TVG DISTANCE       4.0                          │        │
│ │  RES. COLOR         LOG                          │        │
│ │  CLUTTER            0                            │        │
│ │  TARGET KEY         ECHO                         │        │
│ │  LOCK MODE          AUTO                         │        │
│ │  AUTO TILT          OFF                          │        │
│ │                                                 │        │
│ │                                                 │        │
│ └────────────────────────────────────────────────┘        │
│  ─────────────────────────────────────────────────────    │
│  ▲▼ : SELECT ◄ ► : CHANGE    MENU: END                    │
└──────────────────────────────────────────────────────────┘
```

HORZ menu

3. Press ▲ or ▼ to choose item desired.
4. Press ► to show corresponding dialog box.
5. Press ◄ or ► to choose option desired.
8. Press the **MENU** key to register your selection and close the menu.

2.14.1   Horizontal menu description

TVG LEVEL: Compensates for propagation loss of sound in water. Default setting is 4.0. For further details, see paragraph 2.12.3.

TVG DISTANCE: As above. Default setting is 4.0.

RES. COLOR: Sets transfer characteristics of input signal level versus display echo level. Echo strength is emphasized in order of CUBE, SQUARE, LINEAR, LOG, and you can observe the characteristics of each by watching the color bar as you change the setting.

LOG: Displays weak to strong echoes in their respective levels. This is the default setting,
           and is suitable for general use.
LINEAR: Downplays the weak echoes when compared with LOG. Effective for suppressing weak echoes such as plankton.
SQUARE: Strong echoes are emphasized more than in LINEAR.
CUBE: Strong echoes are emphasized even more than in SQUARE.

CLUTTER: Low intensity echoes, often caused by sediments in water, are painted on the screen as a large number or random dots. This noise can be suppressed. The higher the number (setting) the weaker the echoes which are erased.

TARGET KEY: Chooses target lock function between position and echo. Default setting is ECHO. For further details see paragraph 2.13.

LOCK MODE: Chooses how to track fish echo in "echo" target lock; automatically or manually. Default setting is AUTO. For further details see paragraph 2.13.

AUTO TILT: Turns automatic tilt on or off, and the default setting is OFF. The choices are $\pm2°$, $\pm4°$, $\pm6°$, and $\pm10°$. Automatic tilt adjusts the tilt angle in the following sequence:
B → (B-A) → B → (B+A) → B → (B-A) → B → (B+A)…
B: Current tilt angle
A: Auto tilt setting

For example, the tilt angle is 30° and the automatic tilt setting is 4°. Then, the tilt angle is changed in the following sequence: 30° → 26° → 30° → 34° → 30° → 26° → 30° → 34°…

Note: The **TILT** control is inoperative when automatic tilt is active.

2.15 Interpreting the Horizontal Display

This section provides information necessary for interpreting the horizontal display.

2.15.1 How the horizontal mode picture is painted

The wide sounding beam is emitted from the soundome at a certain tilt angle (see hatched area in the figure below). The information (target echoes) obtained by this beam is displayed in sectors of increments of 12° of the screen. Thus, all directions around the boat are sounded in 30 times of transmissions.

Note: When the "FAST SCAN" is switched off, the equipment operates in a narrow sounding beam. Then, the echoes appear on a 6° sector in each transmission, so 60 transmissions are required to complete the full 360° picture (6°x 60=360°). This means that training speed is slower. However, since transmission power is concentrated into the narrow sounding beam, a superior detection range is obtained. Furthermore, since the bottom contour is painted distinctly, bottom fish may be more easily detected.

Sounding Beam	Screen Display
Tilt: θ Sounding Beam 1 2 3 4 When the narrow sounding beam (6°) is selected 60 transmissions are required to complete the full circle.	Train: 6°* Tilt: θ *12° When high speed training is selected.
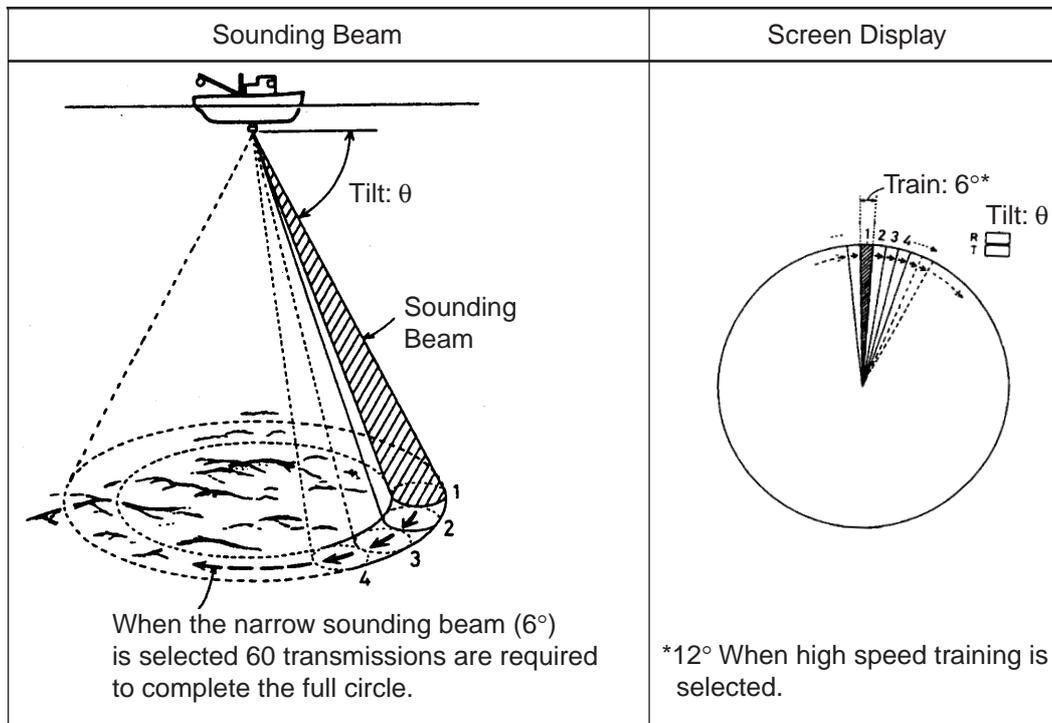
How the horizontal mode picture is painted

2.15.2   Sample displays

This section provides various examples of horizontal mode displays. The appearance of actual fish echoes will vary according to factors such as transmission frequency, gain and TVG settings, and bottom composition and contour.

Bottom echoes

When the tilt angle is changed, the bottom echo illustrated below will appear on the display. When the tilt is decrease (toward 0°), the bottom trace becomes winder and weaker. By observing the bottom condition on the display, the skipper can prevent net damage.

(A) Flat bottom
    Tilt angle: 10° to 15°
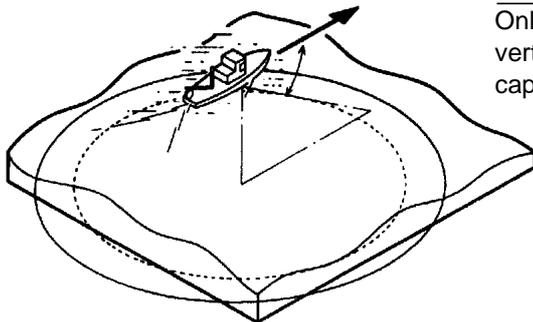
Decreased tilt angle
Only half of
vertical beam width
captures the bottom.
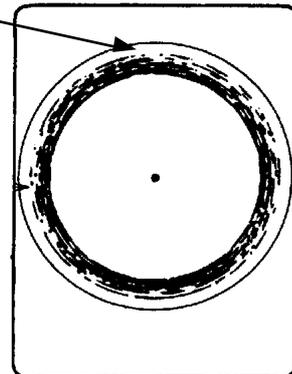
(B) Flat bottom
    Tilt angle: 20° or more
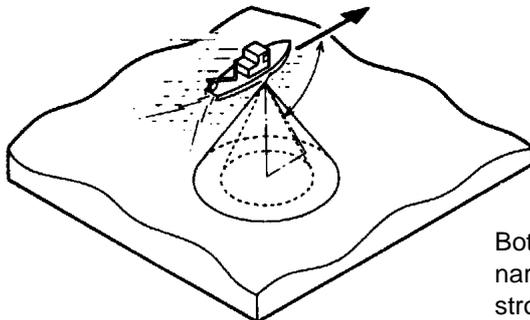
Bottom is displayed
narrower and in
stronger colors when
compared to (A).
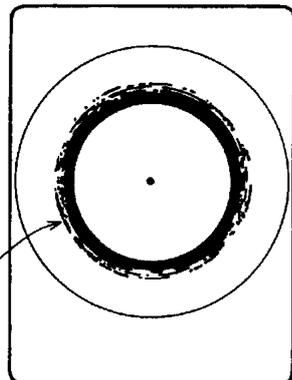
(C) Sloping bottom
    Tilt angle: 20° or more
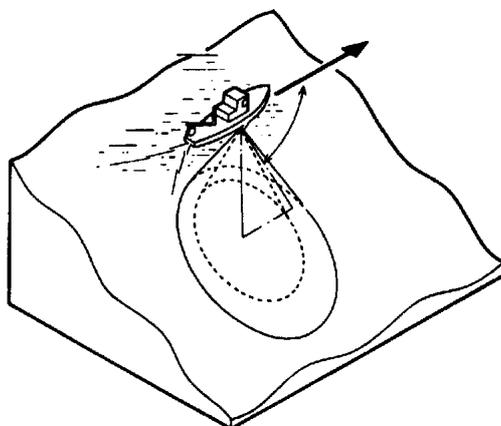
Shallow bottom
is displayed in
a strong color
and with a
short tail.

Bottom
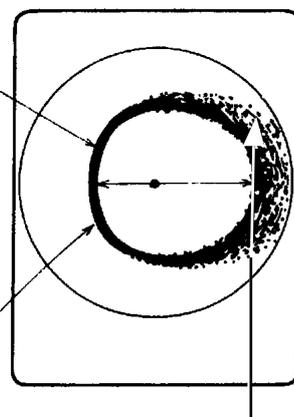
The deeper, sloping
 bottom echo is displayed
in a weak color and
with a long tail.

Bottom echoes

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Fish schools

A fish school appears as a mass of echoes on the screen. The color of the mass shows the density of fish schools on the sonar beam. To find distribution and center point of a fish school, try several different tilt angles.

(A) Sea surface fish
   Tilt angle: 0° to 10°

Fish school

Sea surface reflections

Bottom echo not displayed because of decreased tilt angle. Sea surface reflections are present.
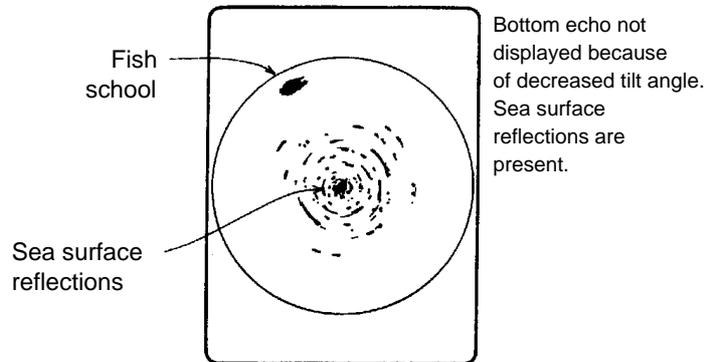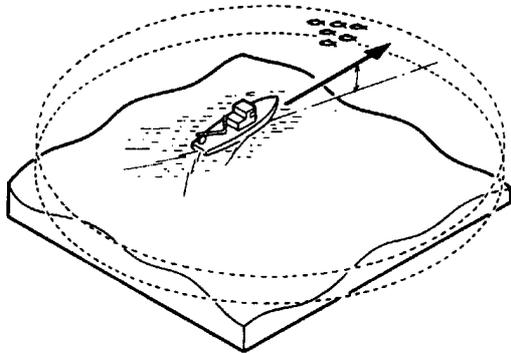
(B) Midwater, bottom fish   Tilt angle: 30° or more
   Fish echo which appears before bottom can be detected.

Bottom

Fish school

Large midwater fish school is present.
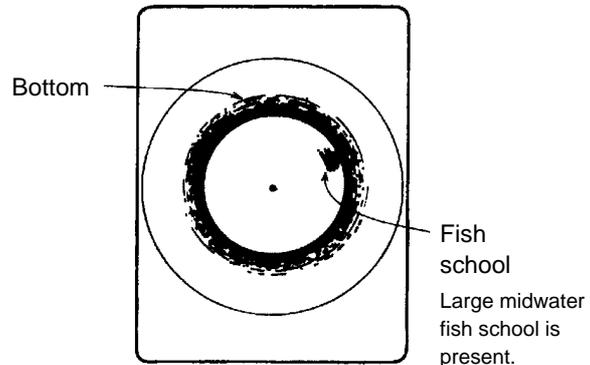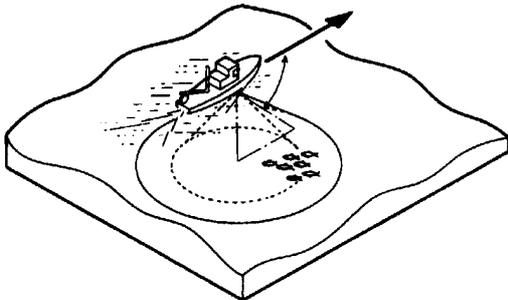
Tilt angle: 0° to 20°
Fish echo which appears together with or after bottom can be detected.
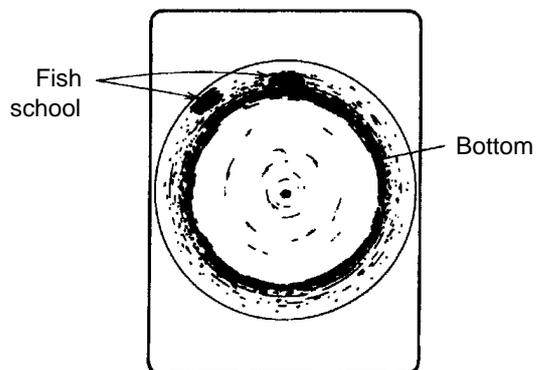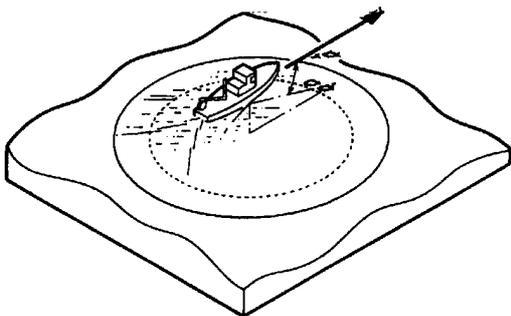
Fish school

Bottom

When the tilt angle is shallow, the reflection echo from bottom is weak and the fish echo which appears from bottom is easy to find.

Fish schools

Sea surface reflections

To reduce sea surface reflections, set the tilt angle to 5° or higher, so the upper edge of the sonar beam does not hit the sea surface, or adjust TVG. When a decreased tilt angle is used, sea surface reflections cover a large area as illustrated below.
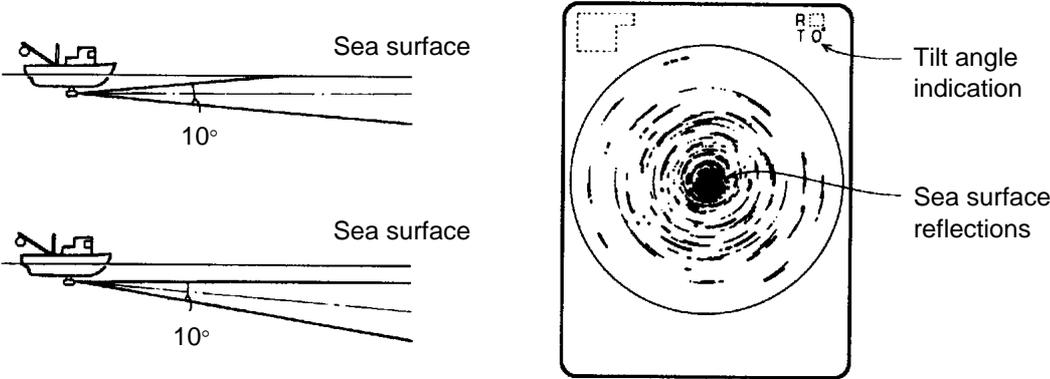
Sea surface reflections

Wake

A wake produced by own ship or another ship can be a strong reflecting object when a decreased tilt angle is used. As the wake appears as a thick continuous line, it can be easily distinguishes from a fish school. A wake contains many air bubbles which attenuate ultrasonic energy, making it difficult to sound beyond the wake.

Wake

2-27
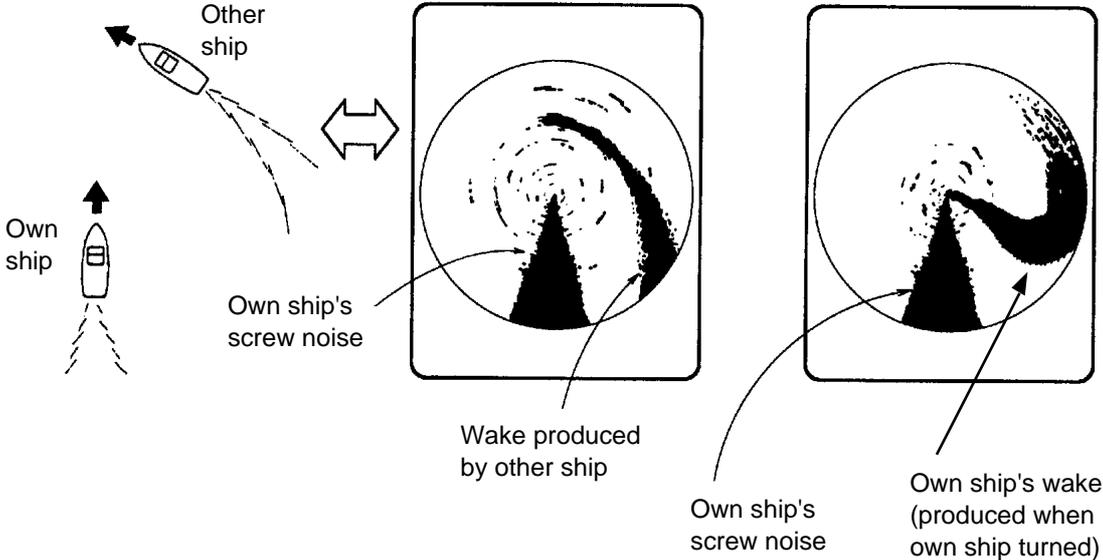
Sidelobe echo (false echo)

An ultrasonic wave is emitted only in the direction set by the **TILT** control, however there are some emissions outside the main beam. These are called sidelobes. The energy of the sidelobe is fairly weak but when the water is comparatively shallow and the bottom is rocky and hard, strong signals are detected by the sidelobe. These are represented on the display as a false echo as shown below.

Mainlobe echo

Sidelobe echo

The bottom echo detected by sidelobe appears at a certain tilt angle when the sidelobe points vertically. Also, poor soundome projection may result in a similar false echo.
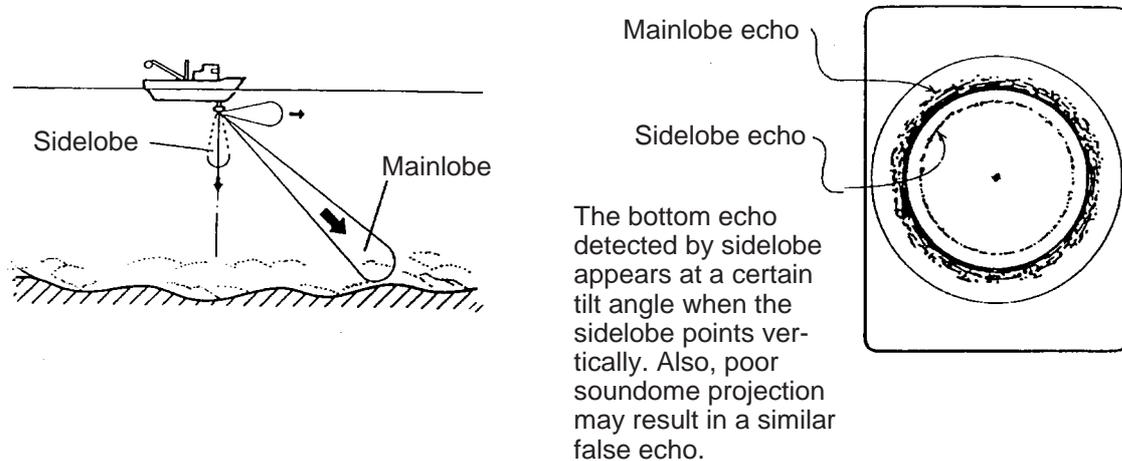
Sidelobe echoes

Noise

When the fishing ground is crowded with many fishing boats, the sonar is subject to interference from ultrasonic equipment (echo sounder or sonar) on other boats as well as those on own ship.

For instance, interference from the sonar operated on other boats will show itself on the display as in the figure below. This interference can be suppressed by changing the Tx rate on the COM1 menu.
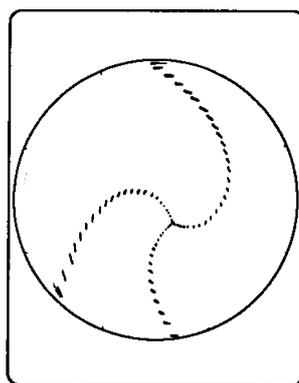
Interference from sonars

2.15.3   Combination display examples

How to choose a combination display

1. Press the ⊙⊡ key to show the combination display selection window.

▲   HORZ/HISTORY

HORZ/VERT

HORZ/VERT ZOOM

▼   HORZ/PLOTTER

2. Use ▲ or ▼ to choose the combination display desired. You may also use the ⊙⊡ key to choose a display.
3. Press the **MENU** key to close the selection window, or wait four seconds for it to close automatically.

Note 1: Combination displays may be disabled on the SYSTEM SETTING 2 menu. Only those displays which are turned on appear in the combination display selection window.

Note 2: If all combination displays are turned off the vertical scan combination display is automatically shown.

Horizontal/history display

The horizontal display appears in the main window; the history display in the sub window. The length of the picture displayed in the history display is equal to about four full circle pictures. Thus the history display enables you to observe the history of fish movement and distribution. It is also useful for detecting bottom fish, reefs and sunken vessels.

The history display cannot be adjusted.
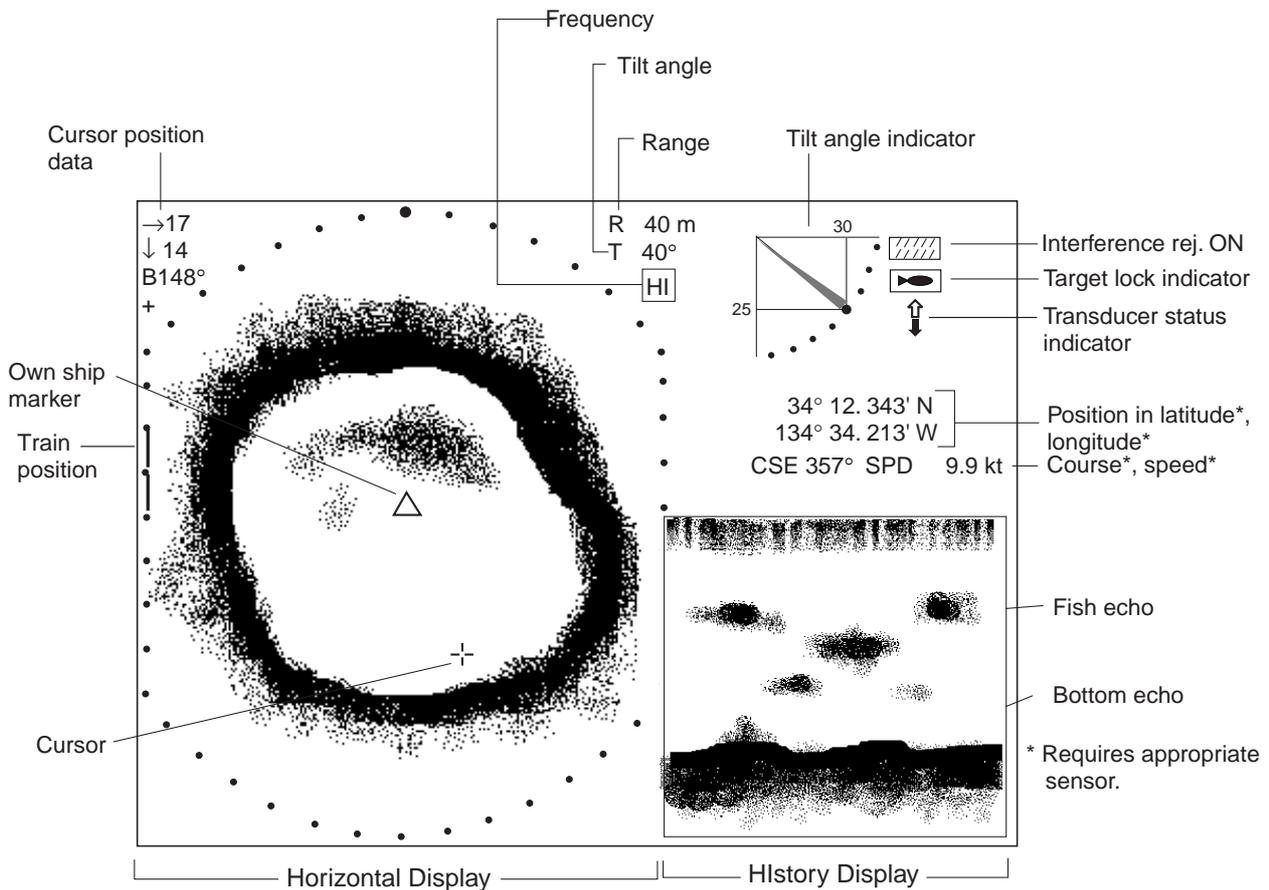
Horizontal/history display

Horizontal/video plotter display

The horizontal display appears in the main window; the video plotter display, which traces ship's track on the display, in the sub window. Compared to the horizontal display the video plotter's range is much longer. For example, an event marker entered on the horizontal display disappears from that display when it goes out of the current range. However, when entered on the video plotter display it remains on the video plotter display for a much longer time when a long range scale is used. This can be useful when you want to return to the location denoted with an event marker. Like with the horizontal display you can inscribed five event markers on the video plotter display.

To display track on the horizontal display, the tilt angle must be less than 75 degrees.

You may switch control between the horizontal display and the video plotter display with the **MAIN/SUB** key. The message MAIN WINDOW CONTROLLABLE or SUB WINDOW CONTROLLABLE appears with each pressing of the key. A red rectangle circumscribes the sub window when it is chosen. With the video plotter display selected you may change its range with the **RANGE** control.

Note: Controls other than RANGE may only be operated from the main window. When you attempt to operate them when the sub window is chosen the message SELECT MAIN WINDOW appears.
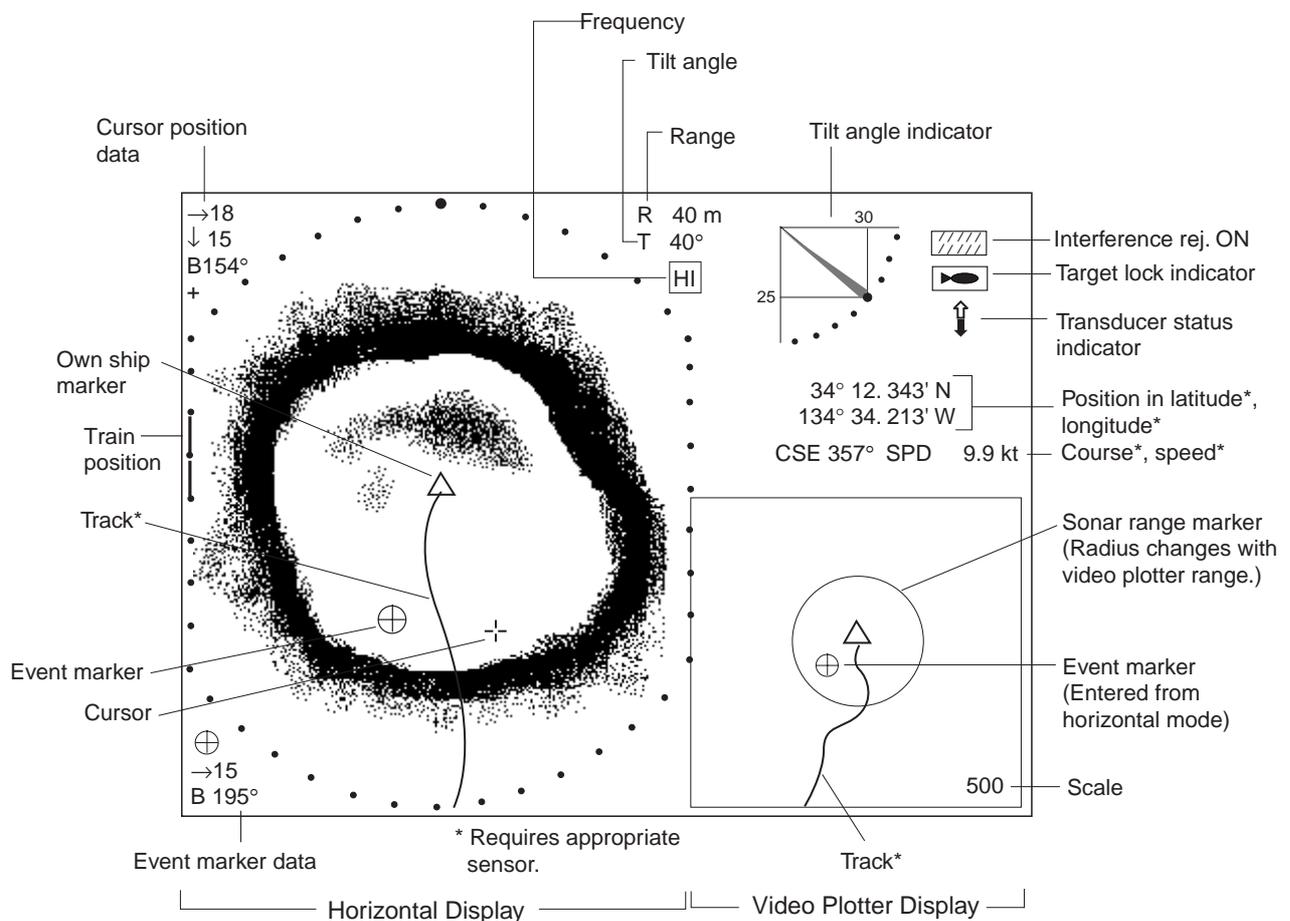
Horizontal/Video Plotter display

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3. VERTICAL SCAN MODE

3.1 Operational Overview

The figure below shows the typical vertical scan mode operating sequence.

6. Set train bearing.

8. Set tilt angle.

7(a). Set scanning sector.

5. Set range.

1. Turn on the power.

11. Adjust menu settings (ex. TVG) as required.

9. Adjust gain.

2. Lower the transducer.

4. Select appropriate vertical scan mode.

3. Adjust screen brilliance.

10. Measure range and bearing to target with cursor.

7(b). Select training sector 180°.
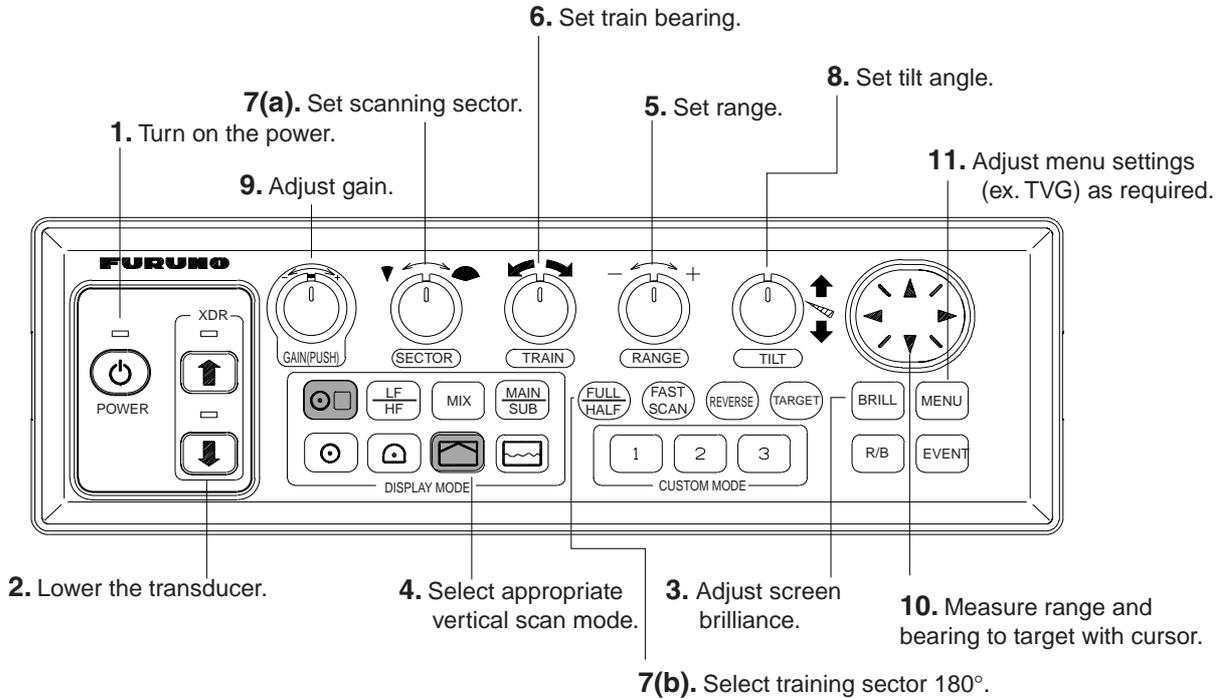
Control panel

3.2 Typical Vertical Scan Mode Display

Press the ▭ key to show the vertical scan display. You can switch between the single-frequency vertical scan display and the dual-frequency vertical scan display alternately with the ▭ key as shown below.

Single-freq. Display   Dual-freq. Display
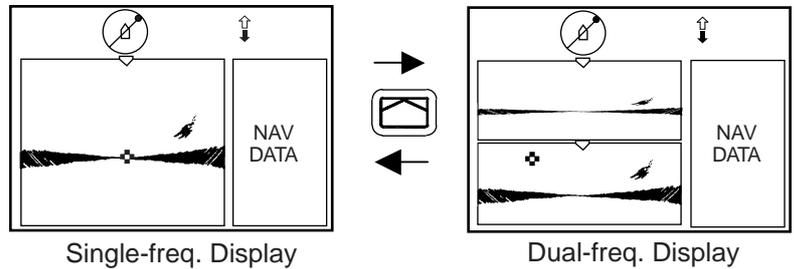
Switching between single-frequency vertical scan and dual-frequency vertical scan displays
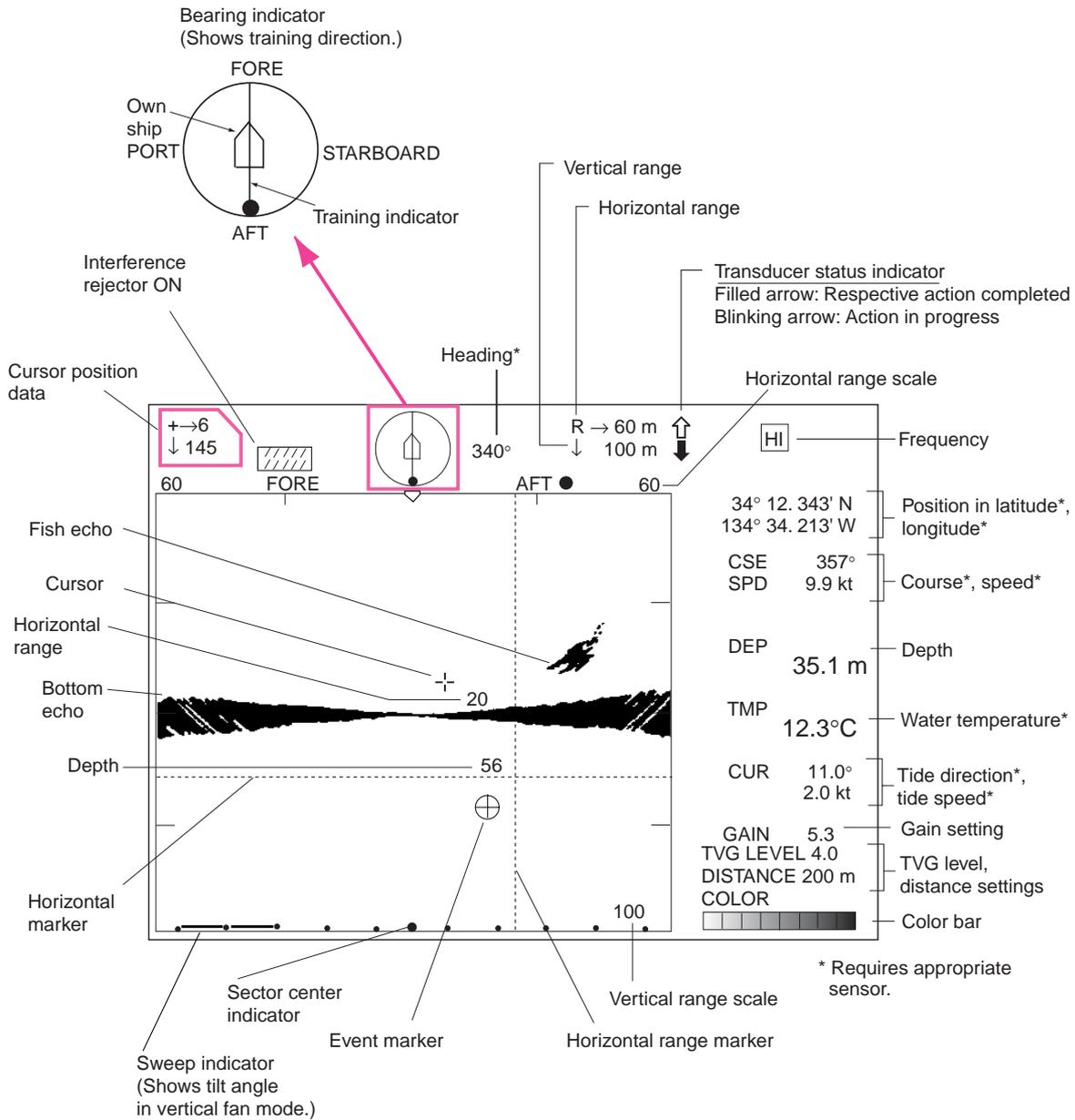
Single-frequency vertical scan display

3.3   Choosing a Range

The **RANGE** control chooses the detection (display) range, in 15 settings. Choose the range according to either the fish species being searched or the depth desired. Each time the control is operated the newly chosen range briefly appears in large characters at the screen top. Range is permanently displayed at the top right-hand corner of the screen. Normally the range is set so that the bottom is traced at the lower part of the screen (like an echo sounder).
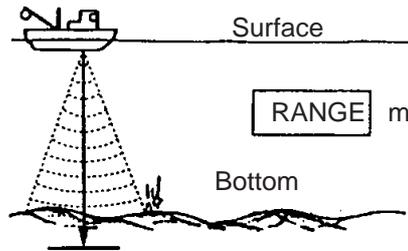
Range concept

Default vertical scan mode range settings

Unit	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Meters	10	20	30	40	60	80	100	120	160	200	250	300	400	500	600
Feet	30	60	90	120	150	200	250	300	400	500	600	800	1000	1500	2000

Note 1: Unit of range measurement may be chosen from among meters, feet, fathoms, passi/braza or Hiro (Japanese) with UNIT on the SYSTEM SETTING 1 menu. For details see page 5-11.

Note 2: Ranges may be freely preset as desired. For details see page 5-15.

3.4   Choosing Train Center

The **TRAIN** control determines the bearing of the vertical scan beam, from 0° to 180°. Bearing of beam position can be found with the train indicator.

0° (360°) → 6° → 12° → 18° → ... 180°
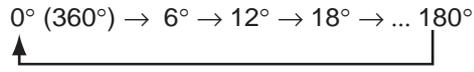
Train indicator
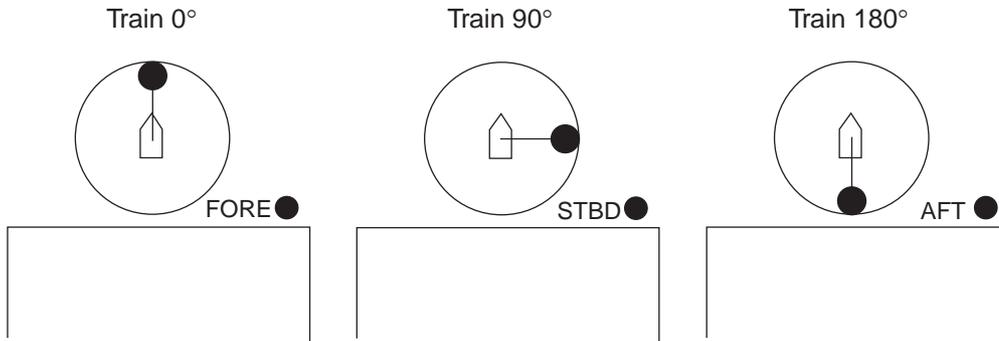
Train indicator and display

3.5   Choosing Display Sector

Sector means the width of the transducer training, from 6° to 180°.
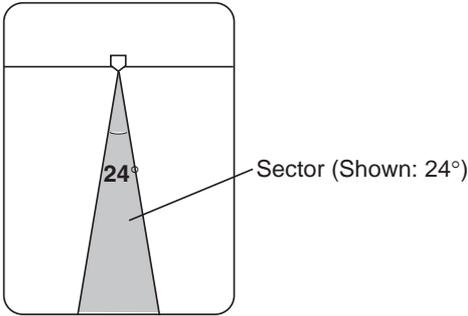
Sector

The **SECTOR** control chooses the training area among the sixteen positions shown in the table below. Clockwise rotation of the control increases the sector width; counterclockwise rotation decreases it.

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Sector width (°)	6	12	24	36	48	60	72	84	96	108	120	132	144	156	168	180

One-touch selection of 180° sector

1. Press the **FULL/HALF** key. A half-circle display of 180° is presented.
2. Press the **FULL/HALF** key again, and a 120°-sector display is presented.

Note: Operating the **SECTOR** control between steps 1 and 2 in the procedure above displays the 180° sector at the next pressing of the **FULL/HALF** key.
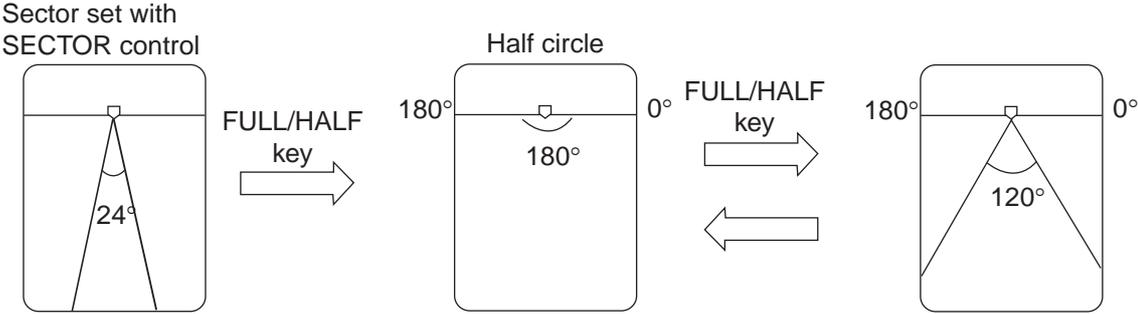
How the FULL/HALF key works

3.6   Choosing Sector Center

The center direction of the sounding beam in the vertical direction can be changed with the **TILT** control. The setting range is 0° to 180° in increments of 6°. Choose the setting which places the sector center in the middle of the detection range.
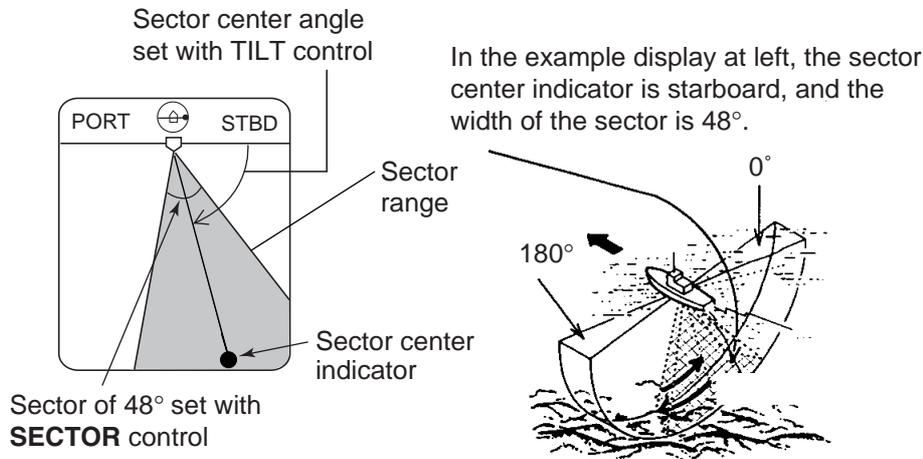
Sector center

Automatic shifting of own ship position

Own ship position on the screen is automatically shifted either rightward or leftward according to the direction of the sector center and display sector width.
The figure below shows the own ship position has been shifted rightward on the screen to provide the wider view at the port side.

Sector center 0° to 60°:   Own ship position shifted to port side
Sector center 66° to 114°:   Own ship position shifted to center
Sector center 120° to 180°:   Own ship position shifted starboard
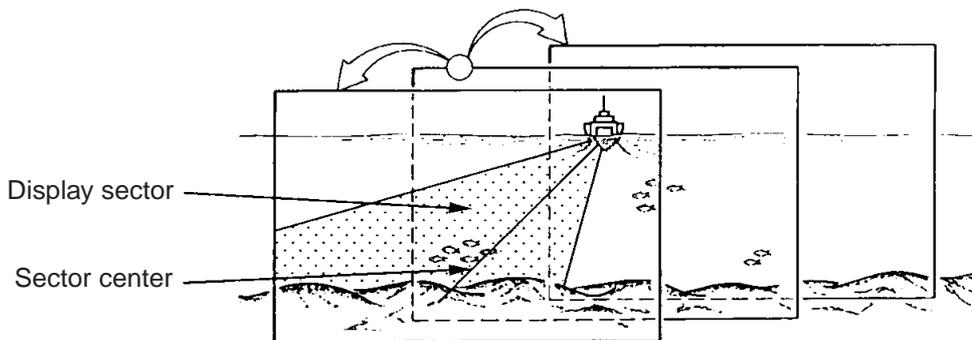
How automatic shifting works

3.7   Choosing Training Speed

The training speed chooses how fast the transducer scans the display sector. Two choices are available, 3° (normal speed, default setting) and 6° (high speed), and one may be selected with the **FAST SCAN** key. Each time the key is pressed the display momentarily shows "NORM" (normal speed) or "FAST" (high speed).

Normal: 60 transmissions for half circle in increments of 3°.
High: 30 transmissions for half circle in increments of 6°.

3.8   Finding Echo Position with the Cursor

The cursor measures horizontal range and depth. Operate the Omnipad to place the cursor where desired. Cursor data appears at the top left-hand corner on the screen.
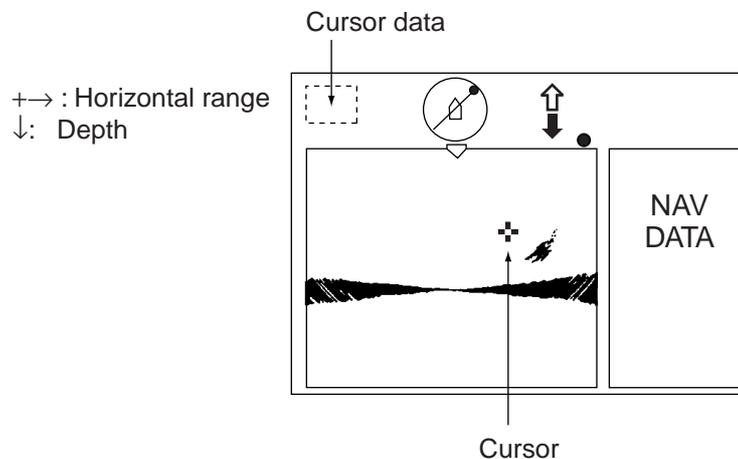
Location of cursor position data

3.9   Changing Training Direction

The training direction may be reversed to reconfirm fish echoes. Press the **REVERSE** key to reverse training direction between counterclockwise and clockwise alternately. "REVERSE" appears at the top of the screen for three seconds when training direction is reversed.

3.10 Event Marker

The event marker functions to mark important locations on the vertical scan display, and five event markers may be inscribed. Each time the **EVENT** key is pressed the "latest event marker" (⊕) is inscribed at the cursor location and all previously entered event markers are shown by the "previous event marker" (+). When the capacity for event markers is reached the eldest event marker is erased from the screen to make room for the latest. Note that the marker cannot be inscribed from the vertical scan display in the horizontal/vertical scan display.

1. Operate the Omnipad to place the cursor on the location desired for an event marker.
2. Press the **EVENT** key to inscribe the event marker. The event marker is inscribed on the vertical scan display, as well as the horizontal and video plotter displays.
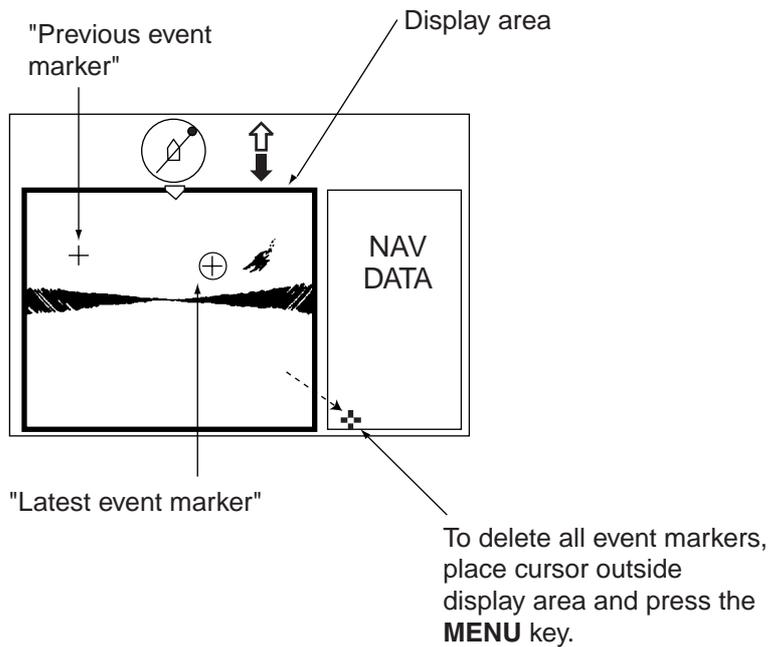
How to inscribe, delete the event markers

3.10.1 Deleting all event markers from the vertical scan display

All event markers inscribed on the vertical scan display may be deleted as follows:

1. Operate the Omnipad to place the cursor outside the display area.
2. Press the **EVENT** key to show the following dialog box. Do the next step within four seconds, otherwise the dialog box will be erased.

```
┌─────────────────────────────┐
│  DELETE EVENT MARK?         │
│                             │
│   [NO]     YES              │
└─────────────────────────────┘
```
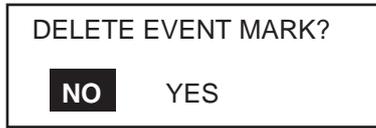
3. Press ► to choose YES and press the **MENU** key.

3.11 Depth and Horizontal Range Markers

The depth and horizontal range markers function to measure the horizontal range and depth to a desired echo.

Note: Depth and horizontal range markers cannot be inscribed from the vertical scan display when it is in the sub window (Horizontal/vertical scan display). Inscribe the markers from the horizontal display to show it in the vertical scan display.

1. Operate the Omnipad to place the cursor on the location desired.
2. Press the **R/B** key to display the depth and horizontal range markers. Horizontal range and depth appear on the screen.
3. To erase the depth and horizontal range markers, press the **R/B** key again, or place the cursor on the depth or horizontal range marker and press the **R/B** key.
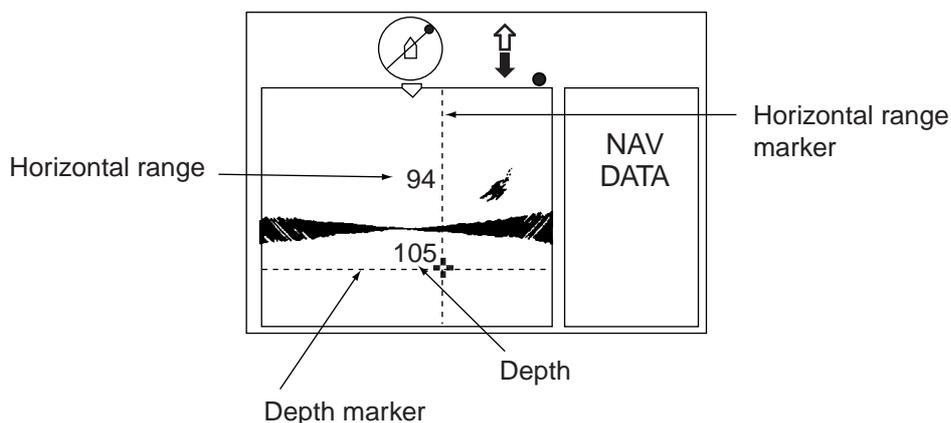
Depth and horizontal range markers

3.12 Adjusting the Picture

3.12.1 Displaying weak echoes clearly

Echoes from targets (such as the bottom or a fish) return to the transducer in order of the distance to them, and when their intensities are compared at the transducer face, those from nearer targets are generally stronger when their reflecting properties are nearly equal. The sonar operator will be quite inconvenienced if these echoes are directly displayed on the screen, since he won't be able to judge the actual size of the target from the size of echoes displayed on the screen. To overcome this inconvenience, use the TVG function. It compensates for propagation loss of sound in water: amplification of echoes on short range is suppressed and gradually increased as range increases, so that similar targets are displayed in similar intensities irrespective of the ranges to them.
The TVG also functions to suppress unwanted echoes and noise which appears in a certain range area on the screen.

To adjust TVG:

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ or ► to choose the VERT menu.

```
MENU          COM1   COM2   HORZ  VERT   ES   PRESET    SYS

  TVG LEVEL          4.0
  TVG DISTANCE       4.0
  RES. COLOR         LOG
  CLUTTER            0
  HORZ SCAN RATE     1
  VERT SCAN RATE     1
  HORZ RANGE         x1



  ▲▼ : SELECT ◄ ► : CHANGE    MENU: END
```

VERT menu

3. Press ▲ or ▼ to choose TVG DISTANCE and then press ► to show the following dialog box.

```
  TVG DISTANCE      4.0

Hi

Lo
        200
```
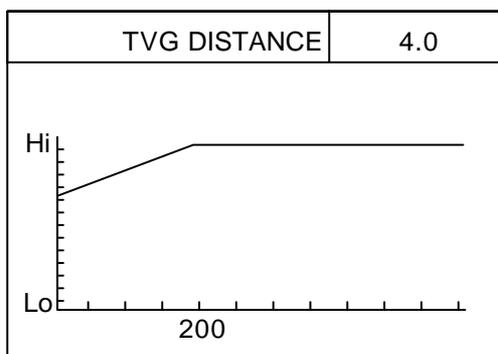
4. Press ◄ or ► to adjust TVG distance, considering sea conditions. The larger the figure the greater the distance at which the TVG works.

TVG Distance Setting	0	0.5	1.0	1.5	2.0	2.5	3.0	3.5	4.0	4.5	5.0	….	10.0
Meters	3	8	20	40	60	100	130	160	200	250	320	….	1000
Feet	10	30	70	130	210	330	410	520	660	820	1040		3280
Passi/braza	2	5	10	20	40	60	80	100	120	150	180		600
Hiro	2	5	10	20	40	60	80	100	130	170	210	….	660

5. Press   or   to close the dialog box and return to the VERT menu.
6. To suppress reflections by the sea surface or plankton, choose TVG LEVEL and press ►.
7. Press ◄ or ► to adjust TVG LEVEL, considering sea conditions. The larger the figure the less the gain over distance.
8. Press the **MENU** key to register your selection and close the menu.
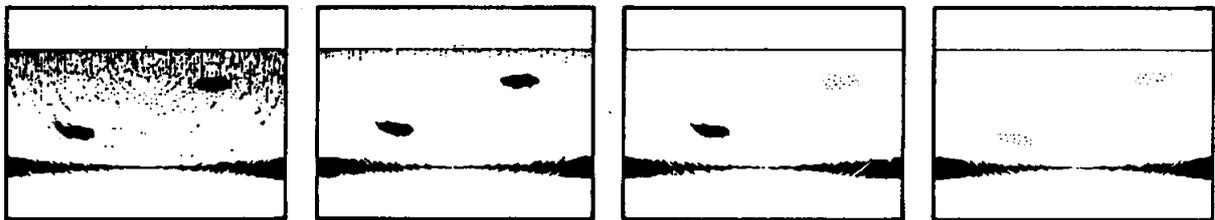
Wrong   Correct   Level too high   Distance too high

Examples of proper and improper TVG

3.12.2 Suppressing noise and interference

You may encounter occasional noise or intermittent interference as shown below. This is mostly caused by electrical equipment, engine, propeller noise from own ship, or noise from other sonars being operated nearby. If interference appears, turn on the interference rejector in the COM1 menu to suppress it. Note that the interference rejector cannot be turned on/off independently for each frequency in case of the dual-frequency display.

Interference rejector ON

Interference (In this display, interference shows itself every 6°.)
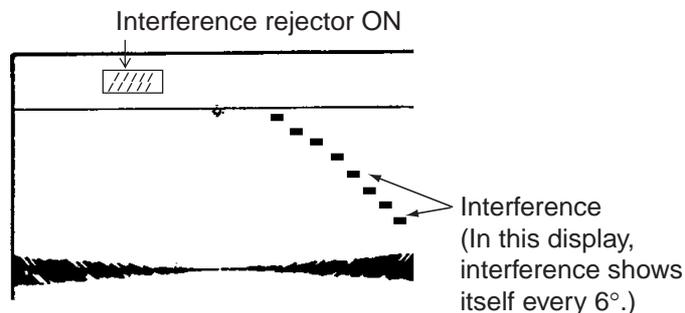
Appearance of interference

3.13   Vertical Menu Overview

This section presents an overview of the items on the VERT menu.
1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ or ► to choose the VERT menu.

```
┌──────────────────────────────────────────────────────────┐
│ MENU          COM1   COM2   HORZ  VERT   ES  PRESET   SYS  │
│  ┌────────────────────────────────────────────────────┐   │
│  │ TVG LEVEL          4.0                              │   │
│  │ TVG DISTANCE       4.0                              │   │
│  │ RES. COLOR         LOG                              │   │
│  │ CLUTTER            0                                │   │
│  │ HORZ SCAN RATE     1                                │   │
│  │ VERT SCAN RATE     1                                │   │
│  │ HORZ RANGE         x1                               │   │
│  │                                                    │   │
│  │                                                    │   │
│  └────────────────────────────────────────────────────┘   │
│  ▲▼ : SELECT ◄ ► : CHANGE    MENU: END                     │
└──────────────────────────────────────────────────────────┘
```

VERT menu

3. Press ▲ or ▼ to choose item desired.
4. Press ► to show corresponding dialog box.
5. Press ◄ or ► or to choose option desired.
6. Press the **MENU** key to register your selection and close the menu.

3.13.1   Vertical menu description

TVG LEVEL: Compensates for propagation loss of sound in water. The default setting is 4.0.

TVG DISTANCE: As above. Default setting is 4.0.

RES. COLOR: Sets transfer characteristics of input signal level versus display echo level. Echo strength is emphasized in order of CUBE, SQUARE, LINEAR, LOG. You can see the characteristics of each by watching the color bar as you change the setting. Default setting is LOG.

LOG: Displays weak to strong echoes in their respective levels. This setting is suitable for general use.

LINEAR: Downplays the weak echoes when compared with LOG. Effective for suppressing weak echoes such as plankton.

SQUARE: Strong echoes are emphasized more than in LINEAR.

CUBE: Strong echoes are emphasized even more than in SQUARE.

CLUTTER: Low intensity echoes, often caused by sediments in water, are painted on the screen as a large number of random dots. The higher the number (setting) the weaker the echoes which are erased.

HORZ SCAN RATE: Sets the scan rate (1, 2, 3, 4) for the horizontal display in the horizontal/vertical scan combination display. For example, if the scan for the horizontal display is "4" and the scan rate for the vertical scan display is "2", then for every four scans at the horizontal display two scans are produced at the vertical scan display. Raise the figure to give importance to the horizontal display.

VERT SCAN RATE: Sets the scan rate (1, 2, 3, 4) for the vertical scan display in the horizontal/vertical scan combination display. Raise the figure to give importance to the vertical display.

HORZ RANGE: You may choose the horizontal range expansion factor for the horizontal expansion display from x1 or x2. Note that this feature cannot be adjusted when the vertical search mode or target lock is active.

3.14   Interpreting the Vertical Scan Display

This section provides information necessary for interpreting the vertical scan display.

3.14.1   How the vertical scan mode picture is painted

The sounding beam is emitted and the information (target echoes) obtained by the beam appears in the corresponding sector as it appears on the sonar mode. The difference is that the training is performed only in vertical direction. It forms a sounding area of a half-circle (like a slice of watermelon) to observe a vertical section of underwater conditions.
The bearing of the vertical sounding beam can be chosen manually or automatically.

Sounding Beam	Screen Display
(1) Bearing of the sounding beam Freq: 60 kHz Bow 0° 180° θ Tilting direction (2) Sector center (3) Display area	(1) Bearing of the sounding beam 180° 0° Sector center 90°. Display range 24°. (2) Sector center, (3) Display area
Select the bearing of the sounding beam (1) by **TRAIN** control, the sounding sector center (2) by the **TILT** control and the display area (3) by the **SECTOR** control.	
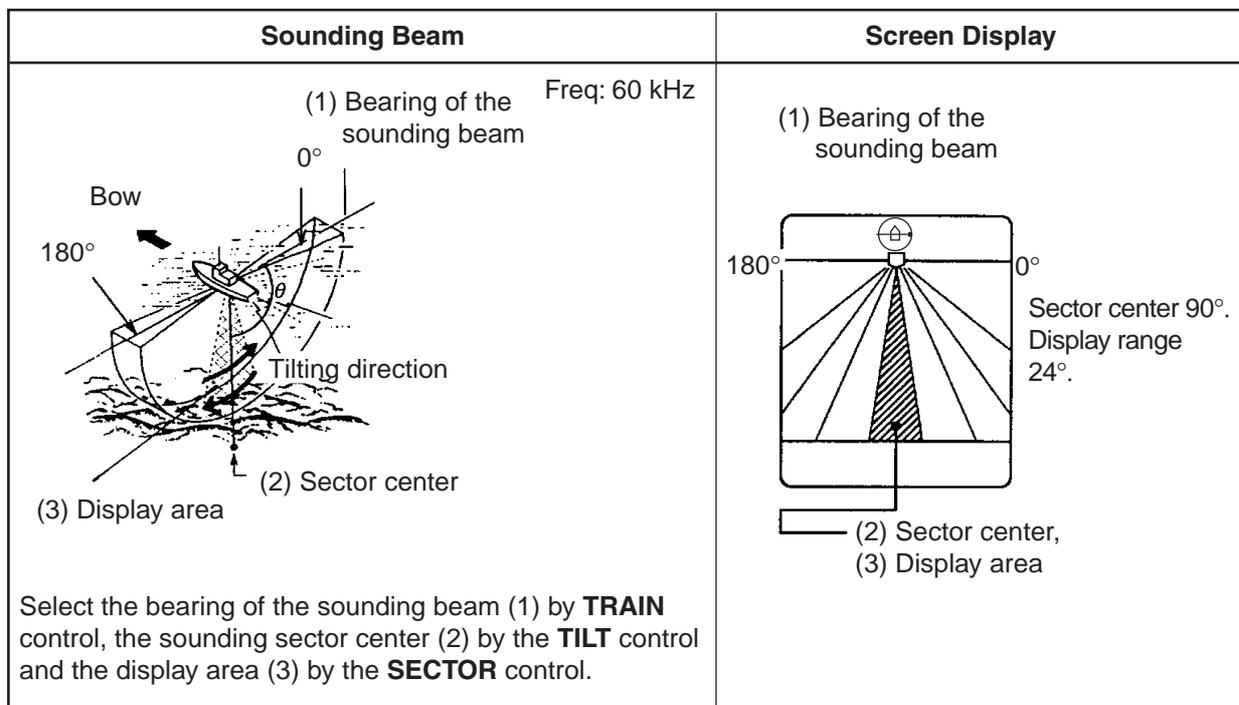
How the vertical scan mode picture is painted

3-13

3.14.2   Sample displays

Port-starboard picture (bottom)

You can see fish echoes at the center-right of the screen. The bottom is displayed wider as the distance from the ship's position increases. Therefore, it may be difficult to discriminate bottom fish.
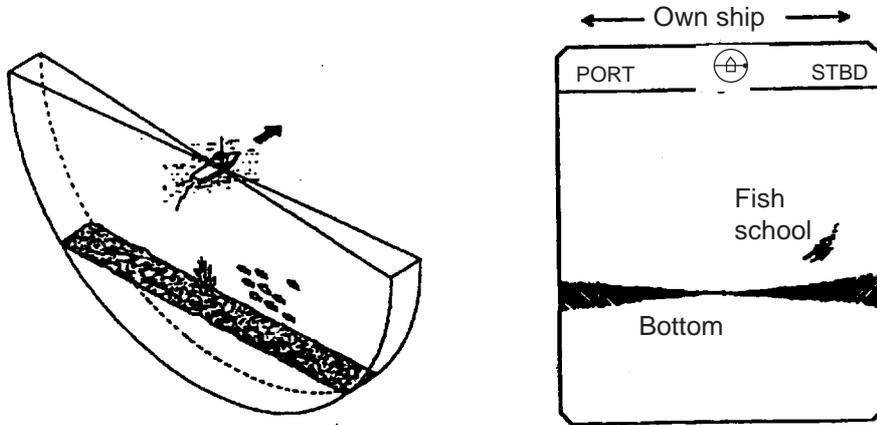
Port-starboard picture

When ship passes over fish schools

The sounding beam is directed fore-aft and the display is off-centered* to present a wider view of the area forward of the ship. You can clearly see fish schools approaching from the bow of the ship.
*: Automatically shifted.
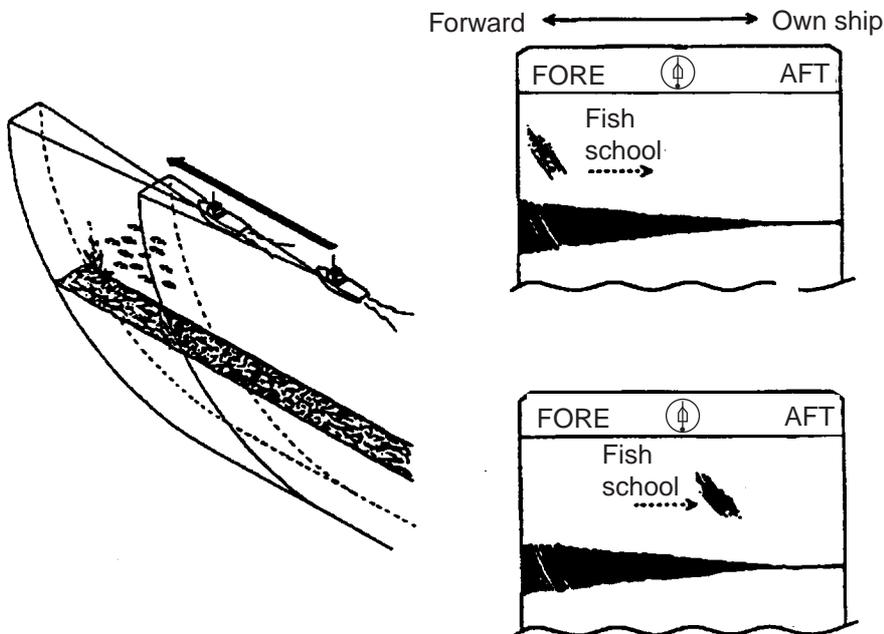
Picture appearance when passing over fish schools

Display of net hauling

This is an example of net hauling display. The location of the net is indicated clearly.

Own ship ──────────→ Aft
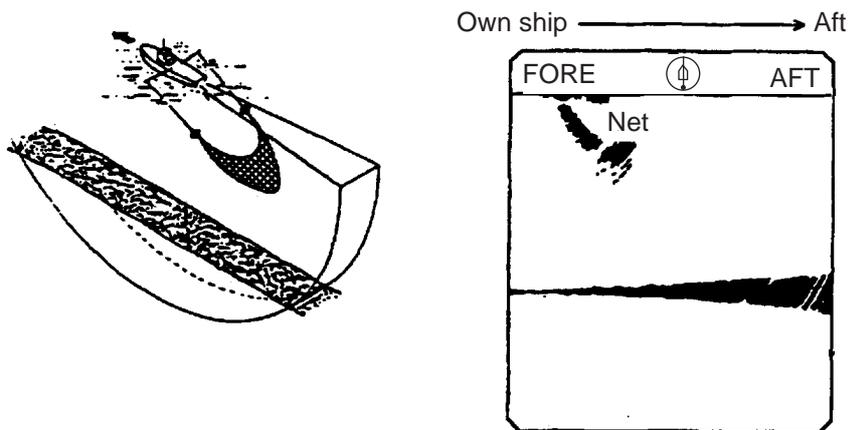
Net hauling and sonar picture

False echo

In shallow water (depth less than 100 m) detection, unwanted echoes shown in the figure may appear. This phenomenon is caused by the false echo from the previous transmission. Reducing the Tx rate (on the COM1 menu) or lowering the range may lessen this effect.
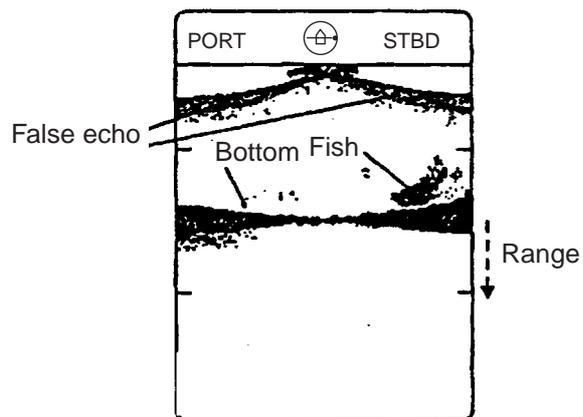
False echoes

3.14.3 Horizontal/vertical scan port-starboard, Horizontal/vertical scan upward-downward display
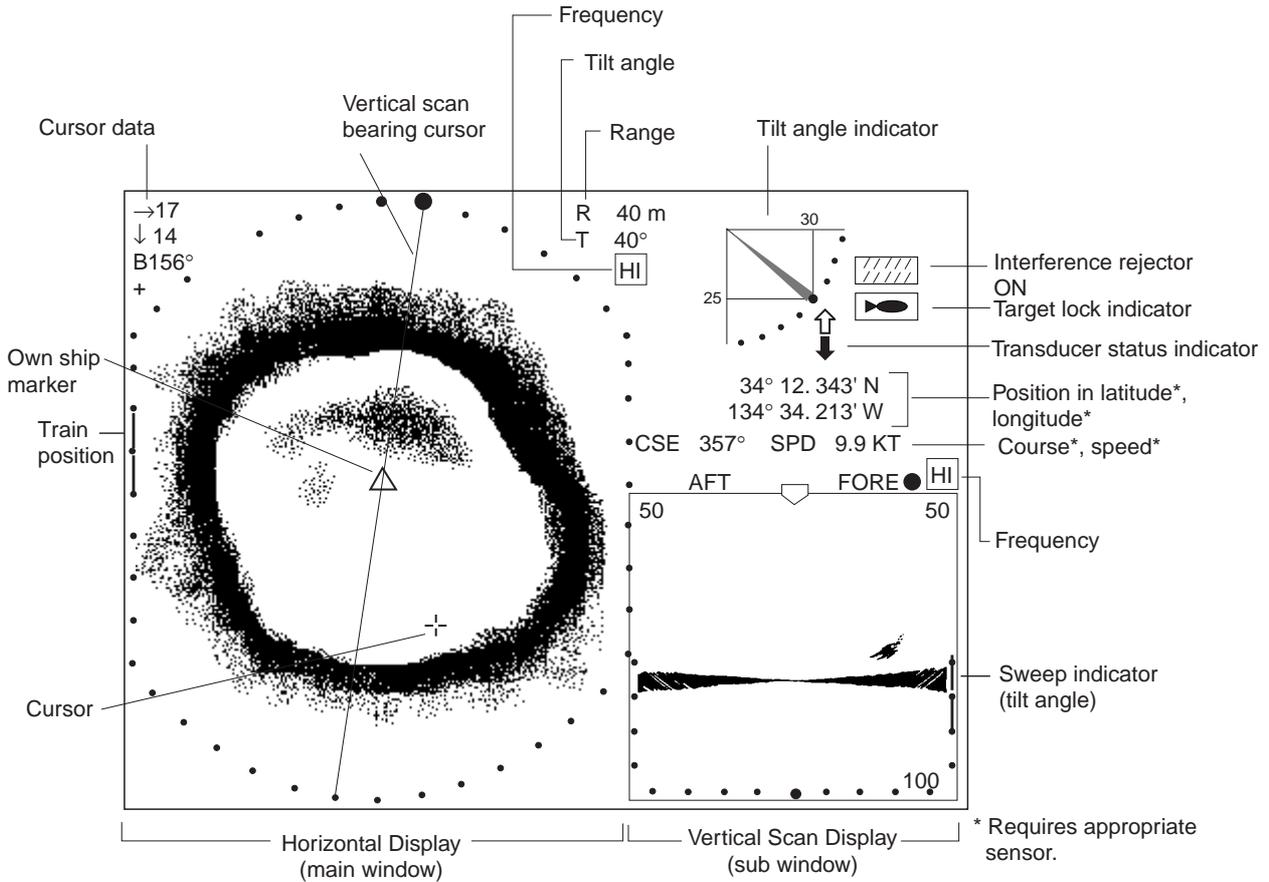
Horizontal/vertical scan display (port-starboard direction)

Horizontal Display (main window)

Vertical Scan Display (sub window)

→16
↓ 13
B 288°
+

R   60 m
T   40°
LO

30

25

34° 12. 343' N
134° 34. 213' W

CSE   357°
SPD   9.9 kt

DEP   35.1 m
TMP   12.3°C

100   AFT   FORE ●   100 HI

100
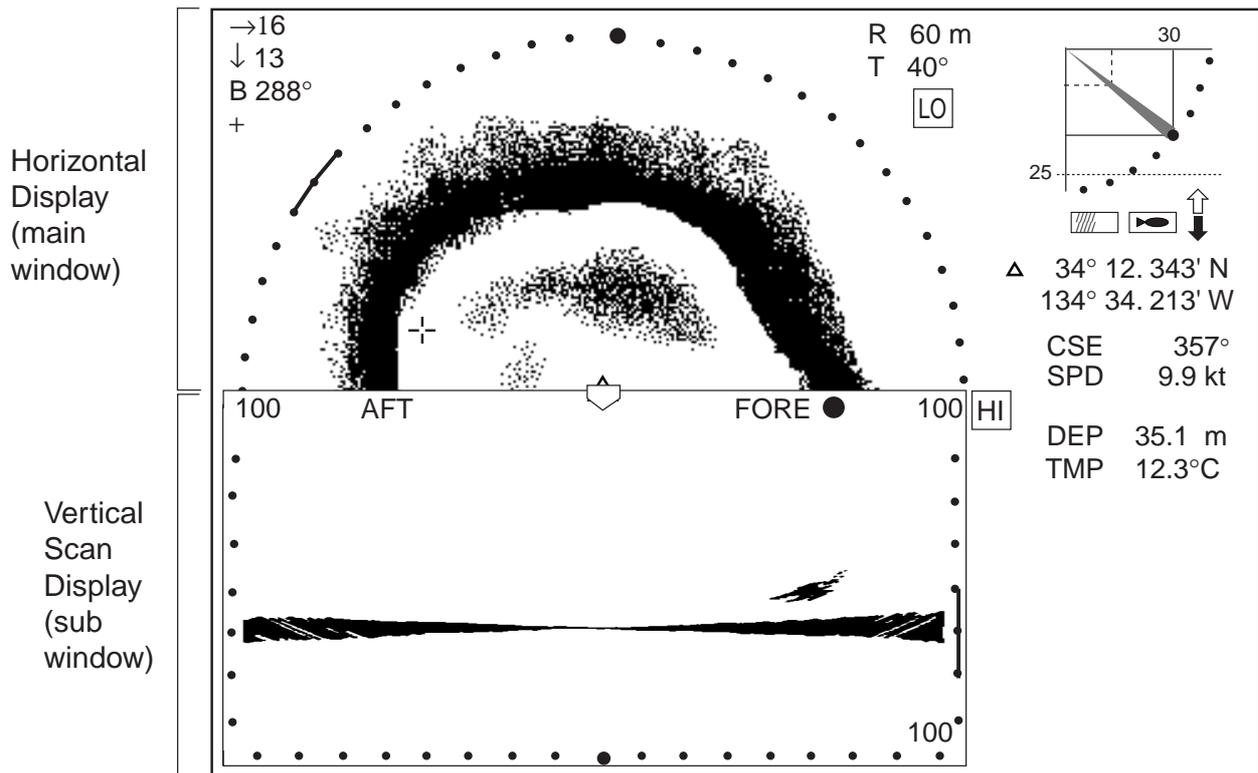
Horizontal/vertical scan display (upward-downward direction)

Press the ⊙▫ key to choose and display the horizontal/vertical scan display. The horizontal display appears in the main window; the vertical scan display in the sub window.

The displays are independent of each other so you can adjust them as desired. Press the **MAIN/SUB** key to choose the window to adjust. Each pressing of the key momentarily displays MAIN WINDOW CONTROLLABLE or SUB WINDOW CONTROLLABLE at the top of the screen. A red cursor appears in the sub window when it can be controlled. The following controls are operative on either window: **SECTOR**, **TRAIN**, **RANGE**, **TILT**, **FAST LF/HF, MIX, SCAN**, **FULL/HALF** and **CUSTOM MODE**.

Note: R/B, **EVENT** or **TARGET** controls may only be operated from the main window. When you attempt to operate them from the sub window the message SELECT MAIN WINDOW appears.

TRAIN control

For horizontal display: Sets training center direction.
For vertical scan display: Sets direction of bearing cursor shown on the horizontal mode display.

SECTOR control

For the vertical scan display: When the display sector is 6° (minimum) the tilt angle of the horizontal and vertical scan modes are interlocked and each transmission on the horizontal display is reflected on the vertical scan display. The message TILT ANGLE MONITOR WINDOW momentarily appears on the screen and the vertical bearing cursor disappears.

Note: Only the **SECTOR** control may be operated in this condition.
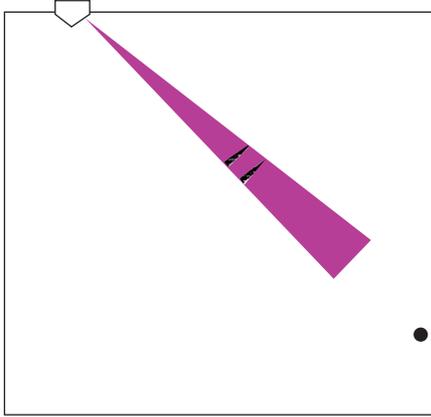
4. ECHO SOUNDER MODE

4.1 Operational Overview

The figure below shows the typical echo sounder mode operating sequence.

7. Set sector.

8. Set train bearing.

9. Set tilt angle.

5. Set range.

1. Turn on the power.

12. Adjust menu settings (turn on A-scope display, etc.).

6. Adjust gain.

2. Lower the transducer.

4. Select echo sounder mode.

3. Adjust screen brilliance.

11. Measure range to fish school with cursor.

10. Set picture advance speed.
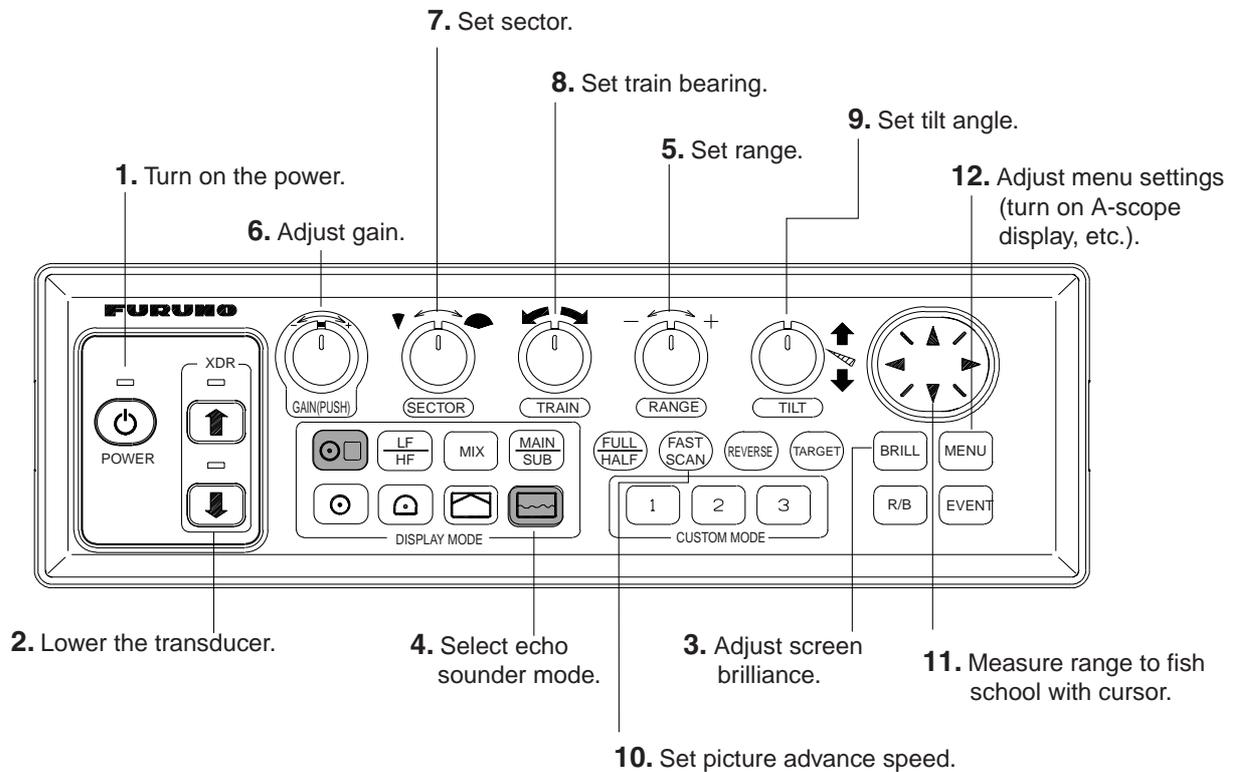
Control panel

4.2 Typical Echo Sounder Display

Press the ▭ key to display the echo sounder picture. You can switch between the single-frequency echo sounder display and the dual-frequency echo sounder display alternately with the ▭ key as shown below.
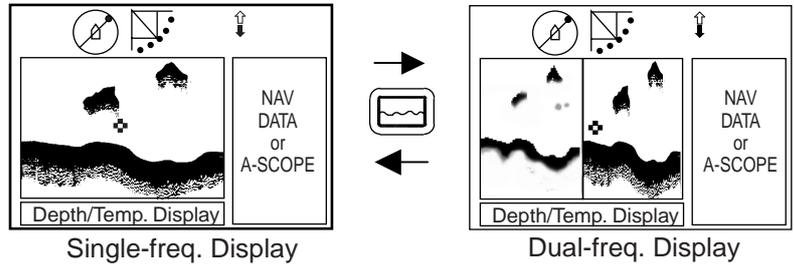
Switching between single-frequency echo sounder and dual-frequency echo sounder displays
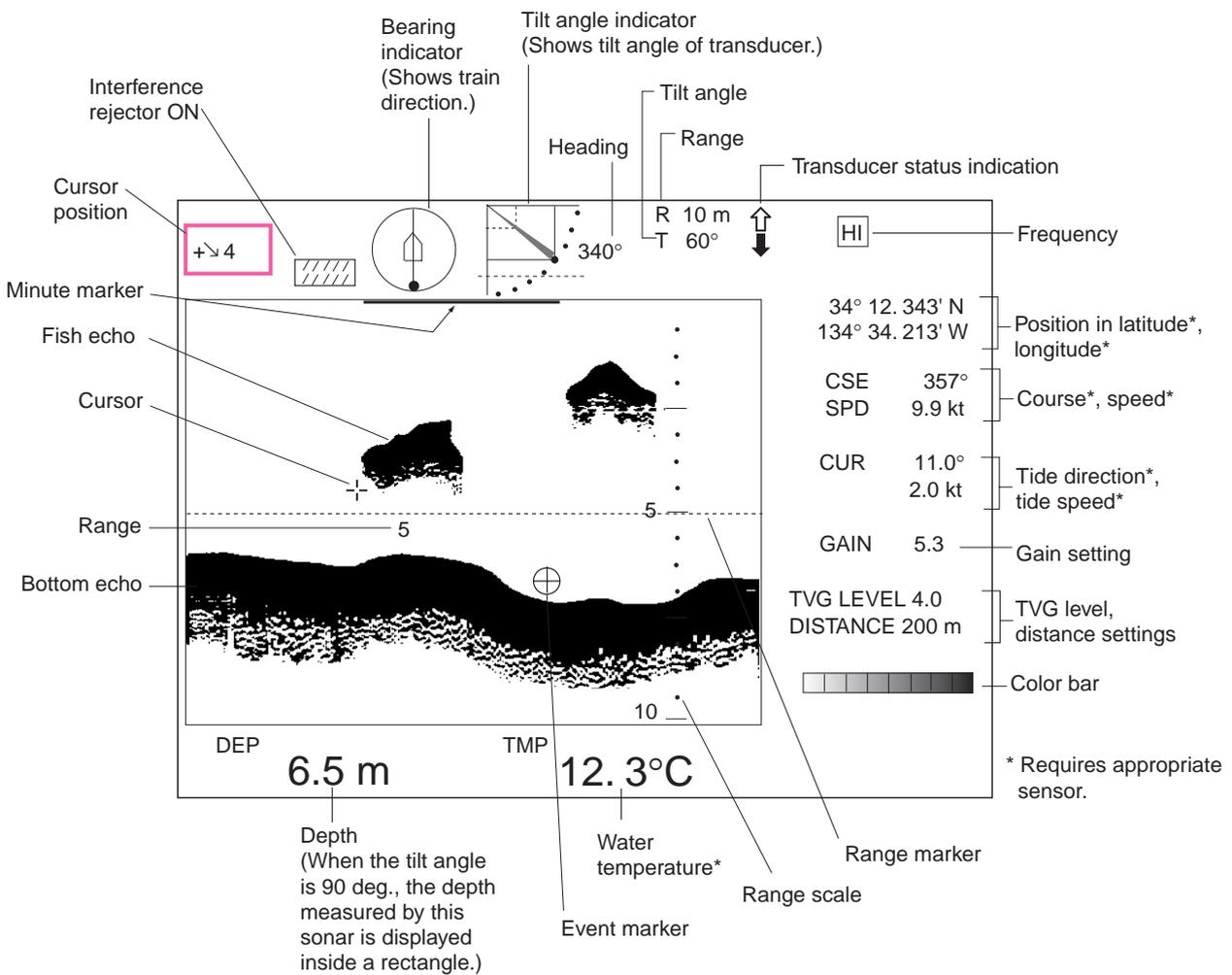
Single-frequency echo sounder display

4.3   Choosing a Range

The **RANGE** control chooses the detection (display) range, in 15 settings. Choose the range according to either the fish species being searched or the depth desired. Each time the control is operated the newly chosen range briefly appears in large characters at the screen top. Range is permanently displayed at the top right-hand corner.

Normally the range is set so that the bottom is traced at the lower part of the screen.
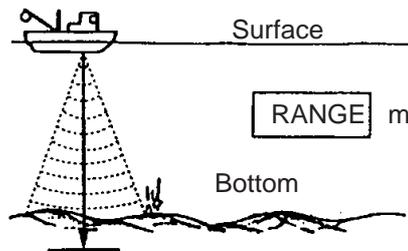
Range concept

Default echo sounder mode range settings

Unit	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Meters	10	20	30	40	60	80	100	120	160	200	250	300	400	500	600
Feet	30	60	90	120	150	200	250	300	400	500	600	800	1000	1500	2000

Note 1: Unit of range measurement may be selected for meters, feet, fathoms, passi/braza or Hiro (Japanese). For details see UNIT on page 5-11.

Note 2: Ranges may be freely preset as desired. For details see page 5-16.

4.4   Train Direction

The sounding beam may be directed toward fore, aft, port or starboard. Operate the **TRAIN** control to choose sounding beam direction. Each setting on the control is an increment of 6°. The train indicator at the top of the screen shows training direction: 0°, fore direction; 90°, starboard direction; 180°, aft direction, and 270°, port direction.

$$0° (360°) \rightarrow 6° \rightarrow 12° \rightarrow 18° \rightarrow ... 354°$$

Train 0°   Train 90°   Train 180°   Train 270°
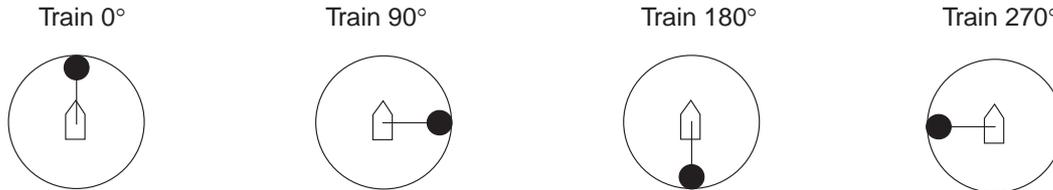
Train indicator and display

4.5   Choosing a Tilt Angle

The transducer can pointed directly toward the bottom or forward of the ship. Operate the **TILT** control to choose an appropriate tilt angle. The available tilt angle is 0° (horizontal direction) to 90° (vertical) in increments of 1°. Chosen tilt angle appears at the top of the display to the right of "T".

4.6   Choosing a Picture Advance Speed

The picture advance speed determines how quickly the vertical scan lines run across the screen, from right to left. When choosing a picture speed, keep in mind that a fast advance speed will expand a fish school horizontally on the screen and a slow one will contract it.

1. Press the **FAST SCAN** key to show the following dialog box.

    ```
    ADVANCE

    1/8      1/4      1/2      1/1      2/1
    ```
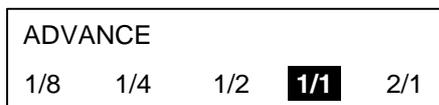
2. Press ◄ or ► (**FAST SCAN** key may also be used) to select a speed. The fractions in dialog box correspond to the number of scan lines produced per transmission. For example, "2/1" means two scan lines are produced per transmission.
3. Press the **MENU** key to close the dialog box. Note that the dialog box is automatically closed if there is no control operation for about four seconds.

4.7   Measuring Range by Cursor

Use the cursor to display the range from own ship to the cursor location. Use the Omnipad to place the cursor where desired. The range to the cursor appears at the upper left-hand corner of the screen.
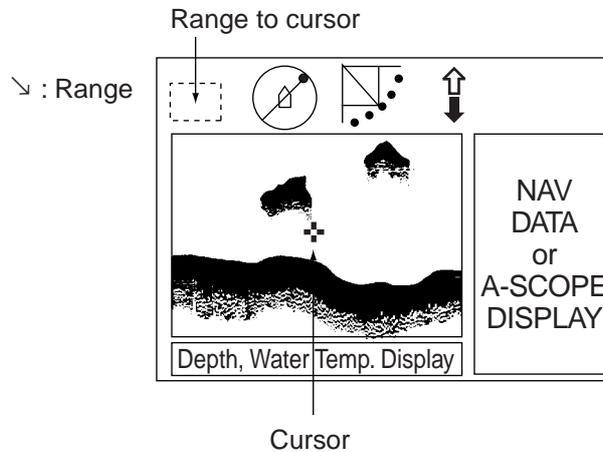
How to measure range with the cursor

4.8   Event Marker

The event marker functions to mark important locations on the echo sounder display, and five event markers may be inscribed. Each time the **EVENT** key is pressed the "latest event marker" (⊕) is inscribed at the cursor location and all previously entered event markers are shown by the "previous event marker" (+). When the capacity for event markers is reached the eldest event marker is erased from the screen to make room for the latest.

Note 1: The event marker inscribed on the echo sounder display will also be inscribed on the horizontal and video plotter displays, at own ship position always.

Note 2: Event marker position can be output to external equipment. For details see TARGET L/L on page 5-10.

Note 3: Event markers are automatically erased as they move off the screen with picture advancement.

4.8.1 Inscribing the event marker

1. Operate the Omnipad to place the cursor on the location desired for an event marker.
2. Press the **EVENT** key to inscribe the event marker.
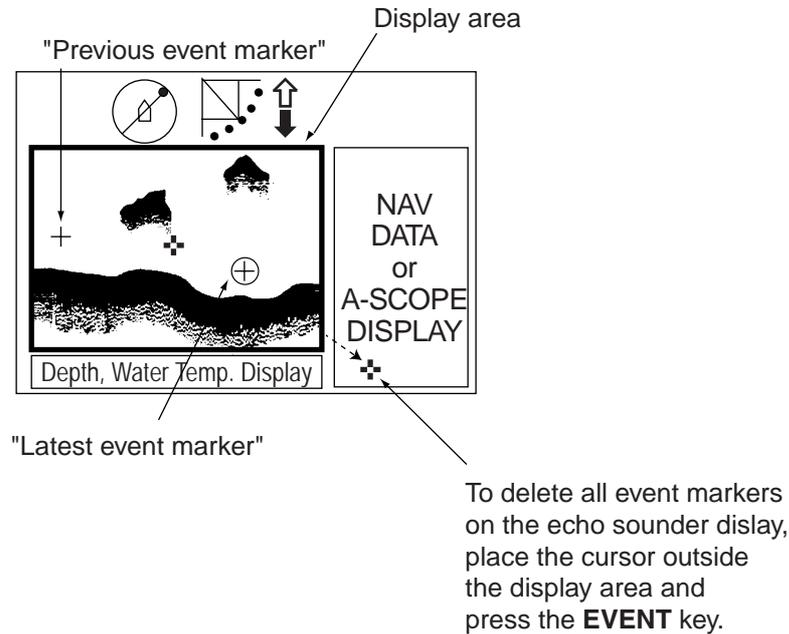
How to inscribe, delete the event markers

4.8.2 Deleting all event markers from echo sounder display

Event markers inscribed on the echo sounder display may be erased collectively as follows:

1. Operate the Omnipad to place the cursor outside the display area.
2. Press the **EVENT** key to show the following dialog box. Do the next step within four seconds, otherwise the dialog box will be erased.

```
DELETE EVENT MARK?

  NO    YES
```
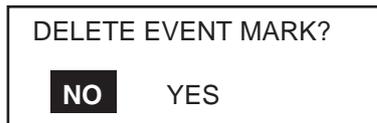
3. Press ► to choose YES and press the **MENU** key.

4.9 Range Marker

The range marker functions to measure the range to a target echo (fish school, bottom, etc.)

1. Operate the Omnipad to place the cursor on the location desired.
2. Press the **R/B** key to display the range marker. The range marker appears along with range indication.
3. To erase the range marker, press the **R/B** key again, or place the cursor on the range marker and press the **R/B** key.
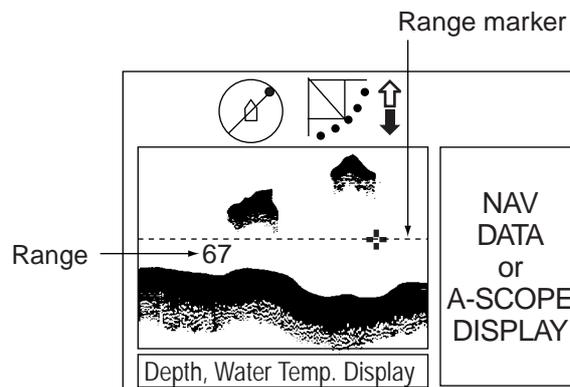
Range marker

4.10 Adjusting the Picture

4.10.1 Displaying weak echoes clearly

Echoes from targets (such as the bottom or a fish) return to the transducer in order of the distance to them, and when their intensities are compared at the transducer face, those from nearer targets are generally stronger when their reflecting properties are nearly equal. The sonar operator will be quite inconvenienced if these echoes are directly displayed on the screen, since he won't be able to judge the actual size of the target from the size of echoes displayed on the screen. To overcome this inconvenience, use the TVG function. It compensates for propagation loss of sound in water: amplification of echoes on short range is suppressed and gradually increased as range increases, so that similar targets are displayed in similar intensities irrespective of the ranges to them.
The TVG also functions to suppress unwanted echoes and noise which appears in a certain range area on the screen.

To adjust TVG:

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ or ► to choose the ES menu.

```
MENU          COM1   COM2   HORZ   VERT   ES   PRESET    SYS

  TVG LEVEL           4.0
  TVG DISTANCE        4.0
  RES. COLOR          LOG
  CLUTTER             0
  A-SCOPE             OFF




  ▲▼ : SELECT   ◀ ▶ : CHANGE    MENU: END
```

ES menu

3. Press ▲ or ▼ to choose TVG DISTANCE and press ►. The following dialog box appears.

```
  TVG DISTANCE │   4.0

  Hi

  Lo
         200m
```

4. Press ◄ or ►or to adjust TVG distance.

TVG Distance Setting	0	0.5	1.0	1.5	2.0	2.5	3.0	3.5	4.0	4.5	5.0	….	10.0
Meters	3	8	20	40	60	100	130	160	200	250	320	….	1000
Feet	10	30	70	130	210	330	410	520	660	820	1040		3280
Passi/braza	2	5	10	20	40	60	80	100	120	150	180		600
Hiro	2	5	10	20	40	60	80	100	130	170	210	….	660

5. Press ▲ or ▼ to close the dialog box and return the ES menu.
6. To suppress reflections by the sea surface or plankton, choose TVG LEVEL and press ►.
7. Press ◄ or ► to adjust TVG LEVEL.
8. Press the **MENU** key to register your selection and close the menu.

4.10.2 Finding echo strength (A-scope display)

The A-scope display shows echoes at each transmission with amplitudes and tone proportional to their intensities on the right 1/4 of the screen. It is useful for estimating the kind of fish school and bottom composition.

1. Press the **MENU** key.
2. Press ▲ to choose MENU.
3. Press ◄ or ► or to choose ES.
4. Press ▼ to choose A-SCOPE.
5. Press ◄ or ► to open the dialog box.
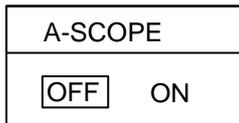
> A-SCOPE
>
> OFF   ON

6. Press ► to choose ON.
7. Press the **MENU** key to close the dialog box.
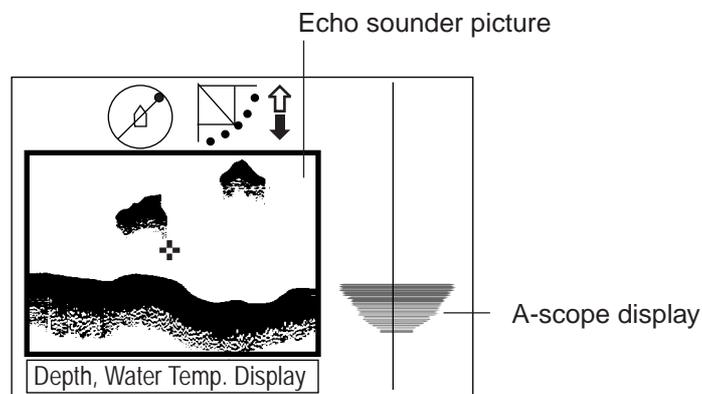
A-scope display

4.10.3 Suppressing interference and noise

You may encounter occasional noise or intermittent interference on the display. This is mostly caused by electrical equipment, engine, propeller noise from own ship, or noise from other sonars being operated nearby. If interference appears, turn on the interference rejector in the COM1 menu to suppress it. Note that the interference rejector cannot be turned on/off independently for each frequency in case of the dual-frequency display.
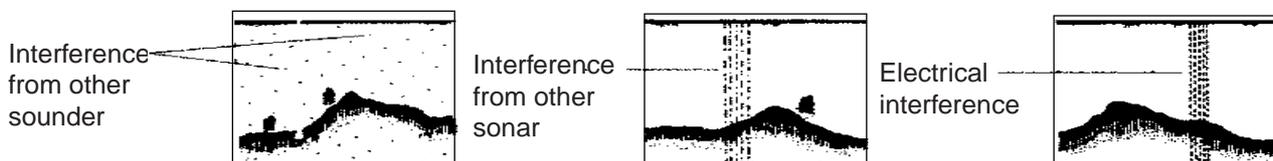
Interference

4.11 Echo Sounder Menu Overview

This section presents an overview of the items on the ES menu.

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU and then press ◄ or ► or to choose the ES menu.

```
┌─────────────────────────────────────────────────────────┐
│ MENU        COM1  COM2  HORZ  VERT  ES  PRESET    SYS     │
│ ┌───────────────────────────────────────────────────┐   │
│ │ TVG LEVEL          4.0                             │   │
│ │ TVG DISTANCE       4.0                             │   │
│ │ RES. COLOR         LOG                             │   │
│ │ CLUTTER            0                               │   │
│ │ A-SCOPE            OFF                             │   │
│ │                                                   │   │
│ │                                                   │   │
│ │                                                   │   │
│ │                                                   │   │
│ └───────────────────────────────────────────────────┘   │
│                                                          │
│  ▲▼ : SELECT   ◄ ► : CHANGE    MENU: END                 │
└─────────────────────────────────────────────────────────┘
```

ES menu

3. Press ▲ or ▼ to choose item desired.
4. Press ► to show corresponding dialog box.
5. Press ◄ or ► to choose option desired.
6. Press the **MENU** key to register your selection and close the menu.

4.11.1 Echo sounder menu description

TVG LEVEL: Compensates for propagation loss of sound in water. See paragraph 4.10.1. Default setting is 4.0.

TVG DISTANCE: As above. Default setting is 4.0.

RES. COLOR: Sets transfer characteristics of input signal level versus display echo level. Echo strength is emphasized in order of CUBE, SQUARE, LINEAR, LOG. You can see the characteristics of each by watching the color bar as you change the setting. The default setting is LOG.

LOG: Displays weak to strong echoes in their respective levels. This setting is suitable for general use.

LINEAR: Downplays the weak echoes when compared with LOG. Effective for suppressing weak echoes such as plankton.

SQUARE: Strong echoes are emphasized more than in LINEAR.

CUBE: Strong echoes are emphasized even more than in SQUARE.

CLUTTER: Low intensity echoes, often caused by sediments in water, are painted on the screen as a large number of random dots. The higher the number (setting) the weaker the echoes which are erased.

A- SCOPE: Turns the A-scope display on/off. Default setting is OFF. See paragraph 4.10.2.

5. MENU OPERATION

This chapter provides menu operating information on menus not previously discussed: COM1, COM2, PRESET (or SHORT-CUT, depending on the setting of CUSTOM KEY on the SYSTEM SETTING 1 menu) and SYS (System) menu.

5.1   COM1 Menu

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU, and then press ◄ to choose COM1.

```
MENU           COM1  COM2  HORZ  VERT  ES  PRESET   SYS

   TX POWER          MAX
   PULSELENGTH       LONG
   TX RATE           10
   INT REJECT        OFF
   AGC               OFF
   AUDIO LEVEL       0




 ▲▼ : SELECT ◀ ▶ : CHANGE    MENU: END
```
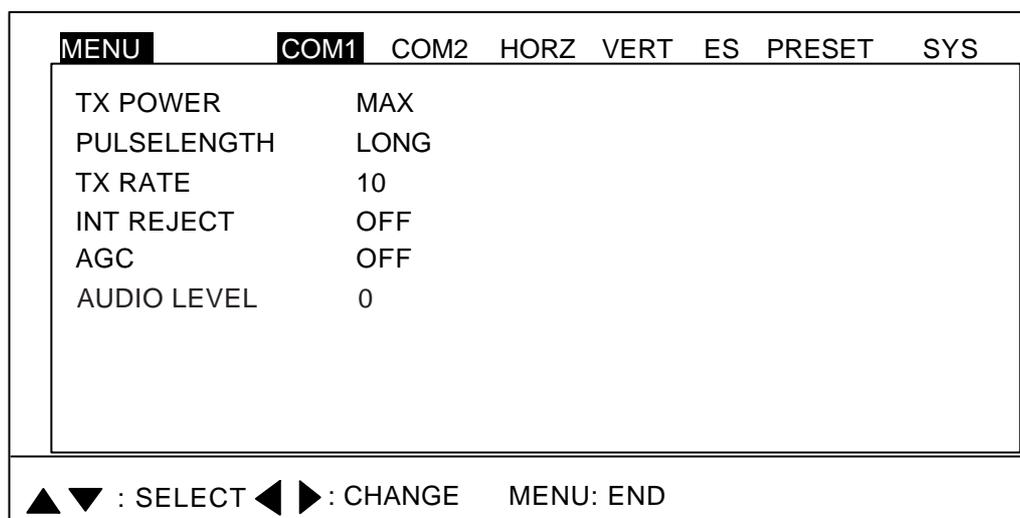
COM1 menu

3. Press ▲ or ▼ to choose item; ◄ or ► to open associated dialog box.
4. Press ◄ or ► to choose option desired.
5. Press ▲ or ▼ to return to the COM1 menu, or press the **MENU** key to register your selection and close the menu.

5.1.1 COM1 menu description

TX POWER: Chooses transmitter output power to maximum or minimum. The default setting is "maximum." For further details see paragraph 2.12.1.

PULSELENGTH: Chooses pulselength to short or long (default setting). For details see paragraph 2.12.2.

TX RATE: The Tx rate may be set between 1-10 (default setting: 10) in the case of the internal transmitter, or an external synchronous signal may be used. The higher the number the greater the number of transmissions. For operation in shallow waters, choose the Tx rate which displays the second reflection from the bottom between the sea surface and bottom. For use of an external video sounder or sonar, choose EXT.

INT REJECT: Turns the interference rejector on (high freq, low freq or both low and high freq) or off (default setting). When turned on ▨▨▨ appears at the top of the screen. Note that the interference rejector cannot be turned on/off independently for each frequency in case of the dual-frequency display. For further details about interference rejection, see paragraph 2.12.5 (horizontal display) and 3.12.2 (vertical scan display).

AGC: Automatically lowers sensitivity against strong echoes such as those from the bottom and large fish schools to emphasize weak echoes such as those from fish close to the bottom. The default setting is OFF.

AUDIO LEVEL: Adjusts the audio level (0-10) of the external loudspeaker (option). Sometimes you may be preoccupied with other tasks and unable to concentrate on watching the sonar picture. In such cases it would be a good choice to use the audio function. This function enables you to monitor echoes from fish schools and seabed through the built-in speaker. After you've become accustomed to monitoring fish aurally, you should be able to detect a fish school from a range longer than you can detect it on the screen. In addition you may judge whether the fish school is approaching or going away; the tone becomes higher when the school is approaching and lowers when the school is going away.

Note: If a dual-frequency display is active, the frequency sound from the left-side display* (for the dual-frequency vertical scan display the top display) is output.

*: Dual-frequency horizontal display, dual-frequency horizontal expansion, dual frequency echo sounder

5.2 COM2 Menu

5.2.1 Displaying the COM2 menu

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU, and then press ◄ or ► to choose COM2.

```
┌──────────────────────────────────────────────────┐
│ MENU        COM1  COM2  HORZ  VERT  ES  PRESET  SYS │
│                                                    │
│  DELETING TRACK    NO                              │
│  MIX MODE          STANDARD                        │
│  WHITE MARKER      OFF                             │
│  SIG LEVEL         OFF                             │
│  COLOR             16                              │
│  BKGD COLOR        2                              │
│                                                    │
│                                                    │
│                                                    │
│ ─────────────────────────────────────────────     │
│  ▲▼ : SELECT ◄ ► : CHANGE    MENU: END            │
└──────────────────────────────────────────────────┘
```
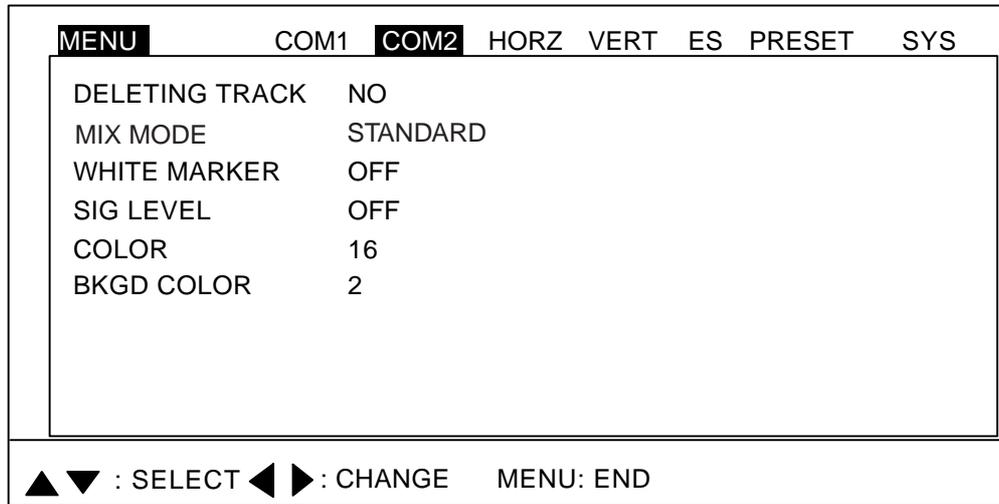
COM2 menu

5.2.2 COM2 menu description

DELETING TRACK: Choose ON to delete all ship's track (from horizontal and horizontal/video plotter displays).

MIX MODE: Choose how to process the mix display. "STANDARD" displays high frequency level when high frequency signal is larger than low frequency signal, which is useful for finding absolute echo level. "EMPHASIS" displays difference in level when high frequency signal is larger than low frequency signal, which is useful for finding difference in echo level between low and high frequencies. Default setting is STANDARD.

WHITE MARKER: Displays desired echo in white. It is useful for discriminating bottom fish from the bottom echo. The setting range for the 8-color display is OFF, 1-7, and for the 16-color display, OFF, 1-15.

SIG LEVEL: Refer to page 2-16.

COLOR: Chooses 8- or 16-color display.

BKGD COLOR: Chooses color of background, text and menu. Three choices are available and these are shown in the table below.

BKGD COLOR	Background	Text	Menu
1	Black	Gray	Dark-blue
2	Dark-blue	White	Medium blue
3	White	Black	Gray

5.3 Short-cut Menu, Preset Menu

These menus program the CUSTOM MODE keys [1], [2] and [3], and one of the menus appears according to the setting of CUSTOM KEY on the SYSTEM SETTING 1 menu.
Short-cut key: One-touch activation of corresponding dialog box. This is the default setting.
Preset key: One-touch setup of mode, sector, train, range, tilt and speed controls. Below are the default settings for PRESET.

CUSTOM MODE key	Display Mode	Frequency	Sector	Train	Range (m)*	Tilt
Key 1	Horizontal expansion	LO	240°	0°	200	30°
Key 2	Horizontal	HI	360°	0°	200	30°
Key 3	Vertical scan	LO	180°	90°	120	90°

5.3.1 Choosing short-cut or preset

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU, and then press ► to choose SYS.

```
┌─────────────────────────────────────────────────────────┐
│ MENU          COM1  COM2  HORZ  VERT  ES  PRESET    SYS   │
│   GO TO SYS MENU          YES    NO                       │
│                                                           │
│                                                           │
├─────────────────────────────────────────────────────────┤
│ ▲▼ : SELECT   ◄ ► : CHANGE    MENU: END                  │
└─────────────────────────────────────────────────────────┘
```
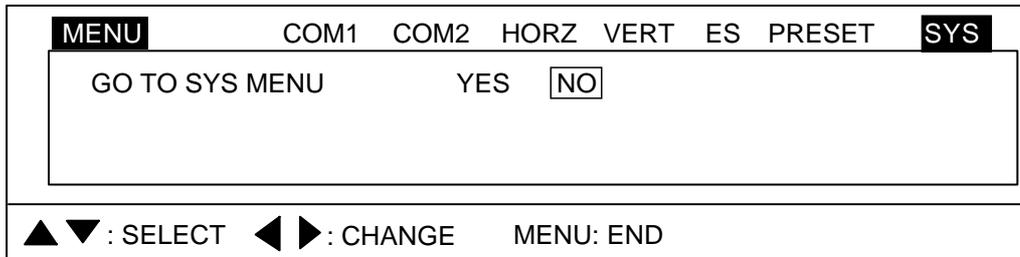
Display for opening system menu

3. Press ▼ to choose GO TO SYS MENU.
4. Press ◄ to choose YES.

```
┌─────────────────────────────────────────┐
│            ** SYSTEM MENU **             │
│         SYSTEM SETTING        ►          │
│         RANGE-SONAR MODE                  │
│         RANGE-VERTICAL MODE               │
│         RANGE-E/S MODE                    │
│         RANGE-TRACK MODE                  │
│         COLOR PALETTE                     │
│         LANGUAGE                          │
│         SYSTEM BACKUP                     │
│         LOAD BACKUP DATA                  │
│         HEADING OFFSET, DRAFT OFFSET      │
│         ADJ MOTION SENSOR                 │
│         TX FREQ ADJUST                    │
│         TEST                              │
│         TEST PATTERN                      │
│         DEMO MODE                         │
│         DEFAULT                           │
├─────────────────────────────────────────┤
│  ▲▼ : SELECT  ► : MENU DISPLAY  MENU: END │
└─────────────────────────────────────────┘
```
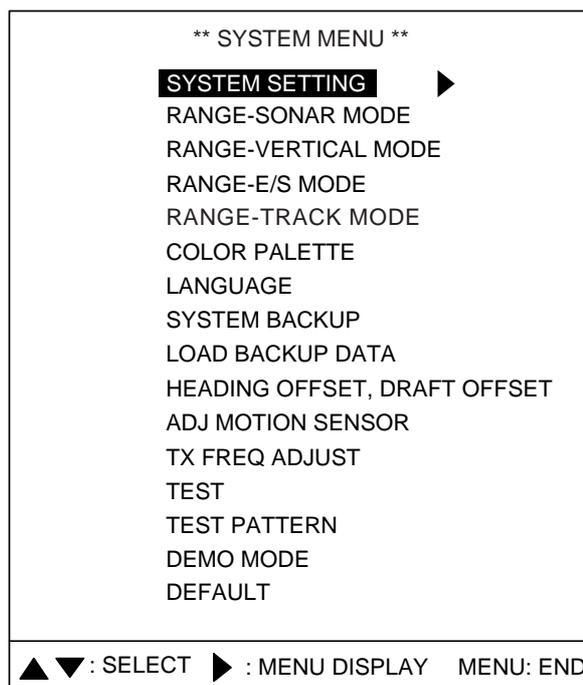
System menu

5.   Press ► to open the SYSTEM SETTING menu.

```
                          ** SYSTEM SETTING 1 **


   MENU                    1              2
     POSITION            : SHIP'S L/L        SHIP'S LOP     CURSOR L/L
     TRACK               : OFF        ON
     CURRENT DATA        : OFF        FLOW FROM     FLOW TO
     HEADING INDICATION  : TRUE       AZ
     NORTH MARK          : OFF        ON
     CSE DATA            : NAV        GYRO
     NAV DATA            : GPS        LoranC  LoranA  DR  DECCA  OTHERS
     NAV2 BAUDRATE       : 4800       9600    19200   38400
     TVG CORRECTION      : OFF        1/2     1/1
     UNIT                : m          ft       fa      HIRO  P/B
     TEMP                : ˚C         ˚F
     TARGET L/L          : OFF        ON
     CUSTOM KEY          : PRESET KEY SHORT-CUT KEY
     ETA MARK            : OFF        10sec  30sec  1min  3min  6min


   ▲ ▼ : SELECT    ◄ ► : CHANGE     MENU: END
```

System setting 1 menu

6.   Press ▲ or ▼ to choose CUSTOM KEY.
7.   Press ◄ or ► to choose PRESET KEY or SHORT-CUT KEY as desired.
8.   Press the **MENU** key twice to register your selection and close the menu.

5.3.2   Preset key

1.   Choose PRESET KEY following the procedure in paragraph 5.2.1.
2.   Press the **MENU** key to open the menu.
3.   Press ▲ to choose MENU, and then press ◄ or ► to choose PRESET.

```
   MENU        COM1  COM2  HORZ  VERT  ES  PRESET  SYS

              MODE   FREQ.  SECTOR   TRAIN   RANGE   TILT

   PRESENT    (·)     HI     360°      0°     200     30°

   CUSTOM1    ⌓       LO     240°      0°     200     30°

   CUSTOM2    (·)     HI     360°      0°     200     30°

   CUSTOM3    ◺       HI     180°     90°     200     90°


   ADJUST THE KNOBS AND FUNCTION KEYS TO THE DESIRED SETTING,
   THEN PRESS A CUSTOM MODE KEY TO SAVE THE SETTING.
   FUNCTION KEY: ENTRY    MENU: END
```

PRESET menu

4. Set the **MODE**, **HI/LO**, **SECTOR**, **TRAIN**, **RANGE** and **TILT** controls according to target fish or fishing area.
5. Press the CUSTOM MODE keys [1], [2] or [3] to program. You are asked if you want to save the settings to the custom key pressed. (In the example, the custom key [1] was pressed.)

```
SAVE THE SETTING TO CUSTOM1 KEY?

        NO     YES


     ◀ ▶ : CHANGE     MENU: END
```

6. Press ► to choose YES.
7. Press the **MENU** key. The message "PRGM SET" appears at the screen top.
8. Press the **MENU** key to finish.

Activating the custom mode

1. Press appropriate CUSTOM MODE key. The indication CUSTOM1, CUSTOM2 or CUSTOM3 appears at the top of the screen depending on key pressed.
2. To escape from the custom mode operation, operate any of the controls among **MODE**, **SECTOR**, **TRAIN**, **RANGE**, **TILT** and **FAST SCAN**.

5.3.3   Short-cut key

The default settings are key [1], interference rejector; key [2], signal level, and key [3], background color. The operator may change their functions as desired.

Note: In the combination modes the short-cut key operation is only possible from the main window.

1. Choose SHORT-CUT following the procedure in paragraph 5.2.1.
2. Press the **MENU** key to open the menu.
3. Press ▲ to choose MENU, and then press ◄ or ► to choose SHORT-CUT.

```
MENU            COM1   COM2   HORZ   VERT   ES  SHORT-CUT  SYS

                VER SEARCH   VOLUME   DEL TRACK   AUTO TILT   BKGD
     KEY 1
                SIG LEVEL    CLUTTER  RES. COLOR  WHITE MARKER

                VER SEARCH   VOLUME   DEL TRACK   AUTO TILT   BKGD
     KEY 2
                SIG LEVEL    CLUTTER  RES. COLOR  WHITE MARKER

                VER SEARCH   VOLUME   DEL TRACK   AUTO TILT   BKGD
     KEY 3
                SIG LEVEL    CLUTTER  RES. COLOR  WHITE MARKER

   SELECT FUNCTION TO BE ALLOCATED TO EACH CUSTOM KEY.
   CUSTOM KEY MAY BE USED AS A PRESET KEY.
   ▲▼ : SELECT    ◄ ► : CHANGE     MENU: END
```

SHORT-CUT menu

4. Press ▲ or ▼ to choose key to preset. For example choose KEY 1.
5. Press ◄ or ► to choose item.
6. Press the **MENU** key to finish.

Activating a short-cut key

1. Press a CUSTOM MODE key, and the dialog box programmed for the custom key pressed appears. For example, the dialog box below is for CLUTTER (HORZ).

```
CLUTTER (HORZ):    0  1  2  3
```

2. Press ◄ or ► to choose option desired.
3. Press the **MENU** key to close the dialog box.

VERTICAL SEARCH FUNCTION

When you find a target of interest on the horizontal display, simply press the function key programmed for VER. SEARCH to get a cross-sectional view of the vertical plane. This mode is useful for evaluating fish school concentration and location of the targeted fish school or for assistance in navigation.
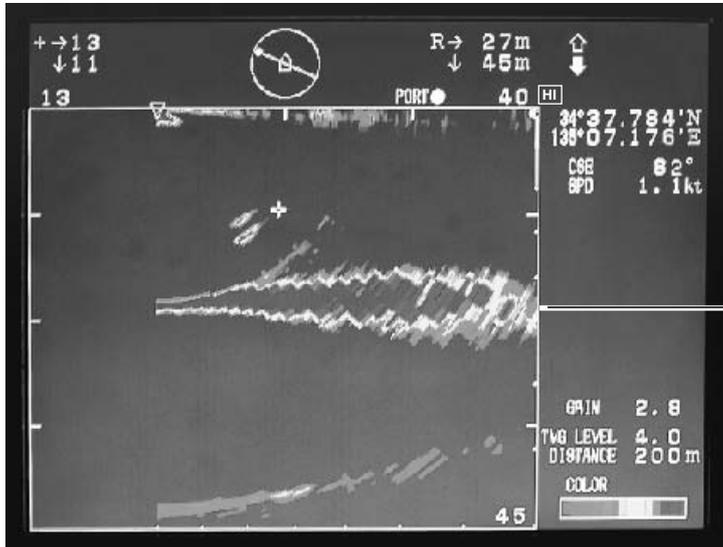
Fish School

The vertical search picture is drawn using the following specifications:
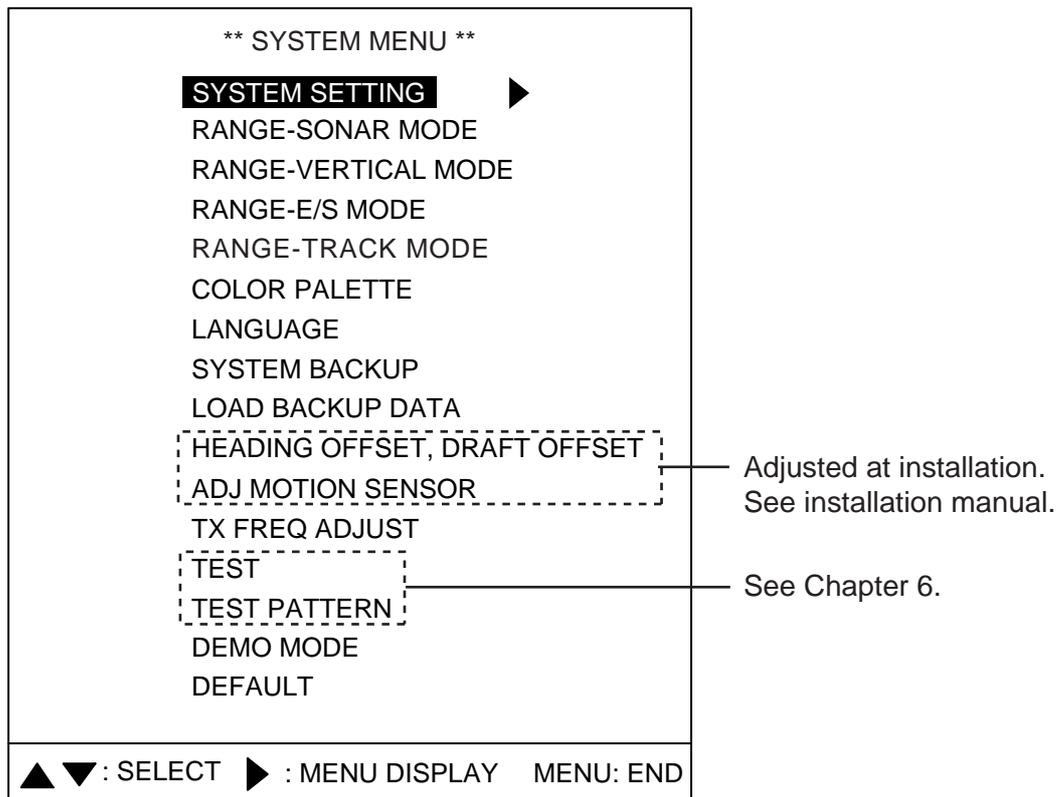
- Horizontal range: Same as set on horizontal mode
- Vertical range: Same as set on horizontal mode
- Train marker: Train angle at the moment function key is turned on
- Vertical scan display range: 0-90 degrees (own ship position shifted leftward)

5.4 SYSTEM Menu

This menu provides items which may be set according to operator's preference. A demonstration mode is provided to acquaint you with the many functions of this equipment, and it may be used without connection of the transducer.

5.4.1 How to open the SYSTEM menu

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU, and then press ► to choose SYS.
3. Press ▼ to choose GO TO SYS MENU.
4. Press ◄ to choose YES.

```
          ** SYSTEM MENU **

      SYSTEM SETTING        ►
      RANGE-SONAR MODE
      RANGE-VERTICAL MODE
      RANGE-E/S MODE
      RANGE-TRACK MODE
      COLOR PALETTE
      LANGUAGE
      SYSTEM BACKUP
      LOAD BACKUP DATA
      HEADING OFFSET, DRAFT OFFSET      ──── Adjusted at installation.
      ADJ MOTION SENSOR                        See installation manual.
      TX FREQ ADJUST
      TEST                              ──── See Chapter 6.
      TEST PATTERN
      DEMO MODE
      DEFAULT

  ▲ ▼ : SELECT   ► : MENU DISPLAY   MENU: END
```

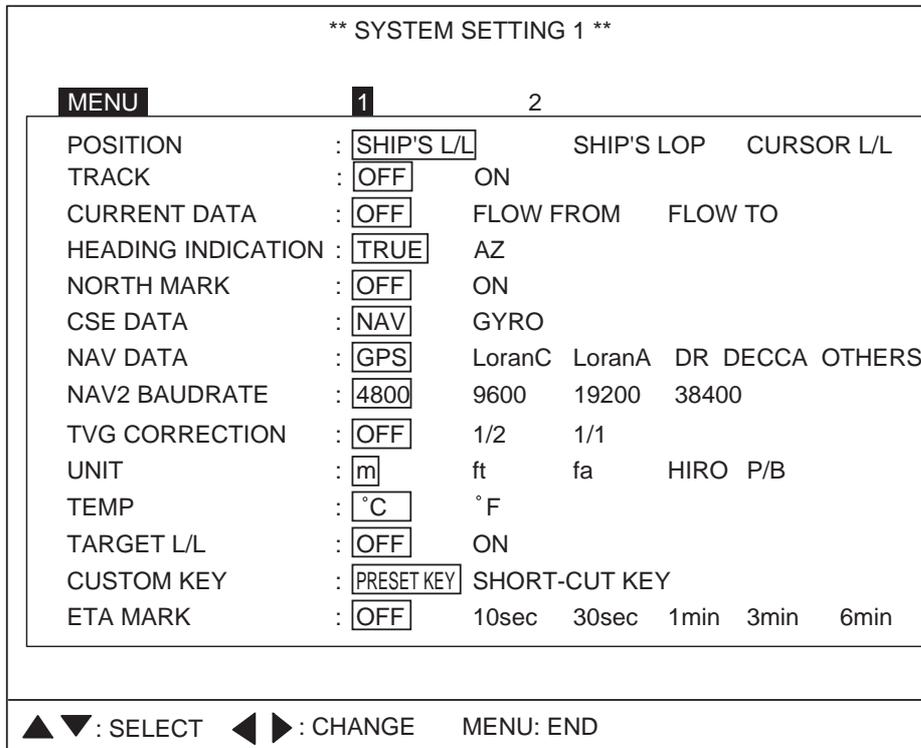*System menu*

5. Press ▲ or ▼ to choose item desired.
6. Press ◄ or ► to open corresponding dialog box.
7. Press ◄ or ► to choose option.
8. Press the **MENU** key twice to register your selection and close the menu.

5.4.2   System setting menus

SYSTEM SETTING 1 menu

1. Display the SYSTEM menu and press ▲ or ▼ to choose SYSTEM SETTING.
2. Press ►.
3. Press ▲ to MENU.
4. Press ◄ to choose "1."

```
                    ** SYSTEM SETTING 1 **


   MENU              1            2
   POSITION        : SHIP'S L/L       SHIP'S LOP    CURSOR L/L
   TRACK           : OFF       ON
   CURRENT DATA    : OFF       FLOW FROM     FLOW TO
   HEADING INDICATION : TRUE   AZ
   NORTH MARK      : OFF       ON
   CSE DATA        : NAV       GYRO
   NAV DATA        : GPS       LoranC   LoranA   DR  DECCA  OTHERS
   NAV2 BAUDRATE   : 4800      9600     19200    38400
   TVG CORRECTION  : OFF       1/2      1/1
   UNIT            : m         ft       fa       HIRO  P/B
   TEMP            : ˚C        ˚F
   TARGET L/L      : OFF       ON
   CUSTOM KEY      : PRESET KEY  SHORT-CUT KEY
   ETA MARK        : OFF       10sec   30sec   1min   3min   6min



   ▲▼ : SELECT   ◄ ► : CHANGE    MENU: END
```

System setting 1 menu

SYSTEM SETTING 1 menu description

POSITION: Chooses how to displays ship's position; latitude and longitude, Decca/Loran C LOP or Cursor L/L. (The connected navigator must be capable of displaying L/L or LOP.) The default setting is latitude and longitude. Position data required.

TRACK: Turns the track display on or off on the horizontal display. The track is always shown on the video plotter display regardless of this setting.

CURRENT DATA: Turns current data (tide), shown by vector, on or off. FLOW FROM shows from what direction the current is flowing; FLOW TO shows the direction the current is heading. The default setting is OFF. Requires a current indicator.

FLOW FROM   FLOW TO
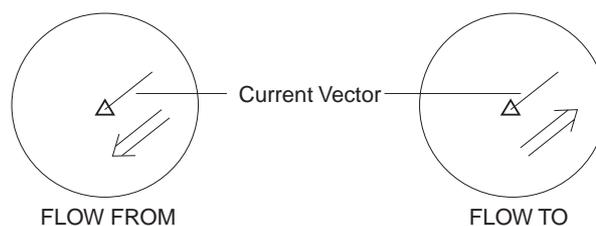
Current vector

HEADING INDICATION: Chooses heading indication format, true (default setting) or azimuth, for the echo sounder and vertical scan modes. The default setting is TRUE. Requires heading data.

NORTH MARK: Turns the north marker on or off (default setting). Requires heading data.

CSE DATA: Chooses heading data source, navigator or gyrocompass, to draw ship's track. The default setting is navigator. For heading sensor or gyrocompass connection, choose gyrocompass.

NAV DATA: Chooses source of position data, GPS, Loran C, Loran A, DR (Dead Reckoning), Decca or Others (for equipment not shown, receives talker only). Default setting is GPS.

NAV2 BAUDRATE: Sets the baud rate of the NMEA port on transceiver unit. Default setting is 4800 bps. For connection with satellite compass, choose 38400 bps.

TVG CORRECTION: Changes TVG curve to compensate for attenuation absorption of ultrasonic wave in water. OFF (default setting), standard TVG curve; 1/2, 1/2 of the theoretical absorption value added to TVG curve, and 1/1, full theoretical absorption value added to TVG curve.

UNIT: Chooses unit of depth measurement: meters (default setting), feet, fathoms, passi/braza, Hiro.

TEMP: Chooses unit of water temperature measurement: °C (default setting), °F.

TARGET L/L: Turn on to output event marker position to external equipment. Requires heading and latitude and longitude data from external equipment. Default setting is OFF.

CUSTOM KEY: Chooses function of custom mode keys: preset (default setting) or short-cut. For details see paragraph 5.2.

ETA MARK: A vector line extends from the own ship marker in direction of ship's bow on the horizontal mode display. The tip of the line shows the estimated time of arrival after the selected ETA time elapses, using the current ship's speed. ETA is calculated every second considering tilt and detection range. This function requires speed input.

ETA marker
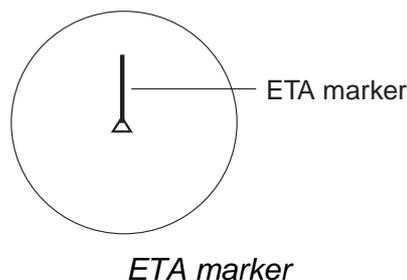
SYSTEM SETTING 2 menu description

```
                    ** SYSTEM SETTING 2 **

    MENU              :  1          2

    GAIN SETTING PROTECT:  OFF      [ON]
    HORZ/HISTORY      :  OFF        [ON]
    HORZ/VERT         :  OFF        [ON]
    HORZ/VERT ZOOM    :  OFF        [ON]
    HORZ/PLOTTER      :  OFF        [ON]
    EMPHASIS MODE     :  OFF        [NORMAL]      RED

    STABILIZER        :  OFF        [MOTION SENSOR]   SAT. COMPASS
    AUTO RETRACTION   :  [OFF]      (OFF, 5-15 kt)
    SPEED ALARM/MESSAGE:  OFF       [ON]
    SWEEP INDICATOR   :  DOT        [LINE]
    DEFAULT SETTING   :  [NO]       YES

    MAXIMUM ALLOWABLE SPEED IS 15 KNOTS WHILE SOUNDOME IS BEING
    RETRACTED. IF VESSEL HAS RAPID ACCELERATION CAPABILITIES,
    AUTO RETRACTION SETTINGS OF 10-12 KNOTS ARE MANDATORY TO
    AVOID CATASTROPHIC DAMAGE TO SOUNDOME ASSY. ANY PHYSICAL
    DAMAGE TO THE SOUNDOME ASSY. IS CONSIDERED ABUSE AND
    IS NOT A WARRANTY ISSUE.


    ▲ ▼ : SELECT    ◀ ▶ : CHANGE    MENU: END
```

System setting 2 menu

GAIN SETTING PROTECT: Prevents accidental adjustment of the gain. When ON the gain cannot be adjusted unless the GAIN control is first pushed. Default setting is ON. This feature is effective on the single-frequency displays and combination displays (mix display OFF).

HORZ/HISTORY: Enables/disables the horizontal/history display. Default setting is ON.

HORZ/VERT: Enables/disables the horizontal/vertical scan display. Default setting is ON.

HORZ/VERT ZOOM: Enables/disables the horizontal/vertical zoom display. Default setting is ON.

HORZ/PLOTTER: Enables/disables the horizontal/plotter display. Default setting is ON.

EMPHASIS MODE: Choose method of picture interpolation. OFF: Interpolation close to raw signal. NORMAL: Clarifies picture. EMPHASIS: Emphasizes strong signals.

STABILIZER: Choose the sensor to use to compensate for effects of ship's pitching and rolling. The choices are Motion Sensor MS-100, Clinometer BS-704 and Satellite Compass (SC-50/SC-110).

AUTO RETRACTION: Turn on to automatically retract the transducer when ship's speed exceeds the speed set here. The ship's speed range for automatic retraction is from 5 to 15 knots. The default setting is OFF (no automatic retraction). The transducer may be retracted at a speed other than the intended one when ship's speed data is erroneous.

SPEED ALARM/MESSAGE: Turn on (default setting) to display speed alarm message and sound the audio alarm when ship's speed exceeds allowable speed for a given transducer operation. The audio alarm can be silenced with the **R/B** key.

[↓] pressed to lower transducer	
Speed above 15 kts	Message 1 appears. Reduce speed below 15 kts to restore normal operation.
Transducer being lowered	
Speed over 15 kts	Message 1 appears and lowering continues.
Transducer lowered	
Speed above 20 kts	Message 2 appears accompanied with the aural alarm. Reduce the speed below 20 kts to restore normal operation.
[↑] pressed to raise transducer	
Speed above 15 kts	Message 1 appears accompanied with the aural alarm. Transducer is not raised. Reduce the speed below 15 kts to erase the message and restore normal operation. Then, press [↑] again to raise the transducer.
Transducer being raised	
Speed above 15 kts	Message 1 appears and raising continues. Reduce the speed below 15 kts to erase the message and restore normal operation.

```
SHIPS  SPEED
    EXCEEDS 15 kt.
(SLOW DOWN UNDER 15 kt WHEN
    MOVING TRANSDUCER UNIT.)

PRESS R/B KEY TO SILENCE ALARM.
```

```
TRANSDUCER REMAINS
    LOWERED.
(REDUCE SHIP'S SPEED AND PRESS
↑ TO RETRACT IT.)

PRESS R/B KEY TO SILENCE ALARM.
```

Message 1   Message 2

SWEEP INDICATOR: Shows train position in the horizontal mode and tilt angle in the vertical scan mode, with a line or a dot. (See the illustration on page 2-2 and 3-2.)

DEFAULT SETTING: Choose YES and press the **MENU** key to restore all default system menu settings. Several beeps sound while default settings are being restored and then normal operation is restored.

```
** FACTORY SETTING **


ARE YOU SURE?          :     NO          YES




NOTE!   ALL THE SYSTEM SETTING WILL BE CHANGED
        TO FACTORY SETTING.

◀ ▶ : CHANGE     MENU: END
```

FACTORY SETTING dialog box

5.4.3   Sonar (horizontal) mode range settings

The user may preset horizontal mode ranges as desired.

1. Choose RANGE-SONAR MODE at the SYS menu and then press ►.

```
          ** RANGE-SONAR MODE **

     1         :         20   (10-1600m)
     2         :         40
     3         :         60
     4         :         80
     5         :        100
     6         :        120
     7         :        160
     8         :        200
     9         :        250
    10         :        300
    11         :        400
    12         :        500
    13         :        600
    14         :        800
    15         :       1200



  DEFAULT SETTING  :          NO        YES

  ▲ ▼ : SELECT   ◄ ▶ : CHANGE    MENU: END
```

Range-sonar mode dialog box

2. Press ▲ or ▼ to choose range number desired.
3. Press ◄ or ► to set range.
4. To restore default horizontal mode range settings, choose DEFAULT SETTING, press ►
    to choose YES and press the **MENU** key.
5. Press the **MENU** key to register settings and close the menu.

5.4.4 Vertical scan mode range settings

As with the horizontal mode, the user may preset the vertical scan mode's ranges.

1. Choose RANGE-VERTICAL MODE at the SYS menu and then press ►.

```
            ** RANGE-VERT MODE **

        1        :        10  (10-600m)
        2        :        20
        3        :        30
        4        :        40
        5        :        60
        6        :        80
        7        :       100
        8        :       120
        9        :       160
       10        :       200
       11        :       250
       12        :       300
       13        :       400
       14        :       500
       15        :       600


   DEFAULT SETTING  :        NO        YES

   ▲▼ : SELECT   ◄► : CHANGE   MENU: END
```

Range-vert mode dialog box

2. Press ▲ or ▼ to choose range number desired.
3. Press ◄ or ► to set range.
4. To restore default vertical scan mode range settings, choose DEFAULT SETTING, press ► to choose YES and press the **MENU** key.
5. Press the **MENU** key to register settings and close the menu.

5.4.5   Echo sounder mode range settings

As with the horizontal and vertical scan modes, the user may preset the echo sounder mode's ranges.

1. Choose RANGE-E/S MODE at the SYS menu and then press ►.

```
            ** RANGE-E/S MODE **

        1        :       10  (10-600m)
        2        :       20
        3        :       30
        4        :       40
        5        :       60
        6        :       80
        7        :      100
        8        :      120
        9        :      160
       10        :      200
       11        :      250
       12        :      300
       13        :      400
       14        :      500
       15        :      600


   DEFAULT SETTING :        NO         YES

   ▲▼ : SELECT    ◄ ► : CHANGE    MENU: END
```

Range-E/S mode dialog box

2. Press ▲ or ▼ to choose range number desired.
3. Press ◄ or ► to set range. The setting range depends on the transducer used.
4. To restore default echo sounder mode range settings, choose DEFAULT SETTING, press ► to choose YES and press the **MENU** key.
5. Press the **MENU** key to register settings and close the menu.

5.4.6   Track range settings

You may choose the video plotter display scale range as follows.

1. Choose RANGE-TRACK at the SYS menu and then press ►.

```
** RANGE-TRACK MODE **

   1          :      [ 500 ] (100-10000m)
   2          :      [1000]
   3          :      [2000]
   4          :      [4000]
   5          :      [8000]


DEFAULT SETTING :     [NO] YES


▲ ▼ : SELECT    ◄ ► : CHANGE    MENU: END
```

Range-track mode dialog box

2. Press ▲ or ▼ to choose range number desired.
3. Press ◄ or ► to set.
4. Press the **MENU** key to register settings and close the menu.

5.4.7 Color palette

The color palette lets the user change the color of echoes, background, text and menu as desired.
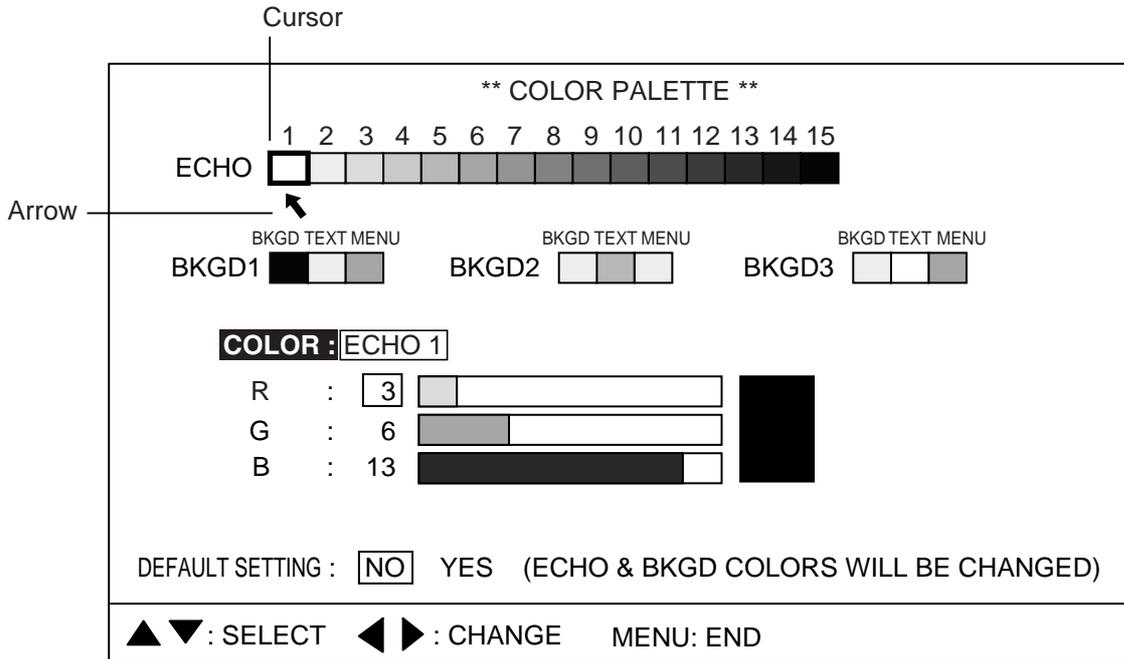
Color palette dialog box

1. Press ◄ or ► to place the cursor and arrow on the item to change. Pressing ► shifts the arrow and cursor from left to right and top to bottom.
2. Press ▲ or ▼ to choose R(red), G(green) or B(blue) as appropriate.
3. Press ◄ or ► to adjust color.
4. Press the **MENU** key to register your settings and close the menu.

Note: To restore default color settings, choose DEFAULT SETTING, press ► to choose YES, and press the **MENU** key. A few beeps sound while the default colors are being restored and then normal operation is restored.

5.4.8 Language

Menu language can chosen from among the languages shown in the Language dialog box and the default language is English.

```
                         ** LANGUAGE **


  LANGUAGE:      JAPANESE    ENGLISH    FRANCAIS   ESPANOL
                 ITALIANO    PORTUGUES  DANSK      NORSK
                 SVENSK      THAI

  ◀ ▶ : CHANGE     MENU: END
```

Language dialog box

5.4.9 System backup

User settings can be backed up with the menu item SYSTEM BACKUP.

```
                      ** SYSTEM BACKUP **


  ARE YOU SURE?          :      NO          YES



     NOTE:  OVERWRITES PREVIOUS BACKUP DATA.


  ◀ ▶ : CHANGE     MENU: END
```

System backup dialog box

5.4.10 Loading backup data

System data may be loaded from the LOAD BACKUP DATA dialog box.

```
                    ** LOAD BACKUP DATA **


  ARE YOU SURE?          :     NO          YES



     NOTE:  OVERWRITES CURRENT SETTINGS.


  ◀ ▶ : CHANGE     MENU: END
```

Load backup data dialog box

5.4.11   Transducer frequency adjustment

If the CH-300 is receiving interference from a video sounder or other sonar on board your ship, adjust the frequency of the CH-300's transducer to reduce the interference.

```
                      ** TX FREQ ADJUST **


  FREQ SHIFT (L)         :     85.0  kHz (85-95 kHz)
  FREQ SHIFT (H)         :    215.0 kHz (205-225 kHz)




  ▲ ▼ : SELECT  ◄ ► : CHANGE     MENU: END
```

TX frequency adjustment dialog box

5.4.12   Demonstration mode

The demonstration mode provides a simulated sonar picture which helps you become acquainted with how your sonar works. Connection of the transducer is not required. All controls are operational.
1. Display the SYS menu.
2. Choose DEMO MODE.
3. Press ► to open the menu.

```
                      ** DEMO MODE **


  DEMO MODE           :     OFF          ON




  ◄ ► : CHANGE    MENU: END
```

Demo mode dialog box

4. Choose OFF or ON as appropriate and press the **MENU** key. (DEMO) appears at the top of the screen when the demonstration mode is active.

5.4.13　Restoring all default settings

The item DEFAULT lets you restore all default menu settings. Choose YES and press the **MENU** key to restore all default settings. Note that SOUNDOME SER. NO (SYSTEM SETTING2 menu) and the contents stored by using the SYSTEM BACKUP feature (paragraph 5.4.9) are not disturbed.

```
                          ** DEFAULT **

    ARE YOU SURE?        :     NO          YES



     NOTE!  RESET ALL THE SETTINGS INCLUDED IN SYSTEM MENU
            TO DEFAULT.

    ◀ ▶ : CHANGE     MENU: END
```

Default menu

```
            ⚠ CAUTION

 All default settings will be restored.
 If necessary jot down settings which
 must be restored.
```

Note: The following appears after the power-up following the restoration of default settings.

```
 Please set language.
 ([▲/▼]: Select, [MENU]: Enter)

 ... For Japanese Customer
 In Japanese)


 (Japanese)
 English
 Francais
```

Language selection screen

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6. MAINTENANCE, TROUBLESHOOTING

This chapter provides information necessary for keeping the equipment in good working order.

⚠ **WARNING**

ELECTRICAL SHOCK HAZARD
Do not open the equipment.

Only qualified personnel should work inside the equipment.

6.1   Preventive Maintenance

Check the following points monthly.

- Check all cables. If damaged, replace.
- Check connectors at rear of each unit. Clean if necessary.
- Check earth of each unit. Clean if necessary.
- Check voltage of ship's mains to be sure it is within the equipment's power rating.

6.2   Cleaning the Equipment

Dust or dirt can be removed from the equipment with a soft, dry cloth. Do not use chemical cleaners to clean the equipment – they can remove paint and markings. The LCD will, in time, accumulate a coating of dust which tends to dim the picture. Wipe LCD lightly with soft cloth to remove dust.

6.3 Hull Unit Maintenance

6.3.1 Lubrication

Grease the raise/lower screw shaft once a year. Also, grease the raise/lower main shaft (upper part of the grease cotton retainer) twice a year. These parts can be accessed by removing the raise/lower drive assembly cover.

6.3.2 Manually raising, lowering transducer

> ⚠ **WARNING**
>
> **Turn off the power at the ship's mains switchboard before conducting the procedure below.**
>
> Rotating motor can cause bodily injury.

1. Turn off the breaker on the hull unit.
2. Turn nut with 19 mm ratchet wrench.
3. Check that the transducer raises and lowers smoothly, from the upper to the lower limit positions. If the transducer cannot be raised smoothly, do not use excessive force; the shaft may bend, causing damage to other components.
4. Check soundome and tank. Remove marine life with fine sandpaper or piece of wood.

Attach ratchet wrench here.

Hull unit
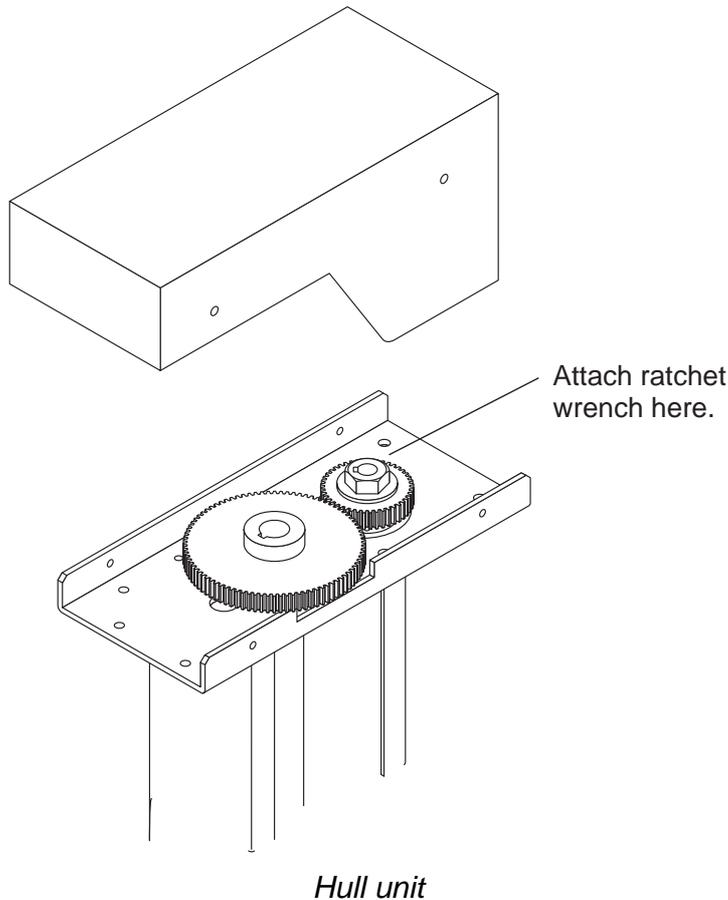
6.4 Transducer Maintenance

When the ship is dry-docked remove marine growth from the transducer with fine sandpaper or a piece of wood. Coat the transducer face with anti-fouling paint (Chugoku MarineStar 20 Red or the equivalent)

NOTICE
Do not paint the transducer face.
Loss of sensitivity will result.
Do not use plastic solvents to clean the transducer.
They can damage the transducer.

6.5 Fuse Replacement

The fuse in the hull and transceiver units protect them from overvoltage, equipment fault and reverse polarity of the ship's mains. If the power cannot be applied first check that the power cable between the transceiver unit and the monitor unit is firmly connected. If the power still cannot be applied, the fuse in the transceiver unit may have blown. Have a suitably qualified technician check the fuse.

Unit	Type	Code No.
Transceiver Unit	FGMB 10A AC125V	000-104-815
Hull Unit	FGMB 7A 125V	000-105-868
Monitor Unit	FGMB 3A 125V	000-104-909
Interface Unit	FGMB 0.2A 125V	000-121-723

⚠ WARNING
Use the proper fuse.
Use of a wrong fuse can cause fire or damage the equipment.

6.6 Troubleshooting

The table below provides common symptoms of equipment troubles and the means to rectify them.

Symptom	Check, Remedy
Cannot turn on the power.	• Check cable between transceiver unit and monitor unit. • Check ship's mains. • Have a suitably qualified technician check the fuse in the transceiver unit.
Bottom echo becomes irregular.	• Rough seas. Distance to the bottom changes due to rolling and pitching. • Long range selected. Transmission period is longer so ship's pitching and rolling are apt to affect detection of echo.
Weak echo	• Output power set to minimum. Set to maximum, on the COM1 menu. • Excessive TVG. Readjust TVG on the appropriate menu (HORZ, VERT, ES). Note that readjustment of TVG is necessary when gain is adjusted.
Somewhat strange color	• Brilliance setting too low. Increase brightness with BRILL key (supplied monitor) or brilliance control on commercial monitor.
Picture contains noise.	• Equipment not grounded properly. Check equipment ground. • Power cable is too close to the signal cable. Relocate power cable or signal cable. • Debris may be on sea surface. Reject unwanted noise with the interference rejector on the COM1 menu.
Picture does not change when tilt angle is changed. (Bottom is not displayed in vertical scan picture when bottom is flat.)	• Problem in tilt mechanism or control line. Contact a FURUNO agent or dealer for advice.

6.7   Error Messages

The table below shows the error messages which may appear on the display. All error messages are accompanied by an audio alarm, which you may silence with the **R/B** key.

Message	Meaning, Remedy
Hull Unit	
HULL UNIT POWER OFF (CHECK BREAKER AND FUSE.) PRESS R/B KEY TO SILENCE ALARM.	Hull unit is not powered. Silence the audio alarm with the **R/B** key, and then turn on the hull unit to erase the message and restore normal operation.
RAISE/LOWER FUNCTION HAS NOT BEEN COMPLETED. CHECK IF THE BREAKER AT THE HULL UNIT HAS BEEN ACTIVATED. MAXIMUM ALLOWABLE SPEED IS 15 KNOTS WHILE SOUNDOME IS BEING RETRACTED. PRESS R/B KEY TO SILENCE ALARM.	You attempted to raise or lower the transducer when the ship's speed is above 15 knots or the breaker on the hull unit tripped. Check the breaker and lower the ship's speed below 15 knots to execute function desired.
Frequency Code Error	
FREQUENCY CODE ERROR (CHECK TRANSCEIVER UNIT.) PRESS R/B KEY TO SILENCE ALARM.	CPU does not receive frequency flag from transducer. Silence the audio alarm with the **R/B** key, and then check the transceiver unit.
Train Error	
TRAIN NG	CPU does not receive heading signal. Check source of heading signal.
Excessive Speed	
SHIPS SPEED EXCEEDS 15 kt. (SLOW DOWN UNDER 15 kt WHEN MOVING TRANSDUCER.) PRESS R/B KEY TO SILENCE ALARM.	See page 5-13 for details.
TRANSDUCER REMAINS LOWERED. (REDUCE SHIP'S SPEED AND PRESS ↑ TO RETRACT IT.) PRESS R/B KEY TO SILENCE ALARM.	

6.8 Diagnostics

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU, and then press ► to choose SYS.
3. Press ▼ to choose GO TO SYS MENU.
4. Press ◄ to choose YES.
5. Choose TEST and press ► to start the test. The lamps above the XDR switches light alternately for one second while the test is being conducted. In a few moments the results of the test appear.

```
MAIN PROGRAM NO.   : 0650111-XX.XX
PANEL PROGRAM NO. : 0650112-XX.XX
ROM                : OK
RAM                : OK
VRAM               : OK
NMEA1              : *
NMEA2              : *
TX FREQUENCY       : 85/215 kHz†
ROLL          MS : 10     SC: - - -
PITCH         MS : 10     SC: - - -
              PULSES     NG
TRAIN          359        0
   TEST COUNT=  :  10
                                          REMOTE CONTROL
 PANEL
       0      0      0    0     0    0  0  0    0       0

    0                                   0     0    0       0
 0     0     0    0     0    0  0     0  0
                                       0  0  0
 0     0     0    0     0         0  EXIT     0
                       0   0   0    0     0   0
```

* Requires special test connector to test. Nothing displayed when plug is not connected.
† Or 60/153 kHz
XX.XX = Program Version No.

Test results

Interpreting the test results display

- The program numbers of the MAIN and PANEL programs appear at the top of the display.

- The ROM, RAM, VRAM, NMEA1, NMEA2 and PANEL CPU are checked for proper operation and the results displayed as OK or NG (No Good). For NG contact a FURUNO agent or dealer for advice. The NMEA1/NMEA2 test checks the NMEA (monitor unit) / NMEA (transceiver unit) ports.

- The TX FREQUENCY of the transducer is measured and displayed.

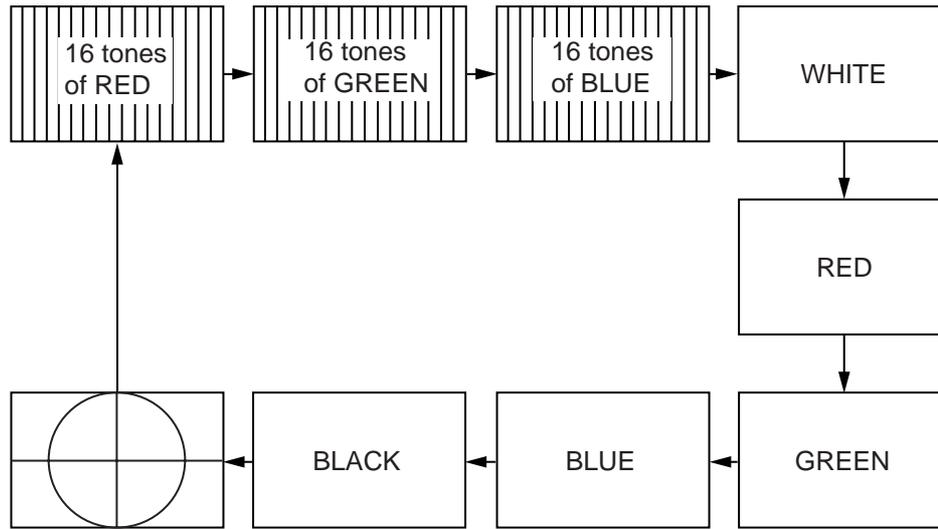- ROLL and PITCH values change with ship's pitching and rolling (range: -30° to +30°).

- TRAIN shows a figure between 355-359 if normal. NG appears in case of train error.

- TEST COUNT shows the number of times the test has been consecutively executed.

- At the bottom of the screen there are two major groups of zeroes (0), and they represent the keys and controls on the control panel and remote controller. Press a key and its on-screen location shows "1" while the key is pressed and "0" when it is released. Operate a control and its on-screen indication changes from 0-19. When the **BRILL** control is operated the panel dimmer increases or decreases with adjustment of the control.

To quit the test, press the **MENU** key three times.

6.9 Test Pattern

A test pattern can be displayed to check for proper display of colors.

1. Press the **MENU** key to open the menu.
2. Press ▲ to choose MENU, and then press ► to choose SYS.
3. Press ▼ to choose GO TO SYS MENU.
4. Press ◄ to choose YES.
5. Choose TEST PATTERN and press ► to display the test pattern. Press ► again to change the test pattern. The pattern changes in the sequence shown below with each press of ►.

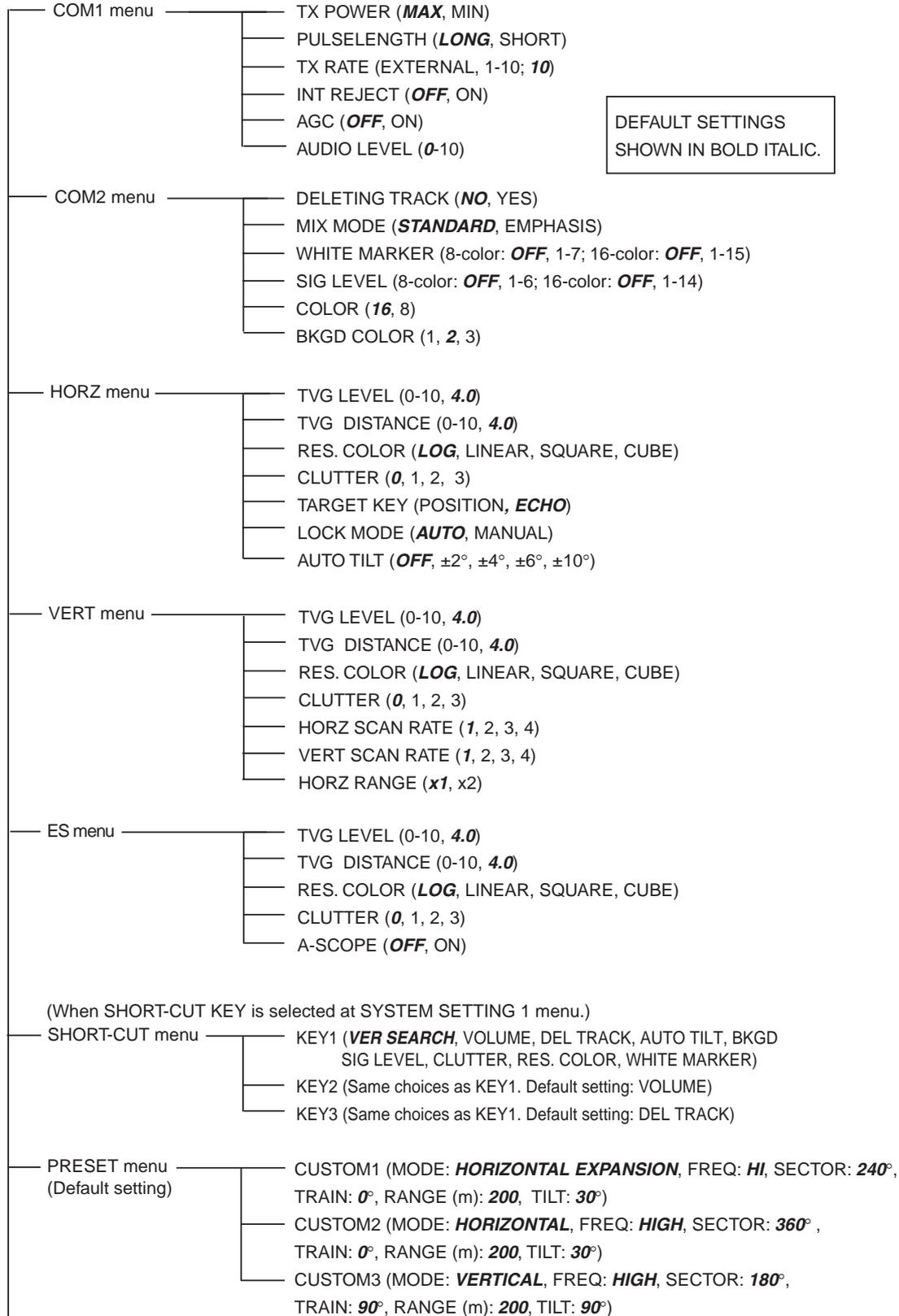*Test pattern*

To quit the test pattern, press the **MENU** key.

MENU TREE

[MENU] key

COM1 menu
- TX POWER (*MAX*, MIN)
- PULSELENGTH (*LONG*, SHORT)
- TX RATE (EXTERNAL, 1-10; *10*)
- INT REJECT (*OFF*, ON)
- AGC (*OFF*, ON)
- AUDIO LEVEL (*0*-10)

DEFAULT SETTINGS
SHOWN IN BOLD ITALIC.

COM2 menu
- DELETING TRACK (*NO*, YES)
- MIX MODE (*STANDARD*, EMPHASIS)
- WHITE MARKER (8-color: *OFF*, 1-7; 16-color: *OFF*, 1-15)
- SIG LEVEL (8-color: *OFF*, 1-6; 16-color: *OFF*, 1-14)
- COLOR (*16*, 8)
- BKGD COLOR (1, *2*, 3)

HORZ menu
- TVG LEVEL (0-10, *4.0*)
- TVG DISTANCE (0-10, *4.0*)
- RES. COLOR (*LOG*, LINEAR, SQUARE, CUBE)
- CLUTTER (*0*, 1, 2, 3)
- TARGET KEY (POSITION*, ECHO*)
- LOCK MODE (*AUTO*, MANUAL)
- AUTO TILT (*OFF*, ±2°, ±4°, ±6°, ±10°)

VERT menu
- TVG LEVEL (0-10, *4.0*)
- TVG DISTANCE (0-10, *4.0*)
- RES. COLOR (*LOG*, LINEAR, SQUARE, CUBE)
- CLUTTER (*0*, 1, 2, 3)
- HORZ SCAN RATE (*1*, 2, 3, 4)
- VERT SCAN RATE (*1*, 2, 3, 4)
- HORZ RANGE (*x1*, x2)

ES menu
- TVG LEVEL (0-10, *4.0*)
- TVG DISTANCE (0-10, *4.0*)
- RES. COLOR (*LOG*, LINEAR, SQUARE, CUBE)
- CLUTTER (*0*, 1, 2, 3)
- A-SCOPE (*OFF*, ON)

(When SHORT-CUT KEY is selected at SYSTEM SETTING 1 menu.)

SHORT-CUT menu
- KEY1 (*VER SEARCH*, VOLUME, DEL TRACK, AUTO TILT, BKGD SIG LEVEL, CLUTTER, RES. COLOR, WHITE MARKER)
- KEY2 (Same choices as KEY1. Default setting: VOLUME)
- KEY3 (Same choices as KEY1. Default setting: DEL TRACK)

PRESET menu
(Default setting)
- CUSTOM1 (MODE: *HORIZONTAL EXPANSION*, FREQ: *HI*, SECTOR: *240*°, TRAIN: *0*°, RANGE (m): *200*, TILT: *30*°)
- CUSTOM2 (MODE: *HORIZONTAL*, FREQ: *HIGH*, SECTOR: *360*° , TRAIN: *0*°, RANGE (m): *200*, TILT: *30*°)
- CUSTOM3 (MODE: *VERTICAL*, FREQ: *HIGH*, SECTOR: *180*°, TRAIN: *90*°, RANGE (m): *200*, TILT: *90*°)

MENU TREE

SYSTEM menu

— SYSTEM SETTING (See below.)

— RANGE-SONAR MODE (all default ranges)
  m: 20, 40, 60, 80, 100, 120, 160, 200, 250, 300, 400, 500, 600, 800, 1200
  ft: 50, 100, 200, 300, 400, 500, 600, 700, 800, 1000, 1200, 1500, 2000, 3000, 4000
  fa: 10, 20, 40, 60, 80, 100, 120, 140, 160, 200, 250, 300, 400, 500, 700
  P/B, Hiro: 10, 20, 40, 60, 80, 100, 120, 160, 200, 250, 300, 400, 500, 600, 800

— RANGE-VER MODE (all default ranges)
  m: 10, 20, 30, 40, 60, 80, 100, 120, 160, 200, 250, 300, 400, 500, 600
  ft: 30, 60, 90, 120, 150, 200, 250, 300, 400, 500, 600, 800, 1000, 1500, 2000
  fa, P/B, Hiro: 10, 20, 30, 40, 50, 60, 80, 100, 120, 140, 160, 200, 250, 300, 400

— RANGE-E/S MODE (all default ranges)
  m: 10, 20, 30, 40, 60, 80, 100, 120, 160, 200, 250, 300, 400, 500, 600
  ft: 30, 60, 90, 120, 150, 200, 250, 300, 400, 500, 600, 800, 1000, 1500, 2000
  fa, P/B, Hiro: 10, 20, 30, 40, 50, 60, 80, 100, 120, 140, 160, 200, 250, 300, 400

— RANGE-TRACK MODE (all default ranges)
  m: 500, 1000, 2000, 4000, 8000
  ft: 1000, 2000, 5000, 10,000, 20,000
  fa, P/B, Hiro: 200, 500, 1000, 2000, 4000

— COLOR PALETTE (Adjusts color of echoes, text and background.)

— LANGUAGE (JAPANESE, *ENGLISH*, FRANCAIS, ESPANOL, ITALIANO, PORTUGUES
  DANSK, NORSK, SVENSK, THAI)

— SYSTEM BACKUP (*NO*, YES)

— LOAD BACKUP DATA (*NO*, YES)

— HEADING OFFSET. DRAFT OFFSET (-180°, +180°, *0*; 0 - 60 (m), *0*)

— ADJ MOTION SENSOR (ROLL ANGLE: -10° - +10°, *0*; PITCH ANGLE: -10° - +10°, *0*)

— TX FREQ ADJUST
  ├ FREQ SHIFT(L) 60 kHz, 57-63; *60* or 85 kHz: 85-95; *85*
  └ FREQ SHIFT(H) 153 kHz: 147-163; *153* or 215 kHz: 205-225; *215*

— TEST (Checks equipment for proper operation.)

— TEST PATTERN (Displays series of test patterns.)

— DEMO MODE (*OFF*, ON)

— DEFAULT (*NO*, YES)

SYSTEM SETTING 1

— POSITION (*SHIP'S L/L*, SHIP'S LOP, CURSOR L/L)
— TRACK (OFF, *ON*)
— CURRENT DATA (*OFF*, FLOW FROM, FLOW TO)
— HEADING INDICATION (*TRUE*, AZ)
— NORTH MARK (*OFF*, ON)
— CSE DATA (*NAV*, GYRO)
— NAV BAUDRATE (*4800*, 9600, 19200, 38400 (bps))
— NAV DATA (*GPS*, LoranC, LoranA, DR, DECCA, OTHERS)
— TVG CORRECTION (*OFF*, 1/2, 1/1)
— UNIT (*m*, ft, fa, HIRO, P/B)
— TEMP (°*C,* °F)
— TARGET L/L (*OFF*, ON)
— CUSTOM KEY (*PRESET KEY*, SHORT-CUT KEY)
— ETA MARK (*OFF,* 10sec, 30sec, 1min, 3min, 6min)

SYSTEM SETTING 2

— GAIN SETTING PROTECT (OFF, *ON*)
— HORZ/HISTORY (OFF, *ON*)
— HORZ/VERT (OFF, *ON*)
— HORZ/VERT ZOOM (OFF, *ON*)
— HORZ/PLOTTER (OFF, *ON*)
— EMPHASIS MODE (OFF, *NORMAL*, RED)
— STABILIZER (OFF, *ON*)
— AUTO RETRACTION (*OFF*, 5-15kt(ON))
— SPEED ALARM/MESSAGE (OFF, *ON*)
— SWEEP INDICATOR (DOT, *LINE*)
— DEFAULT SETTING (*NO*, YES)

DUAL-FREQUENCY SEARCHLIGHT SONAR
CH-300

1. GENERAL

1.1 Display System   10.4-inch color TFT LCD (or external monitor)

1.2 Transmit Frequency   Dual frequency, 60/153 kHz or 85/215 kHz

1.3 Output Power   1.0 kW

1.4 Range (default setting)

Rng	Meter			Feet			Fathom			P/B			Hiro		
	Horz	Vert	ES	Horz	Vert	ES	Horz	Vert	ES	Horz	Vert	ES	Horz	Vert	ES
1	20	10	10	50	30	30	10	10	10	10	10	10	10	10	10
2	40	20	20	100	60	60	20	20	20	20	20	20	20	20	20
3	60	30	30	200	90	90	40	30	30	40	30	30	40	30	30
4	80	40	40	300	120	120	60	40	40	60	40	40	60	40	40
5	100	60	60	400	150	150	80	50	50	80	50	50	80	50	50
6	120	80	80	500	200	200	100	60	60	100	60	60	100	60	60
7	160	100	100	600	250	250	120	80	80	120	80	80	120	80	80
8	200	120	120	700	300	300	140	100	100	160	100	100	160	100	100
9	250	160	160	800	400	400	160	120	120	200	120	120	200	120	120
10	300	200	200	1000	500	500	200	140	140	250	140	140	250	140	140
11	400	250	250	1200	600	600	250	160	160	300	160	160	300	160	160
12	500	300	300	1500	800	800	300	200	200	400	200	200	400	200	200
13	600	400	400	2000	1000	1000	400	250	250	500	250	250	500	250	250
14	800	500	500	3000	1500	1500	500	300	300	600	300	300	600	300	300
15	1200	600	600	4000	2000	2000	700	400	400	800	400	400	800	400	400

1.5 Minimum and maximum ranges

Horizontal mode

	Meter	Feet	Fathom	P/B	Hiro
Min. range	10	30	5	5	5
Max. range	1600	5000	800	1000	1000

Vertical scan mode, echo sounder mode

	Meter	Feet	Fathom	P/B	Hiro
Min. range	10	30	5	5	5
Max. range	600	2000	400	400	400

2. MONITOR/CONTROL UNIT

2.1 Display   VGA (640x480)

2.2 Brilliance   350cd/m^2 TYP

2.3 Display Colors   16 or 8 colors, Background: 3 colors, selectable (user setting available)

2.4	Display Mode	Horizontal1, Horizontal expansion1, Vertical scan1, Echo sounder1, Horizontal2, Horizontal expansion2, Vertical scan2, Echo sounder2, Combination (vertical scan port/starboard, vertical scan upward/downward, Strata, History)
2.5	Alphanumerical Indication	Range, Tilt angle, Sensitivity, TVG, Interference rejection, Frequency (high, low), Transducer status, Tracking, Color
2.6	Data Indication	L/L (Own ship or cursor), Depth, Bearing, Speed, Water temperature, Tide, Ship's track, North mark, Tide vector, ETA marker (External IEC-61162 data required, not shown on some displays),
2.7	Other Markers	Offcenter, Signal level, White marker, Emphasis, Cursor, VRM, Event marker (5 pts.), Target lock, Clutter
2.8	Indication Unit	Meter, Feet, Fathom, P/B, Hiro
2.9	Audio Monitor	2 W output (4 ohms), Freq. 1.0 kHz (external speaker required)
2.10	Language	English and other languages

3. TRANSCEIVER UNIT

3.1	Transmission	Dual frequency Tx/Rx, single frequency
3.2	Pulse Length	0.24 ms to 20.0 ms, according to range (up to 10 ms for each frequency in dual-frequency transmission)
3.3	TVG	Level: 100 dB max. , Distance: 1000 m

4. HULL UNIT

4.1	Transducer Travel	400 mm or 250 mm
4.2	Raise/lower Time	30 s (400 mm travel)
4.3	Ship's Bow Adjustment	±180° offset on menu, set during installation
4.4	Horizontal Mode Control	

Scanning angle: 6° to 360°, 24° step
Scanning center: 6° steps, 360° setting available
Scanning step angle: Normal: 6°, High speed: 12°
Elevation angle: +5° to 90°, 1° step
Auto tilt setting: ±2° to ±10°

4.5   Time to Train Full Circle (* NS, Normal Speed, HS, High Speed)
Single frequency, horizontal mode

Range (m)		20	40	60	80	100	120	160	200	250	300	400	500	600	800	1200
Time (sec)	NS*	9	9	9	9	9	11	14	17	21	25	33	41	49	65	97
	HS*	9	9	9	9	9	11	12	14	16	18	22	26	30	38	54

Dual frequency, horizontal mode

Range (m)		20	40	60	80	100	120	160	200	250	300	400	500	600	800	1200
Time (sec)	NS*	11	11	11	11	11	12	15	18	22	26	34	42	50	66	98
	HS*	11	11	11	11	11	12	14	15	17	19	23	27	31	39	55

4.6 Vertical Scan Mode Control

Scanning angle: 6° to 180°, 12° step
Scanning center: 0° to 180°, 6° step
Scanning step angle: Normal: 3°, High speed: 6°
Time to train: 360°, 6° step

4.7 Transceiver Beam Width

Frequency	Horizontal	Vertical
60 kHz:	16°/22°	14°/20°
85 kHz:	11°/15°	10°/14°
153 kHz:	7°/9°	5°/8°
215 kHz:	5°/6°	4°/6°

4.8 Allowable Ship's Speed   20 knot or less (15 knot during raise/lower operation)

4.9 Stabilization   Within 30°, optional motion sensor required

5. I/O INTERFACE

5.1 Data Format   IEC61162-1 (NMEA0183 Ver 1.5/2.0)

5.2 Input   DBS, DBT, DPT, GGA, GLL, HDG, HDM, HDT, MDA, MTW, RMA, RMC, VDR, VHW, VTG, att (P sentence)

5.3 Output   SSTLL

6 POWER SUPPLY

6.1 MU-100C/Control Unit, Transceiver Unit

12-24 VDC: 7.0-3.5A

6.2 Control Unit, Transceiver Unit

12-24 VDC: 5.0-2.5A

6.3 Hull Unit   12/24 VDC: 4.7/2.3A (16.7/8.2-A, during raising and lowering)

7. ENVIRONMENTAL CONDITIONS

7.1 Ambient Temperature   -15°C to +55°C (Soundome: 0°C to +35°C)

7.2 Relative Humidity   Less than 95%

7.3 Waterproofing   Control unit: IPX5
Transceiver unit: IPX0
Hull unit: IPX2
MU-100C: IPX5

7.4 Vibration   2 Hz-5Hz to 13.2 Hz: Amplitude: ±1 mm ±10%
13.2 Hz to 100 Hz: Max. acceleration 7m/s^2, fixed

8. COATING COLOR

8.1 Control Unit   Panel: N3.0, Chassis: 2.5GY5/1.5

8.2 Transceiver Unit   2.5GY5/1.5

8.3 MU-100C   Panel: N3.0 Newtone No.5, Chassis: 2.5GY5/1.5

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